# HARDY-SOBOLEV INEQUALITY WITH SINGULARITY A CURVE 

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Abstract. We consider a bounded domain $\Omega$ of $\mathbb{R}^{N}, N \geq 3$, and $h$ a continuous function on $\Omega$. Let $\Gamma$ be a closed curve contained in $\Omega$. We study existence of positive solutions $u \in H_{0}^{1}(\Omega)$ to the equation

$$
-\Delta u+h u=\rho_{\Gamma}^{-\sigma} u^{2_{\sigma}^{*}-1} \quad \text { in } \Omega
$$

where $2_{\sigma}^{*}:=2(N-\sigma) /(N-2), \sigma \in(0,2)$, and $\rho_{\Gamma}$ is the distance function to $\Gamma$. For $N \geq 4$, we find a sufficient condition, given by the local geometry of the curve, for the existence of a ground-state solution. In the case $N=3$, we obtain existence of ground-state solution provided the trace of the regular part of the Green of $-\Delta+h$ is positive at a point of the curve.

## 1. Introduction

For $N \geq 3,0 \leq k \leq N-1$ and $\sigma \in[0,2)$, we consider the Hardy-Sobolev inequality

$$
\begin{equation*}
\int_{\mathbb{R}^{N}}|\nabla v|^{2} d x \geq C\left(\int_{\mathbb{R}^{N}}|z|^{-\sigma}|v|^{2_{\sigma}^{*}} d x\right)^{2 / 2_{\sigma}^{*}} \quad \text { for all } v \in \mathcal{D}^{1,2}\left(\mathbb{R}^{N}\right) \tag{1.1}
\end{equation*}
$$

where $x=(t, z) \in \mathbb{R}^{k} \times \mathbb{R}^{N-k}, C=C(N, \sigma, k)>0$ and $2_{\sigma}^{*}:=2(N-\sigma) /(N-2)$. Here the Sobolev space $\mathcal{D}^{1,2}\left(\mathbb{R}^{N}\right)$ is given by the completion of $C_{c}^{\infty}\left(\mathbb{R}^{N}\right)$ with respect to the norm $v \mapsto\left(\int_{\mathbb{R}^{N}}|\nabla v|^{2} d x\right)^{1 / 2}$. Inequality (1.1) interpolates between cylindrical Hardy inequality, which corresponds to the case $\sigma=2$ and $k \neq N-2$,

[^0]and the Sobolev inequality which is the case $\sigma=0$. Moreover it is invariant under scaling on $\mathbb{R}^{N}$ and by translations in the $t$-direction. It is well known that in the case of Hardy inequality, $\sigma=2$ and $k \neq N-2$, there is no positive constant $C$ and $v \in \mathcal{D}^{1,2}\left(\mathbb{R}^{N}\right)$ for which equality holds in (1.1). For $\sigma \in[0,2)$, the best positive constant $C$ in (1.1) is
\[

$$
\begin{equation*}
S_{N, \sigma}:=\inf \left\{\int_{\mathbb{R}^{N}}|\nabla v|^{2} d x, v \in \mathcal{D}^{1,2}\left(\mathbb{R}^{N}\right) \text { and } \int_{\mathbb{R}^{N}}|z|^{-\sigma}|v|^{2_{\sigma}^{*}} d x=1\right\} \tag{1.2}
\end{equation*}
$$

\]

In the case $\sigma=0, S_{N, 0}$ is achieved by the standard bubble $c_{N}\left(1+|x|^{2}\right)^{(2-N) / 2}$, which is unique up to scaling and translations, e.g. Aubin [1] and Talenti [23]. For $k=0,(1.1)$ is a particular case of the Caffarelli-Kohn-Nirenberg inequality, see [6]. In this case, Lieb showed in [20] that only functions of the form $c_{N, \sigma}(1+$ $\left.|x|^{2-\sigma}\right)^{(2-N) /(2-\sigma)}$ achieves $S_{N \sigma}$, up to a scaling. When $k=N-1$, Musina proved in [21] that the support of the minimizer is contained in a half-space. Therefore (1.1) becomes the Hardy-Sobolev inequality with singularity all the boundary of the halfspace.

For $1 \leq k \leq N-2$ and $\sigma \in(0,2)$, Badiale and Tarentello proved the existence of a minimizer $w$ for (1.2) in their paper [3], where they were motivated by questions from astrophysics. Moreover, Mancini, Fabbri and Sandeep showed decay and symmetry properties of $w$ in [10]. In particular, they prove that $w(t, z)=\theta(|t|,|z|)$, for some positive function $\theta$. An interesting classification result was also derived in [10] when $\sigma=1$, that every minimizer is of the form $c_{N, k}\left((1+|z|)^{2}+|t|^{2}\right)^{(2-N) / 2}$, up to scaling in $\mathbb{R}^{N}$ and translations in the $t$ direction.

Since in this paper we are interested with Hardy-Sobolev inequality with weight singular at a given curve, our asymptotic energy level is given by $S_{N, \sigma}$ with $k=1$ and $\sigma \in(0,2)$.

Let $\Omega$ be a bounded domain in $\mathbb{R}^{N}, N \geq 3$, and $h$ a continuous function on $\Omega$. Let $\Gamma \subset \Omega$ be a smooth closed curve. In this paper, we are concerned with the existence of minimizers for the infinimum

$$
\begin{equation*}
\mu_{h}(\Omega, \Gamma):=\inf _{u \in H_{0}^{1}(\Omega) \backslash\{0\}} \frac{\int_{\Omega}|\nabla u|^{2} d x+\int_{\Omega} h u^{2} d x}{\left(\int_{\Omega} \rho_{\Gamma}^{-\sigma}|u|^{2_{\sigma}^{*}} d x\right)^{2 / 2_{\sigma}^{*}}}, \tag{1.3}
\end{equation*}
$$

where $\sigma \in[0,2], 2_{\sigma}^{*}:=2(N-\sigma) /(N-2)$ and $\rho_{\Gamma}(x):=\operatorname{dist}(x, \Gamma)$. Here and in the following, we assume that $-\Delta+h$ defines a coercive bilinear form on $H_{0}^{1}(\Omega)$. We are interested with the effect of the geometry and/or the location of the curve $\Gamma$ on the existence of minimmizer for $\mu_{h}(\Omega, \Gamma)$.

We not that for $\sigma=0$, (1.3) reduces to the famous Brezis-Nirenberg problem [5]. In this case, for $N \geq 4$ it is enough that $h\left(y_{0}\right)<0$ to get a minimizer, whereas for $N=3$, the problem is no more local and existence of minimizers
is guaranteed by the positiveness of a certain mass - the trace of the regular part of the Green function of the operator $-\Delta+h$ with zero Dirichlet data, see Druet [9]. For $\sigma=2$, the problem reduces to a linear eigenvalue problem with Hardy potential, existence and nonexistence results were obtained by the second author in [25].

Here, we deal with the case $\sigma \in(0,2)$. Our results exhibit similar local/global phenomenon as in [5] and [9], with the additional property that for $N \geq 4$, the curvature of the curve at a point $y_{0}$ tells how much $h\left(y_{0}\right)$ should be negative, while positive mass at a point $y_{0} \in \Gamma$ is enough in dimension $N=3$.

Our first main result is the following
Theorem 1.1. Let $N \geq 4, \sigma \in(0,2)$ and $\Omega$ be a bounded domain of $\mathbb{R}^{N}$. Consider $\Gamma$ a smooth closed curve contained in $\Omega$. Let $h$ be a continuous function such that the linear operator $-\Delta+h$ is coercive. Then there exists a positive constant $C_{N, \sigma}$, only depending on $N$ and $\sigma$ with the property that if there exists $y_{0} \in \Gamma$ such that

$$
\begin{equation*}
h\left(y_{0}\right)<-C_{N, \sigma}\left|\kappa\left(y_{0}\right)\right|^{2} \tag{1.4}
\end{equation*}
$$

then $\mu_{h}(\Omega, \Gamma)<S_{N, \sigma}$, and $\mu_{h}(\Omega, \Gamma)$ is achieved by a positive function. Here $\kappa: \Gamma \rightarrow \mathbb{R}^{N}$ is the curvature vector of $\Gamma$.

Inequality (1.4) in Theorem 1.1 shows that the sign of the directional curvatures of $\Gamma$ is not important but the size of the curvature $\kappa$ at a point is.

For the explicit value of $C_{N, \sigma}$ appearing in (1.4), we refer the reader to Proposition 4.2 below. It is given by weighted integrals involving partial derivatives of $w$, a minimizer for $S_{N, \sigma}$. In the case $N=4$, we have $C_{4, \sigma}=3 / 2$.

We now give a consequence of Theorem 1.1 in the case where $h \equiv \lambda$ a constant function. We denote by $\lambda_{1}(\Omega)>0$ the first Dirichlet eigenvalue of $-\Delta$ in $\Omega$. It is easy to see that $-\Delta+\lambda$ is coercive for every $\lambda>-\lambda_{1}(\Omega)$. In our next result, we will consider a curve $\Gamma$ with curvature vanishing at a point. This is (trivially) the case when $\Gamma$ contains a segment.

Corollary 1.2. Let $N \geq 4, \sigma \in(0,2)$ and $\Omega$ be a bounded domain of $\mathbb{R}^{N}$. Consider $\Gamma$ a smooth closed curve contained in $\Omega$. Suppose that the curvature $\kappa$ of $\Gamma$ vanishes at a point. Then for every $\lambda \in\left(-\lambda_{1}(\Omega), 0\right)$, we have $\mu_{\lambda}(\Omega, \Gamma)<S_{N, \sigma}$, and $\mu_{\lambda}(\Omega, \Gamma)$ is achieved by a positive function.

We observe that if $\Gamma=S_{R}^{1}$ a circle of radius $R>0$ and $h \equiv \lambda \in \mathbb{R}$ then condition (1.4) translates into

$$
\lambda<-\frac{C_{N, \sigma}}{R^{2}}
$$

Therefore, provided $-\lambda_{1}(\Omega)<-C_{N, \sigma} / R^{2}$, we have that $\mu_{\lambda}\left(\Omega, S_{R}^{1}\right)$ is achieved for every $\lambda \in\left(-\lambda_{1}(\Omega),-C_{N, \sigma} / R^{2}\right)$. One is thus led to find domains for which
$-\lambda_{1}(\Omega)<-C_{N, \sigma} / R^{2}$. A particular example is given by the annulus $\Omega_{\varepsilon}=$ $B_{R+\varepsilon} \backslash B_{R-\varepsilon}$, which contains $S_{R}^{1}$ for $\varepsilon>0$. It is well known from, e.g., the Faber-Krahn inequality that $\lambda_{1}\left(\Omega_{\varepsilon}\right) \geq c(N) / \varepsilon^{2}$, so that for sufficiently small $\varepsilon$, one always has $-\lambda_{1}\left(\Omega_{\varepsilon}\right)<-C_{N, \sigma} / R^{2}$.

We now turn to the 3-dimensional case. We let $G(x, y)$ be the Dirichlet Green function of the operator $-\Delta+h$, with zero Dirichlet data. It satisfies

$$
\begin{cases}-\Delta_{x} G(x, y)+h(x) G(x, y)=0 & \text { for every } x \in \Omega \backslash\{y\}  \tag{1.5}\\ G(x, y)=0 & \text { for every } x \in \partial \Omega\end{cases}
$$

In addition, for $N=3$, there exists a continuous function $\mathbf{m}: \Omega \rightarrow \mathbb{R}$ and a positive constant $c>0$ such that

$$
\begin{equation*}
G(x, y)=\frac{c}{|x-y|}+c \mathbf{m}(y)+o(1) \quad \text { as } x \rightarrow y \tag{1.6}
\end{equation*}
$$

We call the function $\mathbf{m}: \Omega \rightarrow \mathbb{R}$ the mass of $-\Delta+h$ in $\Omega$. We note that $-\mathbf{m}$ is occasionally called the Robin function of $-\Delta+h$ in the literature. We now state our second main result.

Theorem 1.3. Let $\sigma \in(0,2)$ and $\Omega$ be a bounded domain of $\mathbb{R}^{3}$. Consider $\Gamma$ a smooth closed curve contained in $\Omega$. Let $h$ be a continuous function such that the linear operator $-\Delta+h$ is coercive. If $\mathbf{m}\left(y_{0}\right)>0$, for some $y_{0} \in \Gamma$, then $\mu_{h}(\Omega, \Gamma)<S_{3, \sigma}$, and $\mu_{h}(\Omega, \Gamma)$ is achieved by a positive function.

Since the mass $\mathbf{m}$ is independent on the curve, Theorem 1.3 shows that the location of the curve in the domain $\Omega$ - so that to intersect the positive part of $\mathbf{m}$ - matters for the existence of solution in general. We note that there are situations in which the mass is everywhere positive. This is the case of the operator $-\Delta+\lambda$, provided $\lambda \in\left(-\lambda_{1}\left(B_{1}\right),-\lambda_{1}\left(B_{1}\right) / 4\right)$, as observed in BrezisNirenberg [5]. We therefore have

Corollary 1.4. Let $B_{1}$ the unit ball of $\mathbb{R}^{3}$ and let $\Gamma$ be any smooth closed curve contained in $B_{1}$. If $\lambda \in\left(-\lambda_{1}\left(B_{1}\right),-\lambda_{1}\left(B_{1}\right) / 4\right)$ then $\mu_{\lambda}(\Omega, \Gamma)<S_{3, \sigma}$ and $\mu_{\lambda}(\Omega, \Gamma)$ is achieved by a positive function.

The effect of curvatures in the study of Hardy-Sobolev inequalities has been intensively studied in the recent years. In each approach, the sign of the curvatures at the point of singularity plays important roles for the existence a solution. The first paper in this direction, to our knowledge, is the one by Ghoussoub and Kang [12] who considered the Hardy-Sobolev inequality with singularity at the boundary. For more results, see Ghoussoub and Robert [16], [17], [15], [14], Demyanov and Nazarov [8], Chern and Lin [7], Lin and Li [19], the authors and Minlend [11] and the references there in. We point out that in the pure HardySobolev case, $\sigma \in(0,2)$, with singularity at the boundary, one has existence of
minimizers for every dimension $N \geq 3$ as long as the mean curvature of the boundary is negative at the point singularity, see [13].

The Hardy-Sobolev inequality with interior singularity on Riemannian manifolds has been studied by Jaber [18] and Thiam [25]. Here also the impact of the scalar curvature at the point singularity plays an important role for the existence of minimizers in higher dimensions $N \geq 4$. The paper [18] contains also existence result under positive mass condition for $N=3$.

We expect that the arguments in this paper can be generalized to the case $\Gamma \subset \Omega$, a $k$-dimensional closed submanifold, with $2 \leq k \leq N-2$. Here we believe that the norm of the second fundamental from of $\Gamma$ will play a crucial role for the existence of minimizers. Another problem of interest would be the case $\Gamma \subset \partial \Omega$, a $k$-dimensional submanifold of $\partial \Omega$ with, $1 \leq k \leq N-1$. In this situation, we suspect that the sign of the mean curvature of $\partial \Omega$ at a point might influence on the existence of minimizers. Finally we note that Ghoussoub and Robert in [15] obtained several results for the case $\Gamma$ a subspace of dimension $k \geq 2$, and among other results, if $\Gamma$ intersects $\partial \Omega$ transversely, they obtained existence results under certain negativity assumptions on the mean curvature.

The proofs of Theorems 1.1 and 1.3 rely on test function methods. Namely on constructing appropriate test functions allowing to compare $\mu_{h}(\Omega, \Gamma)$ and $S_{N, \sigma}$. While it always holds that $\mu_{h}(\Omega, \Gamma) \leq S_{N, \sigma}$, our main task is to find a function for which $\mu_{h}(\Omega, \Gamma)<S_{N, \sigma}$. This then allows to recover compactness and thus every minimizing sequence for $\mu_{h}(\Omega, \Gamma)$ converges to a minimizer, up to a subsequence. Building these approximating solutions requires to have sharp decay estimates of a minimizer $w$ for $S_{N, \sigma}$, see Section 3. In Section 4, we treat the case $N=4$ in the spirit of Aubin [1]. Here we find a continuous family of test functions $\left(u_{\varepsilon}\right)_{\varepsilon>0}$ concentrating at a point $y_{0} \in \Gamma$ which yields $\mu_{h}(\Omega, \Gamma)<S_{N, \sigma}$, as $\varepsilon \rightarrow 0$, provided (1.4) holds. In Section 5 , we consider the case $N=3$, which is more difficult. Here we use the argument of Schoen [22] to build our test function. However we cannot adopt the method of [22] straightforwardly. In fact, in contrast to the case $N \geq 4$, we could only find a discrete family of test functions $\left(\Psi_{\varepsilon_{n}}\right)_{n \in \mathbb{N}}$ that leads to the inequality $\mu_{h}(\Omega, \Gamma)<S_{3, \sigma}$. This is due to the fact that the (flat) ground-state $w$ for $S_{3, \sigma}, \sigma \in(0,2)$, is not known explicitly, it is not radially symmetric, it is not smooth, and $S_{3, \sigma}$ is only invariant under translations in the $t$-direction. As in [22], we use some global test functions. These are similar to the test functions $\left(u_{\varepsilon_{n}}\right)_{n \in \mathbb{N}}$ in dimension $N \geq 4$ near the concentration point $y_{0}$, but away from it they are substituted with the regular part of the Green function $G\left(x, y_{0}\right)$, which leads to appearing of the mass $\mathbf{m}\left(y_{0}\right)$ in its first order Taylor expansion, see (1.6).

## 2. Geometric preliminaries

Let $\Gamma \subset \mathbb{R}^{N}$ be a smooth closed curve. Let $\left(E_{1} ; \ldots ; E_{N}\right)$ be an orthonormal basis of $\mathbb{R}^{N}$. For $y_{0} \in \Gamma$ and $r>0$ small, we consider the curve $\gamma:(-r, r) \rightarrow \Gamma$, parameterized by an arclength so that $\gamma(0)=y_{0}$. Up to a translation and a rotation, we may assume that $\gamma^{\prime}(0)=E_{1}$. We choose a smooth orthonormal frame field $\left(E_{2}(t) ; \ldots ; E_{N}(t)\right)$ on the normal bundle of $\Gamma$ such that $\left(\gamma^{\prime}(t) ; E_{2}(t) ; \ldots\right.$; $\left.E_{N}(t)\right)$ is an oriented basis of $\mathbb{R}^{N}$ for every $t \in(-r, r)$, with $E_{i}(0)=E_{i}$.

We fix the following notation, that will be used throughout the paper,

$$
Q_{r}:=(-r, r) \times B_{\mathbb{R}^{N-1}}(0, r),
$$

where $B_{\mathbb{R}^{k}}(0, r)$ denotes the ball in $\mathbb{R}^{k}$ with radius $r$ centered at the origin. Provided $r>0$ is small, the map $F_{y_{0}}: Q_{r} \rightarrow \Omega$, given by

$$
(t, z) \mapsto F_{y_{0}}(t, z):=\gamma(t)+\sum_{i=2}^{N} z_{i} E_{i}(t),
$$

is smooth and parameterizes a neighbourhood of $y_{0}=F_{y_{0}}(0,0)$. We consider $\rho_{\Gamma}: \Gamma \rightarrow \mathbb{R}$, the distance function to the curve, given by

$$
\rho_{\Gamma}(y)=\min _{\bar{y} \in \mathbb{R}^{N}}|y-\bar{y}| .
$$

In the above coordinates, we have

$$
\begin{equation*}
\rho_{\Gamma}\left(F_{y_{0}}(x)\right)=|z| \quad \text { for every } x=(t, z) \in Q_{r} . \tag{2.1}
\end{equation*}
$$

Clearly, for every $t \in(-r, r)$ and $i=2, \ldots N$, there are real numbers $\kappa_{i}(t)$ and $\tau_{i}^{j}(t)$ such that

$$
\begin{equation*}
E_{i}^{\prime}(t)=\kappa_{i}(t) \gamma^{\prime}(t)+\sum_{j=2}^{N} \tau_{i}^{j}(t) E_{j}(t) \tag{2.2}
\end{equation*}
$$

The quantity $\kappa_{i}(t)$ is the curvature in the $E_{i}(t)$-direction while $\tau_{i}^{j}(t)$ is the torsion from the osculating plane spanned by $\left\{\gamma^{\prime}(t) ; E_{j}(t)\right\}$ in the direction $E_{i}$. We note that provided $r>0$ is small, $\kappa_{i}$ and $\tau_{i}^{j}$ are smooth functions on $(-r, r)$. Moreover, it is easy to see that

$$
\begin{equation*}
\tau_{i}^{j}(t)=-\tau_{j}^{i}(t) \quad \text { for } i, j=2, \ldots, N \tag{2.3}
\end{equation*}
$$

The curvature vector $\kappa: \Gamma \rightarrow \mathbb{R}^{N}$ is defined as $\kappa(\gamma(t)):=\sum_{i=2}^{N} \kappa_{i}(t) E_{i}(t)$ and its norm is given by

$$
|\kappa(\gamma(t))|:=\sqrt{\sum_{i=2}^{N} \kappa_{i}^{2}(t)} .
$$

Next, we derive the expansion of the metric induced by the parameterization $F_{y_{0}}$ defined above. For $x=(t, z) \in Q_{r}$, we define

$$
\begin{aligned}
g_{11}(x) & =\partial_{t} F_{y_{0}}(x) \cdot \partial_{t} F_{y_{0}}(x), \\
g_{1 i}(x) & =\partial_{t} F_{y_{0}}(x) \cdot \partial_{z_{i}} F_{y_{0}}(x), \\
g_{i j}(x) & =\partial_{z_{j}} F_{y_{0}}(x) \cdot \partial_{z_{i}} F_{y_{0}}(x) .
\end{aligned}
$$

We have the following result.
Lemma 2.1. There exists $r>0$, depending only on $\Gamma$ and $N$, such that for every $x=(t, z) \in Q_{r}$,

$$
\left\{\begin{align*}
g_{11}(x)= & 1+2 \sum_{i=2}^{N} z_{i} \kappa_{i}(0)+2 t \sum_{i=2}^{N} z_{i} \kappa_{i}^{\prime}(0)  \tag{2.4}\\
& +\sum_{i j=2}^{N} z_{i} z_{j} \kappa_{i}(0) \kappa_{j}(0)+\sum_{i j=2}^{N} z_{i} z_{j} \beta_{i j}(0)+O\left(|x|^{3}\right) \\
g_{1 i}(x)= & \sum_{j=2}^{N} z_{j} \tau_{j}^{i}(0)+t \sum_{j=2}^{N} z_{j}\left(\tau_{j}^{i}\right)^{\prime}(0)+O\left(|x|^{3}\right) \\
g_{i j}(x)= & \delta_{i j}
\end{align*}\right.
$$

where $\beta_{i j}(t):=\sum_{l=2}^{N} \tau_{i}^{l}(t) \tau_{j}^{l}(t)$.
Proof. To alleviate the notations, we will write $F=F_{y_{0}}$. We have

$$
\begin{equation*}
\partial_{t} F(x)=\gamma^{\prime}(t)+\sum_{j=2}^{N} z_{j} E_{j}^{\prime}(t) \quad \text { and } \quad \partial_{z_{i}} F(x)=E_{i}(t) . \tag{2.5}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
g_{i j}(x)=E_{i}(t) \cdot E_{j}(t)=\delta_{i j} . \tag{2.6}
\end{equation*}
$$

By (2.2) and (2.5), we have

$$
\begin{equation*}
g_{1 i}(x)=\sum_{l=2}^{N} z_{l} E_{l}^{\prime}(t) \cdot E_{i}(t)=\sum_{j=2}^{N} z_{j} \tau_{j}^{i}(t) \tag{2.7}
\end{equation*}
$$

and

$$
\begin{align*}
g_{11}(x)= & \partial_{t} F(x) \cdot \partial_{t} F(x)=1+2 \sum_{i=2}^{N} z_{i} \kappa_{i}(t)  \tag{2.8}\\
& +\sum_{i j=2}^{N} z_{i} z_{j} \kappa_{i}(t) \kappa_{j}(t)+\sum_{i j=2}^{N} z_{i} z_{j}\left(\sum_{l=2}^{N} \tau_{i}^{l}(t) \tau_{j}^{l}(t)\right) .
\end{align*}
$$

By Taylor expansions, we get

$$
\kappa_{i}(t)=\kappa_{i}(0)+t \kappa_{i}^{\prime}(0)+O\left(t^{2}\right) \quad \text { and } \quad \tau_{i}^{k}(t)=\tau_{i}^{k}(0)+t\left(\tau_{i}^{k}\right)^{\prime}(0)+O\left(t^{2}\right)
$$

Using these identities in (2.8) and (2.7), we get (2.4), thanks to (2.6).

As a consequence we have the following result.

Lemma 2.2. There exists $r>0$, depending only on $\Gamma$ and $N$, such that for every $x \in Q_{r}$, we have
(2.9) $\sqrt{|g|}(x)=1+\sum_{i=2}^{N} z_{i} \kappa_{i}(0)+t \sum_{i=2}^{N} z_{i} \kappa_{i}^{\prime}(0)+\frac{1}{2} \sum_{i j=2}^{N} z_{i} z_{j} \kappa_{i}(0) \kappa_{j}(0)+O\left(|x|^{3}\right)$,
where $|g|$ stands for the determinant of $g$. Moreover, $g^{-1}(x)$, the matrix inverse of $g(x)$, has components given by

$$
\left\{\begin{align*}
g^{11}(x)= & 1-2 \sum_{i=2}^{N} z_{i} \kappa_{i}(0)-2 t \sum_{i=2}^{N} z_{i} \kappa_{i}^{\prime}(0) \\
& +3 \sum_{i j=2}^{N} z_{i} z_{j} \kappa_{i}(0) \kappa_{j}(0)+O\left(|x|^{3}\right), \\
g^{i 1}(x)= & -\sum_{j=2}^{N} z_{j} \tau_{j}^{i}(0)-t \sum_{j=2}^{N} z_{j}\left(\tau_{j}^{i}\right)^{\prime}(0)  \tag{2.10}\\
& +2 \sum_{j=2}^{N} z_{l} z_{j} \kappa_{l}(0) \tau_{j}^{i}(0)+O\left(|x|^{3}\right), \\
g^{i j}(x)= & \delta_{i j}+\sum_{l m=2}^{N} z_{l} z_{m} \tau_{l}^{j}(0) \tau_{m}^{i}(0)+O\left(|x|^{3}\right) .
\end{align*}\right.
$$

Proof. We write $g(x)=\mathrm{id}+H(x)$, where id denotes the identity matrix on $\mathbb{R}^{N}$ and $H$ is a symmetric matrix with components for $\alpha, \beta=1, \ldots, N$, given by

$$
\left\{\begin{align*}
H_{11}(x)= & 2 \sum_{i=2}^{N} z_{i} \kappa_{i}(0)+2 t \sum_{i=2}^{N} z_{i} \kappa_{i}^{\prime}(0)  \tag{2.11}\\
& +\sum_{i j=2}^{N} z_{i} z_{j} \kappa_{i}(0) \kappa_{j}(0)+\sum_{i j=2}^{N} z_{i} z_{j} \beta_{i j}(0)+O\left(|x|^{3}\right), \\
H_{1 i}(x)= & \sum_{j=2}^{N} z_{i} \tau_{j}^{i}(0)+O\left(|x|^{2}\right), \\
H_{i j}(x)= & 0
\end{align*}\right.
$$

We recall that, as $|H| \rightarrow 0$,

$$
\begin{equation*}
\sqrt{|g|}=\sqrt{\operatorname{det}(I+H)}=1+\frac{\operatorname{tr} H}{2}+\frac{(\operatorname{tr} H)^{2}}{4}-\frac{\operatorname{tr}\left(H^{2}\right)}{4}+O\left(|H|^{3}\right) \tag{2.12}
\end{equation*}
$$

Now, by (2.11), as $|x| \rightarrow 0$, we have

$$
\begin{align*}
\frac{\operatorname{tr} H}{2}=\sum_{i=2}^{N} z_{i} \kappa_{i}(0) & +t \sum_{i=2}^{N} z_{i} \kappa_{i}^{\prime}(0)  \tag{2.13}\\
& +\frac{1}{2} \sum_{i j=2}^{N} z_{i} z_{j} \kappa_{i}(0) \kappa_{j}(0)+\frac{1}{2} \sum_{i j=2}^{N} z_{i} z_{j} \beta_{i j}(0)+O\left(|x|^{3}\right)
\end{align*}
$$

so that

$$
\begin{equation*}
\frac{(\operatorname{tr} H)^{2}}{4}=\sum_{i j=2}^{N} z_{i} z_{j} \kappa_{i}(0) \kappa_{j}(0)+O\left(|x|^{3}\right) \tag{2.14}
\end{equation*}
$$

Moreover, from (2.11), we deduce that

$$
\begin{aligned}
\operatorname{tr}\left(H^{2}\right)(x) & =\sum_{\alpha=1}^{N}\left(H^{2}(x)\right)_{\alpha \alpha}=\sum_{\alpha \beta=1}^{N} H_{\alpha \beta}(x) H_{\beta \alpha}(x) \\
& =\sum_{\alpha \beta=1}^{N} H_{\alpha \beta}^{2}(x)=H_{11}^{2}(x)+2 \sum_{i=2}^{N} H_{i 1}^{2}(x),
\end{aligned}
$$

so that

$$
\begin{equation*}
-\frac{\operatorname{tr}\left(H^{2}\right)}{4}=-\sum_{i j=2}^{N} z_{i} z_{j} \kappa_{i}(0) \kappa_{j}(0)-\frac{1}{2} \sum_{i j l=2}^{N} z_{i} z_{j} \tau_{i}^{l}(0) \tau_{j}^{l}(0)+O\left(|x|^{3}\right) \tag{2.15}
\end{equation*}
$$

Therefore plugging the expression from (2.13)-(2.15) in (2.12), we get

$$
\sqrt{|g|}(x)=1+\sum_{i=2}^{N} z_{i} \kappa_{i}(0)+t \sum_{i=2}^{N} z_{i} \kappa_{i}^{\prime}(0)+\frac{1}{2} \sum_{i j=2}^{N} z_{i} z_{j} \kappa_{i}(0) \kappa_{j}(0)+O\left(|x|^{3}\right)
$$

The proof of (2.9) is thus finished.
By Lemma 2.1 we can write $g(x)=\mathrm{id}+A(x)+B(x)+O\left(|x|^{3}\right)$, where $A$ and $B$ are symmetric matrices with components $\left(A_{\alpha \beta}\right)$ and $\left(B_{\alpha \beta}\right), \alpha, \beta=1, \ldots, N$, given respectively by

$$
\begin{equation*}
A_{11}(x)=2 \sum_{i=2}^{N} z_{i} \kappa_{i}(0), \quad A_{i 1}(x)=\sum_{j=2}^{N} z_{j} \tau_{j}^{i}(0) \quad \text { and } \quad A_{i j}(x)=0 \tag{2.16}
\end{equation*}
$$

and

$$
\left\{\begin{array}{l}
B_{11}(x)=2 t \sum_{i=2}^{N} z_{i} \kappa^{\prime}(0)+\sum_{i=2}^{N} z_{i} z_{j} \kappa_{i}(0) \kappa_{j}(0)+\sum_{i j=2}^{N} z_{i} z_{j} \beta_{i j}(0)  \tag{2.17}\\
B_{i 1}(x)=t \sum_{j=2} z_{j}\left(\tau_{j}^{i}\right)^{\prime}(0) \quad \text { and } \quad B_{i j}(x)=0
\end{array}\right.
$$

We observe that, as $|x| \rightarrow 0$, we have

$$
g^{-1}(x)=\operatorname{id}-A(x)-B(x)+A^{2}(x)+O\left(|x|^{3}\right)
$$

We then deduce from (2.16) and (2.17) that

$$
\begin{aligned}
g^{11}(x)= & 1-A_{11}(x)-B_{11}(x)+\sum_{\alpha=1}^{N} A_{1 \alpha}^{2}(x)+O\left(|x|^{3}\right) \\
= & 1-A_{11}(x)-B_{11}(x)+A_{11}^{2}(x)+\sum_{i=1}^{N} A_{1 i}^{2}(x)+O\left(|x|^{3}\right) \\
= & 1-2 \sum_{i=2}^{N} z_{i} \kappa_{i}(0)-2 t \sum_{i=2}^{N} z_{i} \kappa^{\prime}(0) \\
& +3 \sum_{i=2}^{N} z_{i} z_{j} \kappa_{i}(0) \kappa_{j}(0)+3 \sum_{i j=2}^{N} z_{i} z_{j} \beta_{i j}(0)+O\left(|x|^{3}\right), \\
g^{i 1}(x)= & -A_{1 i}(x)-B_{1 i}(x)+\sum_{\alpha=1}^{N} A_{i \alpha} A_{1 \alpha}+O\left(|x|^{3}\right) \\
= & -A_{1 i}(x)-B_{1 i}(x)+A_{i 1}(x) A_{11}(x)+\sum_{j=2}^{N} A_{i j}(x) A_{1 j}(x)+O\left(|x|^{3}\right) \\
= & -\sum_{j=2}^{N} z_{j} \tau_{j}^{i}(0)-t \sum_{j=2} z_{j}\left(\tau_{j}^{i}\right)^{\prime}(0)+2 \sum_{j l=2}^{N} z_{l} z_{j} \kappa_{l}(0) \tau_{j}^{i}(0)
\end{aligned}
$$

and

$$
\begin{aligned}
g^{i j}(x) & =\delta_{i j}-A_{i j}(x)-B_{i j}(x)+\left(A^{2}\right)_{i j}(x)+O\left(|x|^{3}\right) \\
& =\delta_{i j}-A_{i j}(x)-B_{i j}(x)+A_{1 i} A_{1 j}+\sum_{l=2}^{N} A_{i l}(x) A_{j l}(x)+O\left(|x|^{3}\right) \\
& =\delta_{i j}+\sum_{l m=2}^{N} z_{l} z_{m} \tau_{m}^{i}(0) \tau_{l}^{j}(0)+O\left(|x|^{3}\right) .
\end{aligned}
$$

This ends the proof.

## 3. Some preliminary results

We consider the best constant for the cylindrical Hardy-Sobolev inequality

$$
S_{N, \sigma}=\min \left\{\int_{\mathbb{R}^{N}}|\nabla w|^{2} d x: w \in \mathcal{D}^{1,2}\left(\mathbb{R}^{N}\right), \int_{\mathbb{R}^{N}}|z|^{-\sigma}|w|^{2_{\sigma}^{*}} d x=1\right\}
$$

As mentioned in the first section, it is attained by a positive function $w \in$ $\mathcal{D}^{1,2}\left(\mathbb{R}^{N}\right)$, satisfying

$$
\begin{equation*}
-\Delta w=S_{N, \sigma}|z|^{-\sigma} w^{2_{\sigma}^{*}-1} \quad \text { in } \mathbb{R}^{N}, \tag{3.1}
\end{equation*}
$$

see, e.g., [3]. Moreover, from [10], we have

$$
\begin{equation*}
w(x)=w(t, z)=\theta(|t|,|z|) \quad \text { for a function } \theta: \mathbb{R}_{+} \times \mathbb{R}_{+} \rightarrow \mathbb{R}_{+} \tag{3.2}
\end{equation*}
$$

Next we prove further decay properties of $w$ involving its higher derivatives.
Lemma 3.1. Let $\theta$ be given by (3.2). Then we have the following properties.
(a) The function $t \mapsto \theta(t, \rho)$ is of class $C^{\infty}$ with all its derivatives uniformly bounded with respect to $\rho$.
(b) There exists a constant $C>0$ such that for $|(t, \rho)| \leq 1$, we have

$$
\theta_{\rho}(t, \rho)+\theta_{t \rho}(t, \rho)+\rho \theta_{\rho \rho}(t, \rho) \leq C \rho^{1-\sigma} .
$$

Proof. For the proof of (a), see [10]. To prove (b), we first use polar coordinates to deduce that

$$
\begin{equation*}
\rho^{2-N}\left(\rho^{N-2} \theta_{\rho}\right)_{\rho}+\theta_{t t}=S_{N, \sigma} \rho^{-\sigma} \theta^{2_{\sigma}^{*}-1} \quad \text { for } t, \rho \in \mathbb{R}_{+} . \tag{3.3}
\end{equation*}
$$

Integrating this identity in the $\rho$ variable, we therefore get, for every $\rho>0$,

$$
\theta_{\rho}(t, \rho)=\frac{-1}{\rho^{N-2}} \int_{0}^{\rho} r^{N-2} \theta_{t t}(t, r) d r+S_{N, \sigma} \frac{1}{\rho^{N-2}} \int_{0}^{\rho} r^{N-2} r^{-\sigma} \theta^{\theta_{\sigma}^{*}-1}(t, r) d r .
$$

Moreover, we have

$$
\begin{aligned}
& \theta_{t \rho}(t, \rho)=\frac{-1}{\rho^{N-2}} \int_{0}^{\rho} r^{N-2} \theta_{t t t}(t, r) d r \\
&+S_{N, \sigma} \frac{1}{\rho^{N-2}} \int_{0}^{\rho} r^{N-2} r^{-\sigma} \partial_{t} \theta(t, r) \theta^{2_{\sigma}^{*}-2}(t, r) d r .
\end{aligned}
$$

By (a) and the fact that $2_{\sigma}^{*} \geq 2$, we obtain

$$
\left|\theta_{\rho}(t, \rho)\right|+\left|\theta_{t \rho}(t, \rho)\right| \leq C \rho+C \rho^{1-\sigma} \leq C \rho^{1-\sigma} \quad \text { for }|(t, \rho)| \leq 1
$$

Now using this in (3.3), we get $\left|\theta_{\rho \rho}\right| \leq C \rho^{-\sigma}$, for $|(t, \rho)| \leq 1$. The proof of (b) is completed.

As a consequence we derive decay estimates of the derivatives of $w$ up to order two.

Corollary 3.2. Let $w$ be a ground state for $S_{N, \sigma}$ then there exist positive constants $C_{1}, C_{2}$, depending only on $N$ and $\sigma$, such that
(a) For every $x \in \mathbb{R}^{N}$

$$
\begin{equation*}
\frac{C_{1}}{1+|x|^{N-2}} \leq w(x) \leq \frac{C_{2}}{1+|x|^{N-2}} . \tag{3.4}
\end{equation*}
$$

(b) For $|x|=|(t, z)| \leq 1,|\nabla w(x)|+|x|\left|D^{2} w(x)\right| \leq C_{2}|z|^{1-\sigma}$.
(c) For $|x|=|(t, z)| \geq 1,|\nabla w(x)|+|x|\left|D^{2} w(x)\right| \leq C_{2} \max \left(1,|z|^{-\sigma}\right)|x|^{1-N}$.

Proof. For the proof of (a), we refer to [10, Lemma 3.1]. The proof of $(\mathrm{b})$ is an immediate consequence of Lemma $3.1(\mathrm{~b})$, recalling that $w(t, z)=\theta(|t|,|z|)$. Now (c) follows by Kelvin transform, using that the function $v: \mathbb{R}^{N} \rightarrow \mathbb{R}$, given by $v(t, z)=v(x)=\theta\left(|t||x|^{-2},|z||x|^{-2}\right)|x|^{2-N}$, is also a ground-state for $S_{N, \sigma}$, thus it satisfies (b).

We close this section with the following result.
Lemma 3.3. Let $v \in \mathcal{D}^{1,2}\left(\mathbb{R}^{N}\right), N \geq 3$, satisfy $v(t, z)=\bar{\theta}(|t|,|z|)$, for some function $\bar{\theta}: \mathbb{R}_{+} \times \mathbb{R}_{+} \rightarrow \mathbb{R}$. Then for $0<r<R$, we have

$$
\begin{aligned}
& \int_{Q_{R} \backslash Q_{r}}|\nabla v|_{g}^{2} \sqrt{|g|} d x=\int_{Q_{R} \backslash Q_{r}}|\nabla v|^{2} d x+\frac{\left|\kappa\left(x_{0}\right)\right|^{2}}{N-1} \int_{Q_{R} \backslash Q_{r}}|z|^{2}\left|\partial_{t} v\right|^{2} d x \\
&+\frac{\left|\kappa\left(x_{0}\right)\right|^{2}}{2(N-1)} \int_{Q_{R} \backslash Q_{r}}|z|^{2}|\nabla v|^{2} d x+O\left(\int_{Q_{R} \backslash Q_{r}}|x|^{3}|\nabla v|^{2} d x\right) .
\end{aligned}
$$

Proof. It is easy to see that

$$
\begin{align*}
& \int_{Q_{R} \backslash Q_{r}}|\nabla v|_{g}^{2} \sqrt{|g|} d x=\int_{Q_{R} \backslash Q_{r}}|\nabla v|^{2} d x  \tag{3.5}\\
& \quad+\int_{Q_{R} \backslash Q_{r}}\left(|\nabla v|_{g}^{2}-|\nabla v|^{2}\right) \sqrt{|g|} d x+\int_{Q_{R} \backslash Q_{r}}|\nabla v|^{2}(\sqrt{|g|}-1) d x .
\end{align*}
$$

We recall that

$$
|\nabla v|_{g}^{2}(x)-|\nabla v|^{2}(x)=\sum_{\alpha \beta=1}^{N}\left[g^{\alpha \beta}(x)-\delta_{\alpha \beta}\right] \partial_{z_{\alpha}} v(x) \partial_{z_{\beta}} v(x) .
$$

It then follows that

$$
\begin{align*}
& \int_{Q_{R} \backslash Q_{r}}\left[|\nabla v|_{g}^{2}-|\nabla v|^{2}\right] \sqrt{|g|} d x=\sum_{i j=2}^{N} \int_{Q_{R} \backslash Q_{r}}\left[g^{i j}-\delta_{i j}\right] \partial_{z_{i}} v \partial_{z_{j}} v \sqrt{|g|} d x  \tag{3.6}\\
& \quad+\sum_{i=2}^{N} \int_{Q_{R} \backslash Q_{r}} g^{i 1}\left(\partial_{t} v \partial_{z_{i}} v\right) \sqrt{|g|} d x+\int_{Q_{R} \backslash Q_{r}}\left[g^{11}-1\right]\left(\partial_{t} v\right)^{2} \sqrt{|g|} d x .
\end{align*}
$$

We first use Lemma 2.2 and (2.3), to get
(3.7) $\sum_{i j=2}^{N} \int_{Q_{R} \backslash Q_{r}}\left[g^{i j}-\delta_{i j}\right] \partial_{z_{i}} v \partial_{z_{j}} v \sqrt{|g|} d x$

$$
\begin{aligned}
= & \sum_{i j=2}^{N} \sum_{l m=2}^{N} \tau_{m}^{i}(0) \tau_{l}^{j}(0) \int_{Q_{R} \backslash Q_{r}} z_{i} z_{j} z_{l} z_{m} \frac{\left|\nabla_{z} v\right|^{2}}{|z|^{2}} d x \\
& +O\left(\int_{Q_{R} \backslash Q_{r}}|x|^{3}\left|\nabla_{z} v\right|^{2} d x\right)=O\left(\int_{Q_{R} \backslash Q_{r}}|x|^{3}\left|\nabla_{z} w\right|^{2} d x\right) .
\end{aligned}
$$

Next, we observe that

$$
\sum_{i=2}^{N} \int_{Q_{R} \backslash Q_{r}} g^{i 1}\left(\partial_{t} v \cdot \partial_{i} v\right) \sqrt{|g|} d x=\sum_{i=2}^{N} \int_{Q_{R} \backslash Q_{r}} \Upsilon(|t|,|z|) t z_{i} g^{i 1} d x
$$

where $\Upsilon(|t|,|z|)=\bar{\theta}_{t}(|t|,|z|) \bar{\theta}_{\rho}(|t|,|z|) /(|t||z|)$. In addition, from (2.3), we see that

$$
\sum_{i j=2}^{N} \tau_{j}^{i}(0) z_{i} z_{j}=\sum_{i j=2}^{N}\left(\tau_{i}^{i}(0)\right)^{\prime} z_{i} z_{j}=0
$$

Consequently, from (2.9) and (2.10), we obtain

$$
\begin{align*}
& \sum_{i=2}^{N} \int_{Q_{R} \backslash Q_{r}} g^{i 1} \partial_{t} v \partial_{z_{i}} v \sqrt{|g|} d x=\int_{Q_{R} \backslash Q_{r}} \Upsilon(|t|,|z|) t \sum_{i=2}^{N} z_{i} g^{i 1} \sqrt{|g|} d t d z  \tag{3.8}\\
&=-\sum_{i j=2}^{N} \tau_{j}^{i}(0) \int_{Q_{R} \backslash Q_{r}} \Upsilon(|t|,|z|) t z_{i} z_{j} d t d z \\
&-\sum_{i j=2}^{N}\left(\tau_{j}^{i}\right)^{\prime}(0) \int_{Q_{R} \backslash Q_{r}} \Upsilon(|t|,|z|) t^{2} z_{i} z_{j} d t d z \\
&+2 \sum_{i j l=2}^{N} \kappa_{l}(0) \tau_{i}^{j}(0) \int_{Q_{R} \backslash Q_{r}} \Upsilon(|t|,|z|) t z_{i} z_{j} z_{l} d t d z \\
&-\sum_{i j l=2}^{N} \kappa^{\prime}(0) \tau_{j}^{i}(0) \int_{Q_{R} \backslash Q_{r}} \Upsilon(|t|,|z|) z_{l} z_{i} z_{j} t^{2} d t d z \\
&-\sum_{i j l=2}^{N} \tau_{j}^{i}(0) \kappa_{l}(0) \int_{Q_{R} \backslash Q_{r}} \Upsilon(|t|,|z|) z_{l} z_{i} z_{j} t d t d z \\
&+O\left(\int_{Q_{R} \backslash Q_{r}}|x|^{3}|\nabla v|^{2} d x\right)=O\left(\int_{Q_{R} \backslash Q_{r}}|x|^{3}|\nabla v|^{2} d x\right)
\end{align*}
$$

By (2.9) and (2.10), we have

$$
\begin{aligned}
& \int_{Q_{R} \backslash Q_{r}}\left|\partial_{t} v\right|^{2}\left[g^{11}-1\right] \sqrt{|g|} d x \\
&=\frac{\left|\kappa\left(x_{0}\right)\right|^{2}}{N-1} \int_{Q_{R} \backslash Q_{r}}|z|^{2}\left|\partial_{t} v\right|^{2} d x+O\left(\int_{Q_{R} \backslash Q_{r}}|x|^{3}\left|\partial_{t} v\right|^{2} d x\right) .
\end{aligned}
$$

Using this, (3.7) and (3.8) in (3.6), we then deduce that
(3.9) $\int_{Q_{R} \backslash Q_{r}}\left[|\nabla v|_{g}^{2}-|\nabla v|^{2}\right] \sqrt{|g|} d x$

$$
=\frac{\left|\kappa\left(x_{0}\right)\right|^{2}}{N-1} \int_{Q_{R} \backslash Q_{r}}|z|^{2}\left|\partial_{t} v\right|^{2} d x+O\left(\int_{Q_{R} \backslash Q_{r}}|x|^{3}|\nabla v|^{2} d x\right) .
$$

Now, by (2.9) and (2.10), we also have that

$$
\begin{aligned}
& \int_{Q_{R} \backslash Q_{r}}|\nabla v|^{2}(\sqrt{|g|}-1) d x \\
&=\frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{2(N-1)} \int_{Q_{R} \backslash Q_{r}}|z|^{2}|\nabla v|^{2} d x+O\left(\int_{Q_{R}}|x|^{3}|\nabla v|^{2} d x\right) .
\end{aligned}
$$

This with (3.9) and (3.5) give the desired result.

## 4. Existence of minimzers for $\mu_{h}(\Omega, \Gamma)$ in dimension $N \geq 4$

We consider $\Omega$, a bounded domain of $\mathbb{R}^{N}, N \geq 3$, and $\Gamma \subset \Omega$, a smooth closed curve. For $u \in H_{0}^{1}(\Omega) \backslash\{0\}$, we define the ratio

$$
\begin{equation*}
J(u):=\frac{\int_{\Omega}|\nabla u|^{2} d y+\int_{\Omega} h u^{2} d y}{\left(\int_{\Omega} \rho_{\Gamma}^{-\sigma}|u|^{2 *} d y\right)^{2 / 2_{\sigma}^{*}}} . \tag{4.1}
\end{equation*}
$$

We let $\eta \in \mathcal{C}_{c}^{\infty}\left(F_{y_{0}}\left(Q_{2 r}\right)\right)$ be such that $0 \leq \eta \leq 1$ and $\eta \equiv 1$ in $Q_{r}$. For $\varepsilon>0$, we consider $u_{\varepsilon}: \Omega \rightarrow \mathbb{R}$ given by

$$
\begin{equation*}
u_{\varepsilon}(y):=\varepsilon^{(2-N) / 2} \eta\left(F_{y_{0}}^{-1}(y)\right) w\left(\varepsilon^{-1} F_{y_{0}}^{-1}(y)\right) . \tag{4.2}
\end{equation*}
$$

In particular, for every $x=(t, z) \in \mathbb{R} \times \mathbb{R}^{N-1}$, we have

$$
\begin{equation*}
u_{\varepsilon}\left(F_{y_{0}}(x)\right):=\varepsilon^{(2-N) / 2} \eta(x) \theta(|t| / \varepsilon,|z| / \varepsilon) \tag{4.3}
\end{equation*}
$$

It is clear that $u_{\varepsilon} \in H_{0}^{1}(\Omega)$. We have the following
Lemma 4.1. For $J$ given by (4.1) and $u_{\varepsilon}$ given by (4.2), as $\varepsilon \rightarrow 0$, we have

$$
\begin{align*}
J\left(u_{\varepsilon}\right)= & S_{N, \sigma}+\varepsilon^{2} \frac{\left|\kappa\left(x_{0}\right)\right|^{2}}{N-1} \int_{Q_{r / \varepsilon}}|z|^{2}\left|\partial_{t} w\right|^{2} d x  \tag{4.4}\\
& +\varepsilon^{2} \frac{\left|\kappa\left(x_{0}\right)\right|^{2}}{2(N-1)} \int_{Q_{r / \varepsilon}}|z|^{2}|\nabla w|^{2} d x \\
& -\frac{\varepsilon^{2}}{2_{\sigma}^{*}} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{(N-1)} S_{N, \sigma} \int_{Q_{r / \varepsilon}}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x+\varepsilon^{2} h\left(y_{0}\right) \int_{Q_{r / \varepsilon}} w^{2} d x \\
& +O\left(\varepsilon^{2} \int_{Q_{r / \varepsilon}}\left|h\left(F_{y_{0}}(\varepsilon x)\right)-h\left(y_{0}\right)\right| w^{2} d x\right)+O\left(\varepsilon^{N-2}\right) .
\end{align*}
$$

Proof. To simplify the notations, we will write $F$ in the place of $F_{y_{0}}$. Recalling (4.2), we write

$$
u_{\varepsilon}(y)=\varepsilon^{(2-N) / 2} \eta\left(F^{-1}(y)\right) W_{\varepsilon}(y), \quad \text { where } W_{\varepsilon}(y)=w\left(\frac{F^{-1}(y)}{\varepsilon}\right)
$$

Then $\left|\nabla u_{\varepsilon}\right|^{2}=\varepsilon^{2-N}\left(\eta^{2}\left|\nabla W_{\varepsilon}\right|^{2}+\eta^{2}\left|\nabla W_{\varepsilon}\right|^{2}+\nabla W_{\varepsilon}^{2} \cdot \nabla \eta^{2} / 2\right)$. Integrating by parts, we have

$$
\begin{align*}
& \int_{\Omega}\left|\nabla u_{\varepsilon}\right|^{2} d y=\varepsilon^{2-N} \int_{F\left(Q_{2 r}\right)} \eta^{2}\left|\nabla W_{\varepsilon}\right|^{2} d y  \tag{4.5}\\
&+\varepsilon^{2-N} \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)} W_{\varepsilon}^{2}\left(|\nabla \eta|^{2}-\frac{1}{2} \Delta \eta^{2}\right) d y \\
&= \varepsilon^{2-N} \int_{F\left(Q_{2 r}\right)} \eta^{2}\left|\nabla W_{\varepsilon}\right|^{2} d y-\varepsilon^{2-N} \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)} W_{\varepsilon}^{2} \eta \Delta \eta d y \\
&= \varepsilon^{2-N} \int_{F\left(Q_{2 r}\right)} \eta^{2}\left|\nabla W_{\varepsilon}\right|^{2} d y+O\left(\varepsilon^{2-N} \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)} W_{\varepsilon}^{2} d y\right) .
\end{align*}
$$

By the change of variable $y=F(x) / \varepsilon$ and (4.3), we can apply Lemma 3.3, to get

$$
\begin{aligned}
\int_{\Omega}\left|\nabla u_{\varepsilon}\right|^{2} d y= & \int_{Q_{r / \varepsilon}}|\nabla w|_{g_{\varepsilon}}^{2} \sqrt{\left|g_{\varepsilon}\right|} d x \\
& +O\left(\varepsilon^{2} \int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}} w^{2} d x+\int_{Q_{2 r / \varepsilon \backslash Q_{r / \varepsilon}}}|\nabla w|^{2} d x\right) \\
= & \int_{\mathbb{R}^{N}}|\nabla w|^{2} d x+\varepsilon^{2} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{N-1} \int_{Q_{r / \varepsilon}}|z|^{2}\left|\partial_{t} w\right|^{2} d x \\
& +\varepsilon^{2} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{2(N-1)} \int_{Q_{r / \varepsilon}}|z|^{2}|\nabla w|^{2} d x \\
& +O\left(\varepsilon^{3} \int_{Q_{r / \varepsilon}}|x|^{3}|\nabla w|^{2} d x+\varepsilon^{2} \int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}}|w|^{2} d x\right. \\
& \left.+\int_{\mathbb{R}^{N} \backslash Q_{r / \varepsilon}}|\nabla w|^{2} d x+\varepsilon^{2} \int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}}|z|^{2}|\nabla w|^{2} d x\right) \\
= & S_{N, \sigma}+\varepsilon^{2} \frac{3\left|\kappa\left(y_{0}\right)\right|^{2}}{2(N-1)} \int_{Q_{2 r / \varepsilon}}|z|^{2}|\nabla w|^{2} d x \\
& +O\left(\varepsilon^{3} \int_{Q_{r / \varepsilon}}|x|^{3}|\nabla w|^{2} d x+\varepsilon^{2} \int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}}|w|^{2} d x\right) .
\end{aligned}
$$

Using Corollary 3.2, we find that

$$
\begin{aligned}
& \int_{\Omega}\left|\nabla u_{\varepsilon}\right|^{2} d y=S_{N, \sigma}+\varepsilon^{2} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{N-1} \int_{Q_{r / \varepsilon}}|z|^{2}\left|\partial_{t} w\right|^{2} d x \\
& \quad \quad+\varepsilon^{2} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{2(N-1)} \int_{Q_{r / \varepsilon}}|z|^{2}|\nabla w|^{2} d x+O\left(\varepsilon^{N-2}\right) .
\end{aligned}
$$

By the change of variable $y=F(x) / \varepsilon$, (3.2), (2.1) and (2.9), we get

$$
\begin{aligned}
\int_{\Omega} \rho_{\Gamma}^{-\sigma}\left|u_{\varepsilon}\right|^{2_{\sigma}^{*}} d y= & \int_{Q_{r / \varepsilon}}|z|^{-s} w^{2_{\sigma}^{*}} \sqrt{\left|g_{\varepsilon}\right|} d x+O\left(\int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}}|z|^{-\sigma}(\eta(\varepsilon x) w)^{2_{\sigma}^{*}} d x\right) \\
= & \int_{Q_{r / \varepsilon}}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x+\varepsilon^{2} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{2(N-1)} \int_{Q_{r / \varepsilon}}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x \\
& +O\left(\varepsilon^{3} \int_{Q_{r / \varepsilon}}|x|^{3}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x+\int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x\right) \\
= & 1+\varepsilon^{2} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{2(N-1)} \int_{Q_{r / \varepsilon}}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x \\
& +O\left(\varepsilon^{3} \int_{Q_{r / \varepsilon}}|x|^{3}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x\right. \\
& \left.+\int_{\mathbb{R}^{N} \backslash Q_{r / \varepsilon}}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x+\int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x\right) .
\end{aligned}
$$

Using (3.4), we have

$$
\begin{aligned}
& \varepsilon^{3} \int_{Q_{r / \varepsilon}}|x|^{3}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x+\int_{\mathbb{R}^{N} \backslash Q_{r / \varepsilon}}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x \\
&+\int_{Q_{2 r / \varepsilon \backslash Q_{r / \varepsilon}}}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x=O\left(\varepsilon^{N-\sigma}\right) .
\end{aligned}
$$

Hence by Taylor expansion, we get

$$
\left(\int_{\Omega} \rho_{\Gamma}^{-\sigma}\left|u_{\varepsilon}\right|^{2_{\sigma}^{*}} d x\right)^{2 / 2_{\sigma}^{*}}=1+\frac{\varepsilon^{2}}{2_{\sigma}^{*}} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{(N-1)} \int_{Q_{r / \varepsilon}}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x+O\left(\varepsilon^{N-\sigma}\right)
$$

Finally, by (4.5), we conclude that

$$
\begin{aligned}
J\left(u_{\varepsilon}\right)= & S_{N, \sigma}+\varepsilon^{2} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{N-1} \int_{Q_{r / \varepsilon}}|z|^{2}\left|\partial_{t} w\right|^{2} d x+\varepsilon^{2} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{2(N-1)} \int_{Q_{r / \varepsilon}}|z|^{2}|\nabla w|^{2} d x \\
& -\frac{\varepsilon^{2}}{2_{\sigma}^{*}} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{(N-1)} S_{N, \sigma} \int_{Q_{r / \varepsilon}}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x+\varepsilon^{2} h\left(y_{0}\right) \int_{Q_{r / \varepsilon}} w^{2} d x \\
& +O\left(\varepsilon^{2} \int_{Q_{r / \varepsilon}} \mid h\left(F_{y_{0}}(\varepsilon x)-h\left(y_{0}\right) \mid w^{2} d x\right)+O\left(\varepsilon^{N-2}\right) .\right.
\end{aligned}
$$

We thus get the desired result.
Proposition 4.2. For $N \geq 5$, we define

$$
\begin{aligned}
& A_{N, \sigma}:=\frac{1}{N-1} \int_{\mathbb{R}^{N}}|z|^{2}\left|\partial_{t} w\right|^{2} d x \\
&+\left(\frac{1}{2}-\frac{1}{2_{\sigma}^{*}}\right) \frac{1}{N-1} \int_{\mathbb{R}^{N}}|z|^{2}|\nabla w|^{2} d x+\frac{1}{2_{\sigma}^{*}} \int_{\mathbb{R}^{N}} w^{2} d x>0
\end{aligned}
$$

and

$$
B_{N, \sigma}:=\int_{\mathbb{R}^{N}} w^{2} d x
$$

Assume that, for some $y_{0} \in \Gamma$, there holds

$$
\begin{cases}h\left(y_{0}\right)<-\frac{A_{N, \sigma}}{B_{N, \sigma}}\left|\kappa\left(y_{0}\right)\right|^{2} & \text { for } N \geq 5, \\ h\left(y_{0}\right)<-\frac{3}{2}\left|\kappa\left(y_{0}\right)\right|^{2} & \text { for } N=4 .\end{cases}
$$

Then $\mu_{h}(\Omega, \Gamma)<S_{N, \sigma}$.
Proof. We claim that

$$
\begin{align*}
S_{N, \sigma} \int_{Q_{r / \varepsilon}}|z|^{2-\sigma} & w^{2_{\sigma}^{*}} d x  \tag{4.6}\\
& =\int_{Q_{r / \varepsilon}}|z|^{2}|\nabla w|^{2} d x-(N-1) \int_{Q_{r / \varepsilon}} w^{2} d x+O\left(\varepsilon^{N-2}\right)
\end{align*}
$$

To prove this claim, we let $\eta_{\varepsilon}(x)=\eta(\varepsilon x)$. We multiply (3.1) by $|z|^{2} \eta_{\varepsilon} w$ and integrate by parts to get

$$
\begin{aligned}
S_{N, \sigma} \int_{Q_{2 r / \varepsilon}} & \eta_{\varepsilon}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x=\int_{Q_{2 r / \varepsilon}} \nabla w \cdot \nabla\left(\eta_{\varepsilon}|z|^{2} w\right) d x \\
= & \int_{Q_{2 r / \varepsilon}} \eta_{\varepsilon}|z|^{2}|\nabla w|^{2} d x \\
& +\frac{1}{2} \int_{Q_{2 r / \varepsilon}} \nabla w^{2} \cdot \nabla\left(|z|^{2} \eta_{\varepsilon}\right) d x \int_{Q_{2 r / \varepsilon}} \eta_{\varepsilon}|z|^{2}|\nabla w|^{2} d x \\
& -\frac{1}{2} \int_{Q_{2 r / \varepsilon}} w^{2} \Delta\left(|z|^{2} \eta_{\varepsilon}\right) d x \\
= & \int_{Q_{2 r / \varepsilon}} \eta_{\varepsilon}|z|^{2}|\nabla w|^{2} d x-(N-1) \int_{Q_{2 r / \varepsilon}} w^{2} \eta_{\varepsilon} d x \\
= & -\frac{1}{2} \int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}} w^{2}\left(|z|^{2} \Delta \eta_{\varepsilon}+4 \nabla \eta_{\varepsilon} \cdot z\right) d x .
\end{aligned}
$$

We then deduce that

$$
\begin{aligned}
& S_{N, \sigma} \int_{Q_{r / \varepsilon}}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x=\int_{Q_{r / \varepsilon}}|z|^{2}|\nabla w|^{2} d x-(N-1) \int_{Q_{r / \varepsilon}} w^{2} d x \\
&+O\left(\int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x\right. \\
&+\int_{\left.Q_{2 r / \varepsilon \backslash Q_{r / \varepsilon}}|z|^{2}|\nabla w|^{2} d x+\int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}} w^{2} d x\right)}+O\left(\varepsilon \int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}}|z||\nabla w| d x+\varepsilon^{2} \int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}}|z|^{2} w^{2} d x\right) .
\end{aligned}
$$

Thanks to Corollary 3.2, we get (4.6) as claimed.
Next, by the continuity of $h$, for $\delta>0$, we can find $r_{\delta}>0$ such that

$$
\begin{equation*}
\left|h(y)-h\left(y_{0}\right)\right|<\delta \quad \text { for every } y \in F\left(Q_{r_{\delta}}\right) . \tag{4.7}
\end{equation*}
$$

CASE $N \geq 5$. Using (4.6) and (4.7) in (4.4), we obtain, for every $r \in\left(0, r_{\delta}\right)$,

$$
\begin{aligned}
J\left(u_{\varepsilon}\right)= & S_{N, \sigma}+\varepsilon^{2} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{N-1} \int_{\mathbb{R}^{N}}|z|^{2}\left|\partial_{t} w\right|^{2} d x \\
& +\varepsilon^{2}\left(\frac{1}{2}-\frac{1}{2_{\sigma}^{*}}\right) \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{N-1} \int_{\mathbb{R}^{N}}|z|^{2}|\nabla w|^{2} d x \\
& +\frac{\varepsilon^{2}}{2_{\sigma}^{*}}\left|\kappa\left(y_{0}\right)\right|^{2} \int_{\mathbb{R}^{N}} w^{2} d x+\varepsilon^{2} h\left(y_{0}\right) \int_{\mathbb{R}^{N}} w^{2} d x \\
& +O\left(\varepsilon^{2} \delta^{2} \int_{\mathbb{R}^{N}} w^{2} d x\right)+O\left(\varepsilon^{N-2}\right),
\end{aligned}
$$

where we have used Corollary 3.2 to get the estimates

$$
\int_{\mathbb{R}^{N} \backslash Q_{r / \varepsilon}}|z|^{2}|\nabla w|^{2} d x+\int_{\mathbb{R}^{N} \backslash Q_{r / \varepsilon}} w^{2} d x=O(\varepsilon) .
$$

It follows that, for every $r \in\left(0, r_{\delta}\right)$,

$$
J\left(u_{\varepsilon}\right)=S_{N, \sigma}+\varepsilon^{2}\left\{A_{N, \sigma}\left|\kappa\left(y_{0}\right)\right|^{2}+B_{N, \sigma} h\left(y_{0}\right)\right\}+O\left(\delta \varepsilon^{2} B_{N, \sigma}\right)+O\left(\varepsilon^{3}\right) .
$$

Suppose now that $A_{N, \sigma}\left|\kappa\left(y_{0}\right)\right|^{2}+B_{N, \sigma} h\left(y_{0}\right)<0$. We can thus choose respectively $\delta>0$ small and $\varepsilon>0$ small so that $J\left(u_{\varepsilon}\right)<S_{N, \sigma}$. Hence we get $\mu_{h}(\Omega, \Gamma)<S_{N, \sigma}$.

CaSE $N=4$. From (4.4) and (4.7), we estimate, for every $r \in\left(0, r_{\delta}\right)$,

$$
\begin{aligned}
J\left(u_{\varepsilon}\right) \leq & S_{N, \sigma}+\varepsilon^{2} \frac{3\left|\kappa\left(y_{0}\right)\right|^{2}}{2(N-1)} \int_{Q_{r / \varepsilon}}|z|^{2}|\nabla w|^{2} d x \\
& -\frac{\varepsilon^{2}}{2_{\sigma}^{*}} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{(N-1)} S_{N, \sigma} \int_{Q_{r / \varepsilon}}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x \\
& +\varepsilon^{2} h\left(y_{0}\right) \int_{Q_{r / \varepsilon}} w^{2} d x+O\left(\varepsilon^{2} \delta \int_{Q_{r / \varepsilon}} w^{2} d x\right)+O\left(\varepsilon^{N-2}\right) .
\end{aligned}
$$

This with (4.6) yield

$$
\begin{aligned}
J\left(u_{\varepsilon}\right) \leq & S_{N, \sigma}+\varepsilon^{2} \frac{3\left|\kappa\left(y_{0}\right)\right|^{2}}{2(N-1)} S_{N, \sigma} \int_{Q_{r / \varepsilon}}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x \\
& -\frac{\varepsilon^{2}}{2_{\sigma}^{*}} \frac{\left|\kappa\left(y_{0}\right)\right|^{2}}{(N-1)} S_{N, \sigma} \int_{Q_{r / \varepsilon}}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x \\
& +\varepsilon^{2}\left(\frac{3}{2}\left|\kappa\left(y_{0}\right)\right|^{2}+h\left(y_{0}\right)\right) \int_{Q_{r / \varepsilon}} w^{2} d x \\
& +O\left(\varepsilon^{2} \delta \int_{Q_{r / \varepsilon}} w^{2} d x\right)+O\left(\varepsilon^{N-2}\right) .
\end{aligned}
$$

Since, by (3.4),

$$
\int_{Q_{r / \varepsilon}}|z|^{2-\sigma} w^{2_{\sigma}^{*}} d x=O(1)
$$

we therefore have

$$
\begin{aligned}
& J\left(u_{\varepsilon}\right) \leq S_{4, \sigma}+\varepsilon^{2}\left(\frac{3\left|\kappa\left(y_{0}\right)\right|^{2}}{2}+h\left(y_{0}\right)\right) \int_{Q_{r / \varepsilon}} w^{2} d x \\
&+O\left(\varepsilon^{2} \delta \int_{Q_{r / \varepsilon}} w^{2} d x\right)+C \varepsilon^{2},
\end{aligned}
$$

for some positive constant $C$ independent of $\varepsilon$. By (3.4), we have that

$$
\int_{Q_{r / \varepsilon}} \frac{C_{1}^{2}}{1+|x|^{2}} d x \leq \int_{Q_{r / \varepsilon}} w^{2} d x \leq \int_{Q_{r / \varepsilon}} \frac{C_{2}^{2}}{1+|x|^{2}} d x
$$

so that

$$
\begin{equation*}
\int_{B_{\mathbb{R}^{4}}(0, r / \varepsilon)} \frac{C_{1}^{2}}{\left(1+|x|^{2}\right)^{2}} d x \leq \int_{Q_{r / \varepsilon}} w^{2} d x \leq \int_{B_{\mathbb{R}^{4}}(0,2 r / \varepsilon)} \frac{C_{2}^{2}}{\left(1+|x|^{2}\right)^{2}} d x . \tag{4.8}
\end{equation*}
$$

Using polar coordinates and a change of variable, for $R>0$, we have

$$
\begin{aligned}
& \int_{B_{\mathbb{R}^{4}}(0, R)} \frac{d x}{\left(1+|x|^{2}\right)^{2}} d x=\left|S^{3}\right| \int_{0}^{R} \frac{t^{3}}{\left(1+t^{2}\right)^{2}} d t \\
& \quad=\left|S^{3}\right| \int_{0}^{\sqrt{R}} \frac{s}{2(1+s t)^{2}} d s=\frac{\left|S^{3}\right|}{2}\left(\log (1+\sqrt{R})-\frac{\sqrt{R}}{1+\sqrt{R}}\right)
\end{aligned}
$$

Therefore, there exist numerical constants $c, \bar{c}>0$ such that for every $\varepsilon>0$ small, we have

$$
\begin{equation*}
c|\log \varepsilon| \leq \int_{Q_{r / \varepsilon}} w^{2} d x \leq \bar{c}|\log \varepsilon| \tag{4.9}
\end{equation*}
$$

Now we assume that $3\left|\kappa\left(y_{0}\right)\right|^{2} / 2+h\left(y_{0}\right)<0$. Therefore by Lemma 4.1 and (4.9), we get

$$
J\left(u_{\varepsilon}\right) \leq S_{4, s}+c\left(\frac{3}{2}\left|\kappa\left(y_{0}\right)\right|^{2}+h\left(y_{0}\right)\right) \varepsilon^{2}|\log \varepsilon|+\bar{c} \delta \varepsilon^{2}|\log \varepsilon|+C \varepsilon^{2}
$$

Then, choosing $\delta>0$ small and $\varepsilon$ small, respectively, we deduce that $\mu_{h}(\Omega, \Gamma) \leq$ $J\left(u_{\varepsilon}\right)<S_{4, \sigma}$.

Proof of Theorem 1.1 (completed). By a classical partition of unity (see, e.g., [2, Section 2.27]), we have that for every $r>0$, there exist positive constants $c_{r}>0$, depending only on $\Omega, \Gamma, N, \sigma$ and $r$, such that for every $u \in H_{0}^{1}(\Omega)$,

$$
\begin{equation*}
S_{N, \sigma}\left(\int_{\Omega} \rho_{\Gamma}^{-\sigma}|u|^{2_{\sigma}^{*}} d y\right)^{2 / 2_{\sigma}^{*}} \leq(1+r) \int_{\Omega}|\nabla u|^{2} d y+c_{r}+\left(\int_{\Omega}|u|^{2_{\sigma}^{*}} d y\right)^{2 / 2_{\sigma}^{*}} \tag{4.10}
\end{equation*}
$$

By this and Proposition 4.2, the proof of Theorem 1.1 is completed, since if $\mu_{h}(\Omega, \Gamma)<S_{N, \sigma}$ then every minimizing sequence for $\mu_{h}(\Omega, \Gamma)$ converges, up to a subsequence, to a minimizer in $H_{0}^{1}(\Omega)$, which is positive.

## 5. Existence of minimizer for $\mu_{h}(\Omega, \Gamma)$ in dimension three

We consider the function $\mathcal{R}: \mathbb{R}^{3} \backslash\{0\} \rightarrow \mathbb{R}$, defined by $x \mapsto \mathcal{R}(x)=1 /|x|$ which satisfies

$$
\begin{equation*}
-\Delta \mathcal{R}=0 \quad \text { in } \mathbb{R}^{3} \backslash\{0\} \tag{5.1}
\end{equation*}
$$

We denote by $G$ the solution to the equation

$$
\begin{cases}-\Delta_{x} G(y, \cdot)+h G(y, \cdot)=0 & \text { in } \Omega \backslash\{y\}  \tag{5.2}\\ G(y, \cdot)=0 & \text { on } \partial \Omega\end{cases}
$$

and satisfying

$$
\begin{equation*}
G(x, y)=\mathcal{R}(x-y)+O(1) \quad \text { for } x, y \in \Omega \text { and } x \neq y \tag{5.3}
\end{equation*}
$$

We note that $G$ is proportional to the Green function of $-\Delta+h$ with zero Dirichlet data.

We let $\chi \in C_{c}^{\infty}(-2,2)$ with $\chi \equiv 1$ on $(-1,1)$ and $0 \leq \chi \leq 1$. For $r>0$, we consider the cylindrical symmetric cut-off function

$$
\begin{equation*}
\eta_{r}(t, z)=\chi\left(\frac{|t|+|z|}{r}\right) \quad \text { for every }(t, z) \in \mathbb{R} \times \mathbb{R}^{2} . \tag{5.4}
\end{equation*}
$$

It is clear that

$$
\eta_{r} \equiv 1 \quad \text { in } Q_{r}, \quad \eta_{r} \in H_{0}^{1}\left(Q_{2 r}\right), \quad\left|\nabla \eta_{r}\right| \leq \frac{C}{r} \quad \text { in } \mathbb{R}^{3}
$$

For $y_{0} \in \Omega$, we let $r_{0} \in(0,1)$ such that

$$
\begin{equation*}
y_{0}+Q_{2 r_{0}} \subset \Omega . \tag{5.5}
\end{equation*}
$$

We define the function $M_{y_{0}}: Q_{2 r_{0}} \rightarrow \mathbb{R}$ given by

$$
\begin{equation*}
M_{y_{0}}(x):=G\left(y_{0}, x+y_{0}\right)-\eta_{r}(x) \frac{1}{|x|} \quad \text { for every } x \in Q_{2 r_{0}} \tag{5.6}
\end{equation*}
$$

It follows from (5.3) that $M_{y_{0}} \in L^{\infty}\left(Q_{r_{0}}\right)$. By (5.2) and (5.1),

$$
\left|-\Delta M_{y_{0}}(x)+h(x) M_{y_{0}}(x)\right| \leq \frac{C}{|x|}=C \mathcal{R}(x) \quad \text { for every } x \in Q_{r_{0}}
$$

whereas $\mathcal{R} \in L^{p}\left(Q_{r_{0}}\right)$ for every $p \in(1,3)$. Hence by elliptic regularity theory, $M_{y_{0}} \in W^{2, p}\left(Q_{r_{0} / 2}\right)$ for every $p \in(1,3)$. Therefore by Morrey's embedding theorem, we deduce that

$$
\begin{equation*}
\left\|M_{y_{0}}\right\|_{C^{1, \varrho}\left(Q_{r_{0} / 2}\right)} \leq C \quad \text { for every } \varrho \in(0,1) \tag{5.7}
\end{equation*}
$$

In view of (1.6), the mass of the operator $-\Delta+h$ in $\Omega$ at the point $y_{0} \in \Omega$ is given by

$$
\begin{equation*}
\mathbf{m}\left(y_{0}\right)=M_{y_{0}}(0) . \tag{5.8}
\end{equation*}
$$

We recall that the positive ground state solution $w$ satisfies

$$
\begin{equation*}
-\Delta w=S_{3, \sigma}|z|^{-\sigma} w^{2_{\sigma}^{*}-1} \quad \text { in } \mathbb{R}^{3}, \quad \int_{\mathbb{R}^{3}}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x=1 \tag{5.9}
\end{equation*}
$$

where $x=(t, z) \in \mathbb{R} \times \mathbb{R}^{2}$. In addition by (3.4), we have

$$
\begin{equation*}
\frac{C_{1}}{1+|x|} \leq w(x) \leq \frac{C_{2}}{1+|x|} \quad \text { for every } x \in \mathbb{R}^{3} \tag{5.10}
\end{equation*}
$$

The following result will be crucial for the rest of this section.

Lemma 5.1. Consider the function $v_{\varepsilon}: \mathbb{R}^{3} \backslash\{0\} \rightarrow \mathbb{R}$ given by

$$
v_{\varepsilon}(x)=\varepsilon^{-1} w\left(\frac{x}{\varepsilon}\right) .
$$

Then there exist a constant $\mathbf{c}>0$ and a sequence $\left(\varepsilon_{n}\right)_{n \in \mathbb{N}}$ (still denoted by $\varepsilon$ ) such that

$$
v_{\varepsilon}(x) \rightarrow \frac{\mathbf{c}}{|x|} \quad \text { and } \quad \nabla v_{\varepsilon}(x) \rightarrow-\mathbf{c} \frac{x}{|x|^{3}} \quad \text { for all most every } x \in \mathbb{R}^{3}
$$

and
(5.11) $\quad v_{\varepsilon}(x) \rightarrow \frac{\mathbf{c}}{|x|} \quad$ and $\quad \nabla v_{\varepsilon}(x) \rightarrow-\mathbf{c} \frac{x}{|x|^{3}} \quad$ for every $x \in \mathbb{R}^{3} \backslash\{z=0\}$.

Proof. By Corollary 3.2, we have that $\left(v_{\varepsilon}\right)$ is bounded in $C_{\text {loc }}^{2}\left(\mathbb{R}^{3} \backslash\{z=0\}\right)$. Therefore by Arzelá-Ascoli's theorem $v_{\varepsilon}$ converges to $v$ in $C_{\mathrm{loc}}^{1}\left(\mathbb{R}^{3} \backslash\{z=0\}\right)$. In particular,

$$
v_{\varepsilon} \rightarrow v \quad \text { and } \quad \nabla v_{\varepsilon} \rightarrow \nabla v \quad \text { almost every where on } \mathbb{R}^{3} .
$$

It is plain, from (5.10), that

$$
\begin{equation*}
0<\frac{C_{1}}{\varepsilon+|x|} \leq v_{\varepsilon}(x) \leq \frac{C_{2}}{\varepsilon+|x|} \quad \text { for almost every } x \in \mathbb{R}^{3} \tag{5.12}
\end{equation*}
$$

By (5.9), we have

$$
\begin{equation*}
-\Delta v_{\varepsilon}(x)=\varepsilon^{2-\sigma} f_{\varepsilon}(x) \quad \text { in } \mathbb{R}^{3}, \tag{5.13}
\end{equation*}
$$

where
$f_{\varepsilon}(x)=S_{3, \sigma}|z|^{-\sigma} v_{\varepsilon}^{2_{\sigma}^{*}-1}(x) \leq C|z|^{-\sigma}|x|^{-5+2 \sigma} \quad$ for almost every $x=(t, z) \in \mathbb{R}^{3}$.
We let $\varphi \in C_{c}^{\infty}\left(\mathbb{R}^{3} \backslash\{0\}\right)$. We multiply (5.13) by $\varphi$ and integrate by parts to get

$$
-\int_{\mathbb{R}^{3}} v_{\varepsilon} \Delta \varphi d x=\varepsilon^{2-\sigma} \int_{\mathbb{R}^{3}} f_{\varepsilon}(x) \varphi(x) d x .
$$

By (5.12) and the dominated convergence theorem, we can pass to the limit in the above identity and deduce that $\Delta v=0$ in $\mathcal{D}^{\prime}\left(\mathbb{R}^{3} \backslash\{0\}\right)$. In particular $v$ is equivalent to a function of class $C^{\infty}\left(\mathbb{R}^{3} \backslash\{0\}\right)$ which is still denoted by $v$. Thanks to (5.12), by Bôcher's theorem, there exists a constant $\mathbf{c}>0$ such that $v(x)=\mathbf{c} /|x|$. The proof of the lemma is thus finished.

We start by recording some useful estimates.
Lemma 5.2. There exists a constant $C>0$ such that for every $\varepsilon, r \in$ ( $0, r_{0} / 2$ ), we have

$$
\begin{gather*}
\int_{Q_{r / \varepsilon}}|\nabla w|^{2} d x \leq C \max \left(1, \frac{\varepsilon}{r}\right), \quad \int_{Q_{r / \varepsilon}}|w|^{2} d x \leq C \max \left(1, \frac{r}{\varepsilon}\right),  \tag{5.14}\\
\int_{Q_{r / \varepsilon}} w|\nabla w| d x \leq C \max \left(1, \log \frac{r}{\varepsilon}\right) \tag{5.15}
\end{gather*}
$$

$$
\begin{equation*}
\int_{Q_{r / \varepsilon}}|\nabla w| d x \leq C \max \left(1, \frac{r}{\varepsilon}\right), \quad \int_{Q_{r / \varepsilon}}|w| d x \leq C \max \left(1, \frac{r^{2}}{\varepsilon^{2}}\right) \tag{5.16}
\end{equation*}
$$

and

$$
\begin{align*}
& \varepsilon^{2} \int_{Q_{r / \varepsilon}}|z|^{-\sigma}|x|^{2} w^{2_{\sigma}^{*}} d x+\varepsilon \int_{Q_{4 r / \varepsilon} \backslash Q_{r / \varepsilon}}|z|^{-\sigma} w^{2_{\sigma}^{*}-1} d x  \tag{5.17}\\
& \quad+\int_{\mathbb{R}^{3} \backslash Q_{r / \varepsilon}}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x \leq C r^{\sigma-3} \varepsilon^{3-\sigma}
\end{align*}
$$

Proof. The proof of this lemma is not difficult and uses only the estimates in Corollary 3.2. We therefore skip the details.
5.1. Proof of Theorem 1.3. Given $y_{0} \in \Gamma \subset \Omega \subset \mathbb{R}^{3}$, we let $r_{0}$ as defined in (5.5). For $r \in\left(0, r_{0} / 2\right)$, we consider $F_{y_{0}}: Q_{r} \rightarrow \Omega$ (see Section 2) parameterizing a neighbourhood of $y_{0}$ in $\Omega$, with the property that $F_{y_{0}}(0)=y_{0}$. For $\varepsilon>0$, we consider $u_{\varepsilon}: \Omega \rightarrow \mathbb{R}$ given by

$$
u_{\varepsilon}(y):=\varepsilon^{-1 / 2} \eta_{r}\left(F_{y_{0}}^{-1}(y)\right) w\left(\frac{F_{y_{0}}^{-1}(y)}{\varepsilon}\right)
$$

We can now define the test function $\Psi_{\varepsilon}: \Omega \rightarrow \mathbb{R}$ by

$$
\begin{equation*}
\Psi_{\varepsilon}(y)=u_{\varepsilon}(y)+\varepsilon^{1 / 2} \mathbf{c} \eta_{2 r}\left(F_{y_{0}}^{-1}(y)\right) M_{y_{0}}\left(F_{y_{0}}^{-1}(y)\right) . \tag{5.18}
\end{equation*}
$$

It is plain that $\Psi_{\varepsilon} \in H_{0}^{1}(\Omega)$ and

$$
\Psi_{\varepsilon}\left(F_{y_{0}}(x)\right)=\varepsilon^{-1 / 2} \eta_{r}(x) w\left(\frac{x}{\varepsilon}\right)+\varepsilon^{1 / 2} \mathbf{c} \eta_{2 r}(x) M_{y_{0}}(x) \quad \text { for every } x \in \mathbb{R}^{N}
$$

The main result of this section is contained in the following
Proposition 5.3. Let $\left(\varepsilon_{n}\right)_{n \in \mathbb{N}}$ and $\mathbf{c}$ be the sequence and the number given by Lemma 5.1. Then there exist $r_{0}, n_{0}>0$ such that, for every $r \in\left(0, r_{0}\right)$ and $n \geq n_{0}$,

$$
J\left(\Psi_{\varepsilon}\right):=\frac{\int_{\Omega}\left|\nabla \Psi_{\varepsilon_{n}}\right|^{2} d y+\int_{\Omega} h\left|\Psi_{\varepsilon_{n}}\right|^{2} d y}{\left(\int_{\Omega} \rho_{\Gamma}^{-\sigma}\left|\Psi_{\varepsilon_{n}}\right|^{2_{\sigma}^{*}} d y\right)^{2 / 2_{\sigma}^{*}}}=S_{3, \sigma}-\varepsilon_{n} \pi^{2} \mathbf{m}\left(y_{0}\right) \mathbf{c}^{2}+\mathcal{O}_{r}\left(\varepsilon_{n}\right)
$$

for some numbers $\mathcal{O}_{r}\left(\varepsilon_{n}\right)$ satisfying $\lim _{r \rightarrow 0} \lim _{n \rightarrow \infty} \varepsilon_{n}^{-1} \mathcal{O}_{r}\left(\varepsilon_{n}\right)=0$.
The proof of this proposition will be separated into two steps given by Lemmas 5.4 and 5.5 below. To alleviate the notations, we will write $\varepsilon$ instead of $\varepsilon_{n}$ and we will remove the subscript $y_{0}$, by writing $M$ and $F$ in the place of $M_{y_{0}}$ and $F_{y_{0}}$, respectively. We define

$$
\begin{gathered}
\widetilde{\eta}_{r}(y):=\eta_{r}\left(F^{-1}(y)\right), \quad V_{\varepsilon}(y):=v_{\varepsilon}\left(F^{-1}(y)\right) \\
\widetilde{M}_{2 r}(y):=\eta_{2 r}\left(F^{-1}(y)\right) M\left(F^{-1}(y)\right)
\end{gathered}
$$

where $v_{\varepsilon}(x)=\varepsilon^{-1} w(x / \varepsilon)$. With these notations, (5.18) becomes

$$
\begin{equation*}
\Psi_{\varepsilon}(y)=u_{\varepsilon}(y)+\varepsilon^{1 / 2} \mathbf{c} \widetilde{M}_{2 r}(y)=\varepsilon^{1 / 2} V_{\varepsilon}(y)+\varepsilon^{1 / 2} \mathbf{c} \widetilde{M}_{2 r}(y) \tag{5.19}
\end{equation*}
$$

We first consider the numerator in (5.3).
Lemma 5.4. We have
(5.20) $\int_{\Omega}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y+\int_{\Omega} h \Psi_{\varepsilon}^{2} d y=S_{3, \sigma}-\varepsilon \mathbf{m}\left(y_{0}\right) \mathbf{c}^{2} \int_{\partial Q_{r}} \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)+\mathcal{O}_{r}(\varepsilon)$, where $\nu$ is the unit outer normal of $Q_{r}$.

Proof. Recalling (5.19), direct computations give

$$
\begin{align*}
& \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y=\int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)}\left|\nabla\left(\widetilde{\eta}_{r} u_{\varepsilon}\right)\right|^{2} d y  \tag{5.21}\\
&+\varepsilon \mathbf{c}^{2} \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)}\left|\nabla \widetilde{M}_{2 r}\right|^{2} d y \\
&+2 \varepsilon^{1 / 2} \mathbf{c} \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)} \nabla\left(\widetilde{\eta}_{r} u_{\varepsilon}\right) \cdot \nabla \widetilde{M}_{2 r} d y \\
&= \varepsilon \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)}\left|\nabla\left(\widetilde{\eta}_{r} V_{\varepsilon}\right)\right|^{2} d y \\
&+\varepsilon \mathbf{c}^{2} \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)}\left|\nabla \widetilde{M}_{2 r}\right|^{2} d y \\
&+2 \varepsilon \mathbf{c} \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)} \nabla\left(\widetilde{\eta}_{r} V_{\varepsilon}\right) \cdot \nabla \widetilde{M}_{2 r} d y
\end{align*}
$$

By (5.4), $\eta_{r} v_{\varepsilon}=\eta_{r} \varepsilon^{-1} w(\cdot / \varepsilon)$ is cylindrically symmetric. Therefore by the change variable $y=F(x)$ and using Lemma 3.3, we get
(5.22) $\varepsilon \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)}\left|\nabla\left(\widetilde{\eta}_{r} V_{\varepsilon}\right)\right|^{2} d y=\varepsilon \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} v_{\varepsilon}\right)\right|_{g}^{2} \sqrt{g} d x$

$$
=\varepsilon \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} v_{\varepsilon}\right)\right|^{2} d x+O\left(\varepsilon r^{2} \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} v_{\varepsilon}\right)\right|^{2} d x\right) \text {. }
$$

By computing, we find that

$$
\begin{aligned}
& \varepsilon \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} v_{\varepsilon}\right)\right|^{2} d x \leq \varepsilon \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla v_{\varepsilon}\right|^{2} d x \\
&+\varepsilon \int_{Q_{2 r} \backslash Q_{r}} v_{\varepsilon}^{2}\left|\nabla \eta_{r}\right|^{2} d x+2 \varepsilon \int_{Q_{2 r} \backslash Q_{r}} v_{\varepsilon}\left|\nabla v_{\varepsilon}\right|\left|\nabla \eta_{r}\right| d x \\
& \leq \varepsilon \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla v_{\varepsilon}\right|^{2} d x+\frac{C}{r^{2}} \varepsilon \int_{Q_{2 r} \backslash Q_{r}} v_{\varepsilon}^{2} d x+\frac{C}{r} \varepsilon \int_{Q_{2 r} \backslash Q_{r}} v_{\varepsilon}\left|\nabla v_{\varepsilon}\right| d x \\
&= \int_{Q_{2 r / \varepsilon \backslash Q_{r / \varepsilon}}}|\nabla w|^{2} d x \\
&+C \frac{\varepsilon}{r^{2}} \int_{Q_{2 r / \varepsilon} \backslash Q_{r / \varepsilon}} w^{2} d x+\frac{C}{r} \varepsilon \int_{Q_{2 r / \varepsilon \backslash Q_{r / \varepsilon}}} w|\nabla w| d x .
\end{aligned}
$$

From this and (5.14) and (5.15), we get

$$
O\left(\varepsilon r^{2} \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} v_{\varepsilon}\right)\right|^{2} d x\right)=\mathcal{O}_{r}(\varepsilon)
$$

We replace this in (5.22) to have

$$
\begin{equation*}
\varepsilon \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)}\left|\nabla\left(\widetilde{\eta}_{r} V_{\varepsilon}\right)\right|^{2} d y=\varepsilon \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} v_{\varepsilon}\right)\right|^{2} d x+\mathcal{O}_{r}(\varepsilon) . \tag{5.23}
\end{equation*}
$$

We have the following estimates:

$$
\begin{align*}
0 \leq v_{\varepsilon} \leq C|x|^{-1} & \text { for } x \in \mathbb{R}^{3} \backslash\{0\} \\
\left|\nabla v_{\varepsilon}(x)\right| \leq C|x|^{-2} & \text { for }|x| \geq \varepsilon \tag{5.24}
\end{align*}
$$

which easily follow from (5.10) and Corollary 3.2. By these estimates, Lemma 2.2 and (5.7) together with the change of variable $y=F(x)$, we have

$$
\begin{aligned}
& \varepsilon \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)} \nabla\left(\widetilde{\eta}_{r} V_{\varepsilon}\right) \cdot \nabla \widetilde{M}_{2 r} d y \\
& =\varepsilon \int_{Q_{2 r} \backslash Q_{r}} \nabla\left(\eta_{r} v_{\varepsilon}\right) \cdot \nabla M d x+O\left(\varepsilon \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla v_{\varepsilon}\right| d x+\frac{\varepsilon}{r} \int_{Q_{2 r} \backslash Q_{r}} v_{\varepsilon} d x\right) \\
& \quad=\varepsilon \int_{Q_{2 r} \backslash Q_{r}} \nabla\left(\eta_{r} v_{\varepsilon}\right) \cdot \nabla M d x+\mathcal{O}_{r}(\varepsilon) .
\end{aligned}
$$

This with (5.23), (5.7) and (5.21) give

$$
\begin{aligned}
& \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y=\varepsilon \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} v_{\varepsilon}\right)\right|^{2} d x \\
& \quad+\varepsilon \mathbf{c}^{2} \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{2 r} M\right)\right|^{2} d x+2 \varepsilon \mathbf{c} \int_{Q_{2 r} \backslash Q_{r}} \nabla\left(\eta_{r} v_{\varepsilon}\right) \cdot \nabla M d x+\mathcal{O}_{r}(\varepsilon) .
\end{aligned}
$$

Thanks to Lemma 5.1 and (5.24), we can thus use the dominated convergence theorem to deduce that, as $\varepsilon \rightarrow 0$,

$$
\begin{equation*}
\int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} v_{\varepsilon}\right)\right|^{2} d x=\mathbf{c}^{2} \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} \mathcal{R}\right)\right|^{2} d x+o(1) . \tag{5.25}
\end{equation*}
$$

Similarly, we easily see that

$$
\int_{Q_{2 r} \backslash Q_{r}} \nabla\left(\eta_{r} v_{\varepsilon}\right) \cdot \nabla M d x=\mathbf{c} \int_{Q_{2 r} \backslash Q_{r}} \nabla\left(\eta_{r} \mathcal{R}\right) \cdot \nabla M d x+o(1)
$$

as $\varepsilon \rightarrow 0$. This and (5.25), then give

$$
\begin{align*}
& \int_{F\left(Q_{2 r}\right) \backslash F\left(Q_{r}\right)}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y=\varepsilon \mathbf{c}^{2} \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} \mathcal{R}\right)\right|^{2} d x  \tag{5.26}\\
& +\varepsilon \mathbf{c}^{2} \int_{Q_{2 r} \backslash Q_{r}}|\nabla M|^{2} d x+2 \varepsilon \mathbf{c}^{2} \int_{Q_{2 r} \backslash Q_{r}} \nabla\left(\eta_{r} \mathcal{R}\right) \cdot \nabla M d x+\mathcal{O}_{r}(\varepsilon) \\
& \\
& =\varepsilon \mathbf{c}^{2} \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} \mathcal{R}+M\right)\right|^{2} d x+\mathcal{O}_{r}(\varepsilon) .
\end{align*}
$$

Since the support of $\Psi_{\varepsilon}$ is contained in $Q_{4 r}$ while the one of $\eta_{r}$ is in $Q_{2 r}$, it is easy to deduce from (5.7) that

$$
\int_{\Omega \backslash F\left(Q_{2 r}\right)}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y=\varepsilon \mathbf{c}^{2} \int_{F\left(Q_{4 r}\right) \backslash F\left(Q_{2 r}\right)}\left|\nabla \widetilde{M}_{2 r}\right|^{2} d y=\mathcal{O}_{r}(\varepsilon)
$$

and from Lemma 5.2, that

$$
\int_{\Omega \backslash F\left(Q_{r}\right)} h\left|\Psi_{\varepsilon}\right|^{2} d y=\varepsilon \mathbf{c}^{2} \int_{F\left(Q_{4 r}\right) \backslash F\left(Q_{r}\right)} h\left|\eta_{r} V_{\varepsilon}+\widetilde{M}_{2 r}\right|^{2} d y=\mathcal{O}_{r}(\varepsilon)
$$

Therefore, by (5.26), we conclude that

$$
\begin{aligned}
& \int_{\Omega \backslash F\left(Q_{r}\right)}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y+\int_{\Omega \backslash F\left(Q_{r}\right)} h\left|\Psi_{\varepsilon}\right|^{2} d y \\
= & \varepsilon \mathbf{c}^{2} \int_{Q_{2 r} \backslash Q_{r}}\left|\nabla\left(\eta_{r} \mathcal{R}+M\right)\right|^{2} d x+\varepsilon \mathbf{c}^{2} \int_{Q_{2 r} \backslash Q_{r}} h\left(\cdot+y_{0}\right)\left|\eta_{r} \mathcal{R}+M\right|^{2} d x+\mathcal{O}_{r}(\varepsilon) .
\end{aligned}
$$

Recall that $G\left(x+y_{0}, y_{0}\right)=\eta_{r}(x) \mathcal{R}(x)+M(x)$ for every $x \in Q_{2 r}$ and that by (5.2),

$$
-\Delta_{x} G\left(x+y_{0}, y_{0}\right)+h\left(x+y_{0}\right) G\left(x+y_{0}, y_{0}\right)=0
$$

for every $x \in Q_{2 r} \backslash Q_{r}$. Therefore, by integration by parts, we find that

$$
\begin{aligned}
\int_{\Omega \backslash F\left(Q_{r}\right)}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y+ & \int_{\Omega \backslash F\left(Q_{r}\right)} h\left|\Psi_{\varepsilon}\right|^{2} d y \\
& =\mathbf{c}^{2} \int_{\partial\left(Q_{2 r} \backslash Q_{r}\right)}\left(\eta_{r} \mathcal{R}+M\right) \frac{\partial\left(\eta_{r} \mathcal{R}+M\right)}{\partial \bar{\nu}} \sigma(x)+\mathcal{O}_{r}(\varepsilon),
\end{aligned}
$$

where $\bar{\nu}$ is the exterior normal vectorfield to $Q_{2 r} \backslash Q_{r}$. Thanks to (5.7), we finally get

$$
\begin{align*}
\int_{\Omega \backslash F\left(Q_{r}\right)} \mid & \left.\nabla \Psi_{\varepsilon}\right|^{2} d y+\int_{\Omega \backslash F\left(Q_{r}\right)} h\left|\Psi_{\varepsilon}\right|^{2} d y  \tag{5.27}\\
& =-\varepsilon \mathbf{c}^{2} \int_{\partial Q_{r}} \mathcal{R} \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)-\varepsilon \mathbf{c}^{2} \int_{\partial Q_{r}} M \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)+\mathcal{O}_{r}(\varepsilon),
\end{align*}
$$

where $\nu$ is the exterior normal vectorfield to $Q_{r}$.

Next we make the expansion of $\int_{F\left(Q_{r}\right)}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y$ for $r$ and $\varepsilon$ small. First, we observe that, by Lemma 5.2 and (5.7), we have

$$
\begin{aligned}
\int_{F\left(Q_{r}\right)}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y= & \int_{F\left(Q_{r}\right)}\left|\nabla u_{\varepsilon}\right|^{2} d y \\
& +\varepsilon \mathbf{c}^{2} \int_{F\left(Q_{r}\right)}|\nabla M|^{2} d y+2 \varepsilon^{1 / 2} \mathbf{c} \int_{F\left(Q_{r}\right)} \nabla u_{\varepsilon} \cdot \nabla \widetilde{M}_{2 r} d y \\
= & \int_{Q_{r / \varepsilon}}|\nabla w|^{2} d x \\
& +O\left(\varepsilon^{2} \int_{Q_{r / \varepsilon}}|x|^{2}|\nabla w|^{2} d x+\varepsilon^{2} \int_{Q_{r / \varepsilon}}|\nabla w| d x\right)+\mathcal{O}_{r}(\varepsilon) \\
= & \int_{Q_{r / \varepsilon}}|\nabla w|^{2} d x+\mathcal{O}_{r}(\varepsilon)
\end{aligned}
$$

By integration by parts and using (5.17), we deduce that

$$
\begin{align*}
\int_{F\left(Q_{r}\right)}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y & =S_{3, \sigma} \int_{Q_{r / \varepsilon}}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x+\int_{\partial Q_{r / \varepsilon}} w \frac{\partial w}{\partial \nu} d \sigma(x)+\mathcal{O}_{r}(\varepsilon)  \tag{5.28}\\
& =S_{3, \sigma}+\varepsilon \int_{\partial Q_{r}} v_{\varepsilon} \frac{\partial v_{\varepsilon}}{\partial \nu} d \sigma(x)+\mathcal{O}_{r}(\varepsilon)
\end{align*}
$$

Now (5.24), (5.11) and the dominated convergence theorem yield, for fixed $r>0$ and $\varepsilon \rightarrow 0$

$$
\begin{align*}
\int_{\partial Q_{r}} v_{\varepsilon} \frac{\partial v_{\varepsilon}}{\partial \nu} d \sigma(x)= & \int_{\partial B_{\mathbb{R}^{2}}^{2}(0, r)} \int_{-r}^{r} v_{\varepsilon}(t, z) \nabla v_{\varepsilon}(t, z) \cdot \frac{z}{|z|} d \sigma(z) d t  \tag{5.29}\\
& +2 \int_{B_{\mathbb{R}^{2}}^{2}} v_{\varepsilon}(r, z) \partial_{t} v_{\varepsilon}(r, z) d z \\
= & \mathbf{c}^{2} \int_{\partial B_{\mathbb{R}^{2}}^{2}(0, r)} \int_{-r}^{r} \mathcal{R}(t, z) \nabla \mathcal{R}(t, z) \cdot \frac{z}{|z|} d \sigma(z) d t \\
& +2 \mathbf{c}^{2} \int_{B_{\mathbb{R}^{2}}^{2}} \mathcal{R}(r, z) \partial_{t} \mathcal{R}(r, z) d z+o(1) \\
= & \mathbf{c}^{2} \int_{\partial Q_{r}} \mathcal{R} \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)+o(1)
\end{align*}
$$

Moreover, (5.16) implies that

$$
\int_{F\left(Q_{r}\right)} h \Psi_{\varepsilon}^{2} d y=\mathcal{O}_{r}(\varepsilon) .
$$

From this together with (5.28) and (5.29), we obtain

$$
\int_{F\left(Q_{r}\right)}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y+\int_{F\left(Q_{r}\right)} h \Psi_{\varepsilon}^{2} d y=S_{3, \sigma}+\mathbf{c}^{2} \varepsilon \int_{\partial Q_{r}} \mathcal{R} \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)+\mathcal{O}_{r}(\varepsilon)
$$

Combining this with (5.27), we then have
(5.30) $\int_{\Omega}\left|\nabla \Psi_{\varepsilon}\right|^{2} d y+\int_{\Omega} h \Psi_{\varepsilon}^{2} d y=S_{3, \sigma}-\varepsilon \mathbf{c}^{2} \int_{\partial Q_{r}} M \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)+\mathcal{O}_{r}(\varepsilon)+o(\varepsilon)$.

Since (recalling (5.8)) M(y) $=M(0)+O(r)=\mathbf{m}\left(y_{0}\right)+O(r)$ in $Q_{2 r}$, we get equation (5.20).

The following result together with the previous lemma provides the proof of Proposition 5.3.

Lemma 5.5. We have

$$
\left(\int_{\Omega} \rho_{\Gamma}^{-\sigma}\left|\Psi_{\varepsilon}\right|^{2_{\sigma}^{*}} d y\right)^{2 / 2_{\sigma}^{*}}=1-\frac{2}{S_{3, \sigma}} \varepsilon \mathbf{m}\left(y_{0}\right) \mathbf{c}^{2} \int_{\partial Q_{r}} \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)+\mathcal{O}_{r}(\varepsilon) .
$$

Proof. Since $2_{\sigma}^{*}>2$, there exists a positive constant $C(\sigma)$ such that

$$
\left.\left||a+b|^{2_{\sigma}^{*}}-|a|^{2_{\sigma}^{*}}-2_{\sigma}^{*} a b\right| a\right|^{2_{\sigma}^{*}-2} \mid \leq C(\sigma)\left(|a|^{2_{\sigma}^{*}-2} b^{2}+|b|^{2_{\sigma}^{*}}\right) \quad \text { for all } a, b \in \mathbb{R} .
$$

As a consequence, we obtain

$$
\begin{align*}
& \int_{\Omega} \rho_{\Gamma}^{-\sigma}\left|\Psi_{\varepsilon}\right|^{2_{\sigma}^{*}} d y=\int_{F\left(Q_{r}\right)} \rho_{\Gamma}^{-\sigma}\left|u_{\varepsilon}+\varepsilon^{1 / 2} \widetilde{M}_{2 r}\right|^{2_{\sigma}^{*}} d y  \tag{5.31}\\
&+\int_{F\left(Q_{4 r}\right) \backslash F\left(Q_{r}\right)} \rho_{\Gamma}^{-\sigma}\left|W_{\varepsilon}+\varepsilon^{1 / 2} \widetilde{M}_{2 r}\right|^{2_{\sigma}^{*}} d y \\
&= \int_{F\left(Q_{r}\right)} \rho_{\Gamma}^{-\sigma}\left|u_{\varepsilon}\right|^{2_{\sigma}^{*}} d y+2_{\sigma}^{*} \mathbf{c} \varepsilon^{1 / 2} \int_{F\left(Q_{r}\right)} \rho_{\Gamma}^{-\sigma}\left|u_{\varepsilon}\right|^{2_{\sigma}^{*}-1} \widetilde{M}_{2 r} d y \\
&+O\left(\int_{F\left(Q_{4 r}\right)} \rho_{\Gamma}^{-\sigma}\left|\eta_{r} u_{\varepsilon}\right|^{2_{\sigma}^{*}-2}\left(\varepsilon^{1 / 2} \widetilde{M}_{2 r}\right)^{2} d y\right. \\
&\left.+\int_{F\left(Q_{4 r}\right)} \rho_{\Gamma}^{-\sigma}\left|\varepsilon^{1 / 2} \widetilde{M}_{2 r}\right|^{2_{\sigma}^{*}} d y\right) \\
&+O\left(\int_{F\left(Q_{4 r}\right) \backslash F\left(Q_{r}\right)} \rho_{\Gamma}^{-\sigma}\left|u_{\varepsilon}\right|^{2_{\sigma}^{*}} d y\right. \\
&\left.+2_{\sigma}^{*} \mathbf{c} \varepsilon^{1 / 2} \int_{F\left(Q_{4 r}\right) \backslash F\left(Q_{r}\right)} \rho_{\Gamma}^{-\sigma}\left|u_{\varepsilon}\right|^{2_{\sigma}^{*}-1} \widetilde{M}_{2 r} d y\right)
\end{align*}
$$

By Hölder's inequality and (2.9), we have

$$
\begin{align*}
& \int_{F\left(Q_{4 r}\right)} \rho_{\Gamma}^{-\sigma}\left|\eta u_{\varepsilon}\right|^{2_{\sigma}^{*}-2}\left(\varepsilon^{1 / 2} \widetilde{\beta}_{r}\right)^{2} d y  \tag{5.32}\\
& \leq \varepsilon\left\|u_{\varepsilon}\right\|_{L^{2}\left(F\left(Q_{4 r}\right) ; \rho^{-\sigma}\right)}^{2^{*}-2}\left\|\widetilde{M}_{2 r}\right\|_{\left.L^{2^{2}(F}\left(Q_{4 r}\right) ; \rho_{\Gamma}^{-\sigma}\right)}^{2} \\
& =\varepsilon\|w\|_{L^{2_{\sigma}^{2}( }\left(Q_{4 r} ;|z|-\sigma\right.}^{2^{*}-2} \sqrt{|g|)}\left\|\widetilde{M}_{2 r}\right\|_{L^{2_{\sigma}^{*}}\left(F\left(Q_{4 r}\right) ; \rho_{\Gamma}^{-\sigma}\right)}^{2} \\
& \leq \varepsilon(1+C r)\left\|\widetilde{M}_{2 r}\right\|_{L^{2 *}\left(F\left(Q_{4 r}\right) ; \rho_{\Gamma}^{-\sigma}\right)}^{2}=\mathcal{O}_{r}(\varepsilon),
\end{align*}
$$

recalling that $\|w\|_{L^{L_{\sigma}^{*}}\left(\mathbb{R}^{3} ;|z|^{-\sigma}\right)}=1$. Furthermore, since $2_{\sigma}^{*}>2$, by (5.7), we easily get

$$
\begin{equation*}
\int_{F\left(Q_{4 r}\right)} \rho_{\Gamma}^{-\sigma}\left|\varepsilon^{1 / 2} \widetilde{M}_{2 r}\right|^{2_{\sigma}^{*}} d y=o(\varepsilon) . \tag{5.33}
\end{equation*}
$$

Moreover, by change of variables and (5.17), we also have

$$
\begin{aligned}
& \int_{F\left(Q_{4 r}\right) \backslash F\left(Q_{r}\right)} \rho_{\Gamma}^{-\sigma}\left|u_{\varepsilon}\right|^{2_{\sigma}^{*}} d y+2_{\sigma}^{*} \mathbf{c} \varepsilon^{1 / 2} \int_{F\left(Q_{4 r}\right) \backslash F\left(Q_{r}\right)} \rho_{\Gamma}^{-\sigma}\left|u_{\varepsilon}\right|^{2_{\sigma}^{*}-1} \widetilde{M}_{2 r} d y \\
& \quad \leq C \int_{Q_{4 r / \varepsilon} \backslash Q_{r / \varepsilon}}|z|^{-\sigma}|w|^{2_{\sigma}^{*}} d x+C \varepsilon \int_{Q_{4 r / \varepsilon \backslash Q_{r / \varepsilon}}}|z|^{-\sigma}|w|^{2_{\sigma}^{*}-1} d x=o(\varepsilon) .
\end{aligned}
$$

By this, (5.31), (5.33) and (5.32), it results

$$
\begin{aligned}
& \int_{\Omega} \rho_{\Gamma}^{-\sigma}\left|\Psi_{\varepsilon}\right|^{2_{\sigma}^{*}} d y=\int_{F\left(Q_{r}\right)} \rho_{\Gamma}^{-\sigma}\left|u_{\varepsilon}\right|^{2_{\sigma}^{*}} d y \\
&+2_{\sigma}^{*} \mathbf{c} \varepsilon^{1 / 2} \int_{F\left(Q_{r}\right)} \rho_{\Gamma}^{-\sigma}\left|u_{\varepsilon}\right|^{2_{\sigma}^{*}-1} \widetilde{M}_{2 r} d y+\mathcal{O}_{r}(\varepsilon) .
\end{aligned}
$$

We define $B_{\varepsilon}(x):=M(\varepsilon x) \sqrt{\left|g_{\varepsilon}\right|}(x)=M(\varepsilon x) \sqrt{|g|}(\varepsilon x)$. Then by the change of variable $y=F(x) / \varepsilon$ in the above identity and recalling (2.9), by oddness, we have

$$
\begin{aligned}
\int_{\Omega} \rho_{\Gamma}^{-\sigma} & \left|\Psi_{\varepsilon}\right|^{2_{\sigma}^{*}} d y \\
= & \int_{Q_{r / \varepsilon}}|z|^{-\sigma} w^{2_{\sigma}^{*}} \sqrt{\left|g_{\varepsilon}\right|} d x+2_{\sigma}^{*} \varepsilon \mathbf{c} \int_{Q_{r / \varepsilon}}|z|^{-\sigma}|w|^{2_{\sigma}^{*}-1} B_{\varepsilon} d x+\mathcal{O}_{r}(\varepsilon) \\
= & \int_{Q_{r / \varepsilon}}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x+2_{\sigma}^{*} \varepsilon \mathbf{c} \int_{Q_{r / \varepsilon}}|z|^{-\sigma}|w|^{2_{\sigma}^{*}-1} B_{\varepsilon} d x+\mathcal{O}_{r}(\varepsilon) \\
& +O\left(\varepsilon^{2} \int_{Q_{r / \varepsilon}}|z|^{-\sigma}|x|^{2} w^{2_{\sigma}^{*}} d x\right) \\
= & 1+2_{\sigma}^{*} \varepsilon \mathbf{c} \int_{Q_{r / \varepsilon}}|z|^{-\sigma}|w|^{2_{\sigma}^{*}-1} B_{\varepsilon} d x \\
& +O\left(\int_{\mathbb{R}^{3} \backslash Q_{r / \varepsilon}}|z|^{-\sigma} w^{2_{\sigma}^{*}} d x+\varepsilon^{2} \int_{Q_{r / \varepsilon}}|z|^{-\sigma}|x|^{2} w^{2_{\sigma}^{*}} d x\right)+\mathcal{O}_{r}(\varepsilon)
\end{aligned}
$$

Therefore by (5.17) we then have

$$
\begin{equation*}
\left(\int_{\Omega} \rho_{\Gamma}^{-\sigma}\left|\Psi_{\varepsilon}\right|^{2_{\sigma}^{*}} d y\right)^{2 / 2_{\sigma}^{*}}=1+2 \varepsilon \mathbf{c} \int_{Q_{r / \varepsilon}}|z|^{-\sigma}|w|^{2_{\sigma}^{*}-1} B_{\varepsilon}(x) d x+\mathcal{O}_{r}(\varepsilon) \tag{5.34}
\end{equation*}
$$

Multiply (5.9) by $B_{\varepsilon} \in \mathcal{C}^{1}\left(\overline{Q_{r}}\right)$ and integrate by parts to get

$$
\begin{aligned}
S_{3, \sigma} \int_{Q_{r / \varepsilon}}|z|^{-\sigma}|w|^{2_{\sigma}^{*}-1} B_{\varepsilon} d x & =\int_{Q_{r / \varepsilon}} \nabla w \cdot \nabla B_{\varepsilon} d x-\int_{\partial Q_{r / \varepsilon}} B_{\varepsilon} \frac{\partial w}{\partial \nu} d \sigma(x) \\
& =\int_{Q_{r / \varepsilon}} \nabla w \cdot \nabla B_{\varepsilon} d x-\int_{\partial Q_{r}} B_{1} \frac{\partial v_{\varepsilon}}{\partial \nu} d \sigma(x) .
\end{aligned}
$$

Since $\left|\nabla B_{\varepsilon}\right| \leq C \varepsilon$, by Lemma 5.1 and (5.7), we then have

$$
\varepsilon \int_{Q_{r / \varepsilon}} \nabla w \cdot \nabla B_{\varepsilon} d x=O\left(\varepsilon^{2} \int_{Q_{r / \varepsilon}}|\nabla w| d x\right)=\mathcal{O}_{r}(\varepsilon)
$$

Consequently, on the one hand,

$$
S_{3, \sigma} \varepsilon \int_{Q_{r / \varepsilon}}|z|^{-\sigma}|w|^{2_{\sigma}^{*}-1} B_{\varepsilon} d x=-\varepsilon \int_{\partial Q_{r}} B_{1} \frac{\partial v_{\varepsilon}}{\partial \nu} d \sigma(x)+\mathcal{O}_{r}(\varepsilon) .
$$

On the other hand by Lemma 5.1, (5.7) and the dominated convergence theorem, we get

$$
\begin{aligned}
\int_{\partial Q_{r}} B_{1} \frac{\partial v_{\varepsilon}}{\partial \nu} d \sigma(x) & =\mathbf{c} \int_{\partial Q_{r}} B_{1} \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)+o(1) \\
& =\mathbf{c} M(0) \int_{\partial Q_{r}} \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)+O(r)+o(1)
\end{aligned}
$$

so that

$$
\varepsilon \mathbf{c} \int_{Q_{r / \varepsilon}}|z|^{-\sigma}|w|^{2_{\sigma}^{*}-1} B_{\varepsilon} d x=-\varepsilon \mathbf{c}^{2} \frac{1}{S_{3, \sigma}} M(0) \int_{\partial Q_{r}} \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)+\mathcal{O}_{r}(\varepsilon) .
$$

It then follows from (5.34) that

$$
\left(\int_{\Omega} \rho_{\Gamma}^{-\sigma}\left|\Psi_{\varepsilon}\right|^{2_{\sigma}^{*}} d y\right)^{2 / 2_{\sigma}^{*}}=1-\frac{2}{S_{3, \sigma}} \varepsilon \mathbf{c}^{2} M(0) \int_{\partial Q_{r}} \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)+\mathcal{O}_{r}(\varepsilon)
$$

Since $M(0)=\mathbf{m}\left(y_{0}\right)$, see (5.8), the proof of the lemma is thus finished.
Proof of Proposition 5.3 (completed). By Lemmas 5.4 and 5.5, we have

$$
\begin{equation*}
J\left(\Psi_{\varepsilon}\right)=S_{3, \sigma}-\varepsilon \mathbf{c}^{2} \mathbf{m}\left(y_{0}\right) \int_{\partial Q_{r}} \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x)+\mathcal{O}_{r}(\varepsilon) . \tag{5.35}
\end{equation*}
$$

Finally, recalling that $\mathcal{R}(x)=1 /|x|$, we can compute

$$
\begin{aligned}
\int_{\partial Q_{r}} \frac{\partial \mathcal{R}}{\partial \nu} d \sigma(x) & =-\int_{\partial Q_{r}} \frac{x \cdot \nu(x)}{|x|^{3}} d \sigma(x) \\
& =\int_{B_{\mathbb{R}^{2}}(0, r)} \frac{-2 r}{r^{2}+|z|^{2}} d z-2 \pi \int_{-r}^{r} \frac{r^{3}}{r^{2}+t^{2}} d t=-\pi^{2}\left(1+r^{2}\right)
\end{aligned}
$$

From this and (5.35), we then have

$$
J\left(\Psi_{\varepsilon}\right)=S_{3, \sigma}-\varepsilon \pi^{2} \mathbf{c}^{2} \mathbf{m}\left(y_{0}\right)+\mathcal{O}_{r}(\varepsilon) .
$$

Proof of Theorem 1.3 (completed). By Lemma 5.3, if $\mathbf{m}\left(y_{0}\right)>0$ for some $y_{0} \in \Gamma$, then $\mu_{h}(\Omega, \Gamma)<S_{3, \sigma}$. This with (4.10) (which holds for $N \geq 3$ ) imply that every minimizing sequence for $\mu_{h}(\Omega, \Gamma)$ converges, up to a subsequence, to a minimizer which is positive.

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