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# SET-VALUED PERTURBATION FOR TIME DEPENDENT SUBDIFFERENTIAL OPERATOR 

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#### Abstract

In a separable Hilbert space, we consider an evolution inclusion involving time-dependent subdifferential of a proper convex lower semicontinuous function with a set-valued perturbation depending on both time and state variable. We prove, under a compactness condition on the perturbation, that there exists at least one absolutely continuous solution.


## 1. Introduction

The present work deals with perturbations of evolution equations governed by time dependent subdifferential operator of the form
$\left(\mathcal{P}_{F(\cdot, \cdot)}\right) \quad\left\{\begin{array}{l}-\dot{x}(t) \in \partial \varphi(t, x(t))+F(t, x(t)) \quad \text { for a.e. } t \in I:=\left[T_{0}, T\right], \\ x\left(T_{0}\right)=x_{0} \in \operatorname{dom} \varphi\left(T_{0}, \cdot\right),\end{array}\right.$
where for each $t \in I$, the (set-valued) operator $\partial \varphi(t, \cdot)$ is the subdifferential of a time-dependent proper lower semicontinuous (lsc) convex function $\varphi(t, \cdot)$ of a separable Hilbert space $H$ into $[0,+\infty]$ and $\operatorname{dom} \varphi(t, \cdot)$ denotes the effective domain of the function $\varphi(t, \cdot)$. The set-valued mapping $F: I \times H \rightrightarrows H$ takes nonempty convex compact values. We are interested in the existence of a solution when the perturbation $F(\cdot, \cdot)$ satisfies for some compact subset $K$ of the closed

[^0]unit ball $\mathbb{B}$ of $H$ and some non-negative function $\beta(\cdot) \in L_{\mathbb{R}}^{2}(I)$, the linear growth condition
$$
F(t, x) \subset \beta(t)(1+\|x\|) K, \quad \text { for all } t \in I \text { and } x \in H
$$

The existence and uniqueness results for the unperturbed problem

$$
\left\{\begin{array}{l}
-\dot{x}(t) \in \partial \varphi(t, x(t)) \quad \text { for a.e. } t \in I  \tag{P}\\
x\left(T_{0}\right)=x_{0} \in \operatorname{dom} \varphi\left(T_{0}, \cdot\right)
\end{array}\right.
$$

were established by Peralba [24], [25] with an assumption expressed in terms of the conjugate function $\varphi^{*}(t, \cdot)$ of the convex function $\varphi(t, \cdot)$, that is, there exists a Lipschitz function $k: H \rightarrow \mathbb{R}_{+}$and an absolutely continuous function $a: I \rightarrow \mathbb{R}$ with $\dot{a} \in L_{\mathbb{R}}^{2}(I)$ such that, for all $x \in H$ and $s, t \in I$,

$$
\varphi^{*}(t, x) \leq \varphi^{*}(s, x)+k(x)|a(t)-a(s)|
$$

Other results have been obtained using hypothesis required on $\varphi$ or the Moreau envelope $\varphi_{\lambda}$, see for instance [3], [21], [22], [28], [29], [31]. There are also several works dealing with set-valued or single-valued perturbations of $(\mathcal{P})$ under, in general, some compactness assumptions concerning the sublevel sets of $\varphi(t, \cdot)$ (see, e.g. [2], [6], [9], [15], [23], [27], [30]). In the line of our previous paper with single-valued Lipschitz perturbation [26], conditions on the Moreau envelope $\varphi_{\lambda}(t, \cdot)$ or the Yosida approximation of $\partial \varphi(t, \cdot)$ which cannot be translated to the new operator generated by the perturbed problem, along with compactness assumptions on the sublevel sets of $\varphi(t, \cdot)$ are not appropriate. At the opposite, as we will see below, Peralba's assumption above on the function $\varphi^{*}$ is really suited for our study in the sense that it allows us, in the setting of Hilbert space, through some ideas of Edmond and Thibault [18], [20] (see also [11]) to prove existence of absolutely continuous solution for $\left(\mathcal{P}_{F(\cdot, \cdot)}\right)$ and to avoid any compactness assumption.

For the autonomous case, that is, when $\varphi: H \rightarrow \mathbb{R} \cup\{\infty\}$ is a proper lsc convex function independent of time, we cite Attouch and Damlamian [3], Cellina and Staicu [15] and Castaing and Marcellin [11]; all these papers consider some compactness assumptions concerning the sublevel sets of $\varphi(t, \cdot)$. This hypothesis is also used in the nonautonomous case in Benabdellah and Faik [5] (see also [8]), Benabdellah, Castaing and Salvatori [6], Otani [23] and Tolstonogov [27].

In the particular case of the so-called sweeping process, i.e., for $\varphi(t, \cdot)$ taken as the indicator function of a closed moving set $C(t)$, the fixed point technique is quite efficient, under convexity assumptions of the values of both $C(\cdot)$ and $F(\cdot, \cdot)$. This is true under the additional usual assumption on $F$ requiring separate measurability with respect to $t$ and upper semicontinuity (closed graph) with respect to $x$. Results related to similar problems with nonconvex closed moving sets $C(t)$ in the finite dimensional setting for $\left(\mathcal{P}_{F(\cdot, \cdot)}\right)$, can be found on
one hand in Castaing and Monteiro Marques [12] when $C(t)$ is the complement of an open set of $H$ and on the other hand in Castaing, Salvadori and Thibault [13] when the closed set $C(t)$ is $r$-prox-regular. In the infinite dimensional setting, recent existence theorems have been established in [19], [20], [7] and [10] when in addition to the $r$-prox-regularity of the moving set $C(t)$, a linear growth compactness condition is assumed for the set-valued mapping $F(\cdot, \cdot)$.

The paper is organized as follows. After recalling some concepts in the second section, and useful results of [24] and [25] in the third section concerning the nonautonomous case $(\mathcal{P})$, in Section 4, we establish the existence theorem for the considered problem $\left(\mathcal{P}_{F(\cdot, \cdot)}\right)$ for a globally upper hemicontinuous perturbation. Finally, we extend this result in section 5 , to the case when the perturbation $F$ is just measurable in $t$ and upper semicontinuous in $x$.

## 2. Notation and preliminaries

Throughout the paper $I:=\left[T_{0}, T\right]\left(0 \leq T_{0}<T<+\infty\right)$ is an interval of $\mathbb{R}$ and $H$ is a real separable Hilbert space whose inner product is denoted by $\langle\cdot, \cdot\rangle$ and the associated norm by $\|\cdot\|$.

We use the following definitions and notations. We denote by $\mathbb{B}$ the closed unit ball of $H$. On the space $\mathcal{C}_{H}(I)$ of continuous maps $x: I \rightarrow H$ we consider the norm of uniform convergence on $I$. By $L_{H}^{p}(I)$ for $p \in[1,+\infty[$ (resp. $p=+\infty)$, we denote the space of measurable maps $x: I \rightarrow H$ such that $\int_{I}\|x(t)\|^{p} d t<+\infty$ (resp. which are essentially bounded) endowed with the usual norm $\|x\|_{L_{H}^{p}(I)}=\left(\int_{I}\|x(t)\|^{p} d t\right)^{1 / p}, 1 \leq p<+\infty$ (resp. endowed with the usual essential supremum norm $\|\cdot\|)$. We recall that the topological dual of $L_{H}^{1}(I)$ is $L_{H}^{\infty}(I)$.

Let $\varphi$ be a lower semicontinuous (lsc) convex function from $H$ into $\mathbb{R} \cup\{+\infty\}$ which is proper in the sense that its effective domain $\operatorname{dom} \varphi$ defined by

$$
\operatorname{dom} \varphi:=\{x \in H: \varphi(x)<+\infty\}
$$

is nonempty and, as usual, its Fenchel conjugate is defined by

$$
\varphi^{*}(v):=\sup _{x \in H}[\langle v, x\rangle-\varphi(x)] .
$$

It is often useful to regularize $\varphi$ via its Moreau envelope

$$
\varphi_{\lambda}(x):=\inf _{y \in H}\left[\varphi(y)+\frac{1}{2 \lambda}\|x-y\|^{2}\right]
$$

for $\lambda>0$. The family $\left(\varphi_{\lambda}\right)_{\lambda}$ increases when $\lambda \downarrow 0$ to the proper lsc convex function $\varphi$ and hence it epi-converges to $\varphi$ (see e.g. [1]). This entails in particular for any family $\left(x_{\lambda}\right)_{\lambda}$ of $H$ converging to $x$ that

$$
\begin{equation*}
\varphi(x) \leq \liminf _{\lambda \downarrow 0} \varphi_{\lambda}\left(x_{\lambda}\right) \tag{2.1}
\end{equation*}
$$

The Moreau envelope function $\varphi_{\lambda}$ is also known to have a Lipschitzian continuous derivative $\nabla \varphi_{\lambda}$.

The subdifferential $\partial \varphi(x)$ of $\varphi$ at $x \in \operatorname{dom} \varphi$ is

$$
\partial \varphi(x)=\{v \in H: \varphi(y) \geq\langle v, y-x\rangle+\varphi(x) \text { for all } y \in \operatorname{dom} \varphi\}
$$

and its effective domain is $\operatorname{Dom} \partial \varphi=\{x \in H: \partial \varphi(x) \neq \emptyset\}$. It is well known that if $\varphi$ is a proper lsc convex function, then its subdifferential operator $\partial \varphi$ is a maximal monotone operator. Any maximal monotone operator $A$ satisfies the closure property, that is, if $x=\lim _{n \rightarrow \infty} x_{n}$ strongly in $H$ and $y=\lim _{n \rightarrow \infty} y_{n}$ weakly in $H$, where $x_{n} \in \operatorname{Dom} A$ and $y_{n} \in A\left(x_{n}\right)$, then, $x \in \operatorname{Dom} A$ and $y \in A(x)$. For any subset $S$ of $H, \sigma(S, \cdot)$ represents the support function of $S$, that is, for all $y \in H$,

$$
\sigma(S, y):=\sup _{x \in S}\langle y, x\rangle
$$

A set-valued mapping $F: E \rightrightarrows H$ from a Hausdorff topological space $E$ into $H$ is said to be upper semicontinuous (usc) if, for any open subset $V \subset H$, the set $\{x \in E: F(x) \subset V\}$ is open in $E$. The set-valued mapping $F$ is said to be scalarly upper semicontinuous or upper hemicontinuous if, for any $y \in H$, the real-valued function $x \mapsto \sigma(F(x), y)$ is upper semicontinuous. We refer to [4] and [14] for details concerning convex analysis and measurable set-valued mappings. We will close this section of preliminaries by recalling the following straightforward consequence of Gronwall's lemma.

LEmma $2.1([20])$. Let $\left(x_{n}(\cdot)\right)$ be a sequence of absolutely continuous maps from $I$ to $H$. Assume that $\lim _{n} x_{n}\left(T_{0}\right)=0$ and, for any $n$,

$$
\frac{d}{d t}\left(\left\|x_{n}(t)\right\|^{2}\right) \leq \beta_{n}(t)\left\|x_{n}(t)\right\|^{2}+\alpha_{n}(t) \quad \text { for a.e. } t \in I
$$

where $\alpha_{n}(\cdot)$ and $\beta_{n}(\cdot)$ are non negative functions in $L_{\mathbb{R}}^{1}(I)$. Assume moreover that the sequence $\left(\beta_{n}(\cdot)\right)$ is bounded in $L_{\mathbb{R}}^{1}(I)$ and $\lim _{n} \int_{T_{0}}^{T} \alpha_{n}(t) d t=0$. Then,

$$
\lim _{n}\left\|x_{n}(\cdot)\right\|_{\infty}=0
$$

## 3. Single valued time-dependent perturbation

This section is devoted to the study of the perturbed problem

$$
\left\{\begin{array}{l}
-\dot{x}(t) \in \partial \varphi(t, x(t))+h(t)  \tag{h}\\
x\left(T_{0}\right)=x_{0} \in \operatorname{dom} \varphi\left(T_{0}, \cdot\right)
\end{array}\right.
$$

whose perturbation is a single-valued time-dependent map. Let us first recall a result due to Peralba [24], [25].

Theorem 3.1. Let $\varphi: I \times H \rightarrow \mathbb{R}_{+} \cup\{+\infty\}$ be such that:
$\left(\mathrm{H}_{1}\right)$ for each $t \in I$, the function $x \mapsto \varphi(t, x)$ is proper, lower semicontinuous, and convex;
$\left(\mathrm{H}_{2}\right)$ there exist a $\rho$-Lipschitzean function $k: H \rightarrow \mathbb{R}_{+}$and an absolutely continuous function $a: I \rightarrow \mathbb{R}$, with a non-negative derivative $\dot{a} \in L_{\mathbb{R}}^{2}(I)$, such that

$$
\begin{equation*}
\varphi^{*}(t, x) \leq \varphi^{*}(s, x)+k(x)|a(t)-a(s)| \tag{3.1}
\end{equation*}
$$

for every $(t, s, x) \in I \times I \times H$.
Let also $x_{0} \in \operatorname{dom} \varphi\left(T_{0}, \cdot\right)$ be fixed. Then, the differential inclusion

$$
\left\{\begin{array}{l}
-\dot{x}(t) \in \partial \varphi(t, x(t)) \quad \text { for a.e. } t \in I  \tag{P}\\
x\left(T_{0}\right)=x_{0} \in \operatorname{dom} \varphi\left(T_{0}, \cdot\right)
\end{array}\right.
$$

has a unique absolutely continuous solution $x(\cdot)$ on $I$. Moreover, for all $t \in I$, $x(t) \in \operatorname{dom} \varphi(t, \cdot)$ and the function $t \mapsto \varphi(t, x(t))$ is absolutely continuous on $I$.

Let us start with the following estimate which is a consequence of Propositions 3.3 and 3.4 in [26]

Proposition 3.2.
(a) The unique absolutely continuous solution $x(\cdot)$ of $(\mathcal{P})$ satisfies
(3.2) $\|\dot{x}\|_{L_{H}^{2}} \leq \frac{\rho}{2}\|\dot{a}\|_{L_{\mathbb{R}}^{2}}+\left[\sqrt{T-T_{0}} k(0)\|\dot{a}\|_{L_{\mathbb{R}}^{2}}\right.$

$$
\left.+\frac{\rho^{2}}{4}\|\dot{a}\|_{L_{\mathbb{R}}^{2}}^{2}+\varphi\left(T_{0}, x_{0}\right)-\varphi(T, x(T))\right]^{1 / 2}
$$

(b) If $h \in L_{H}^{2}(I)$ and $x_{0} \in \operatorname{dom} \varphi\left(T_{0}, \cdot\right)$, then the problem $\left(\mathcal{P}_{h}\right)$ admits a unique absolutely continuous solution $x(\cdot)$ that satisfies

$$
\begin{equation*}
\int_{T_{0}}^{T}\|\dot{x}(t)\|^{2} d t \leq 2 b_{0} \int_{T_{0}}^{T} \dot{a}^{2}(t) d t+\sigma \int_{T_{0}}^{T}\|h(t)\|^{2} d t+b_{1} . \tag{3.3}
\end{equation*}
$$

with

$$
\begin{aligned}
b_{0} & =\frac{1}{2}\left(k^{2}(0)+3(\rho+1)^{2}\right), \\
\sigma & =k^{2}(0)+3(\rho+1)^{2}+4, \\
b_{1} & =2\left[\left(T-T_{0}\right)+\varphi\left(T_{0}, x\left(T_{0}\right)\right)-\varphi(T, x(T))\right] .
\end{aligned}
$$

Proof. Assertion (a) corresponds to Proposition 3.3 in [26]. Concerning assertion (b), we know by Proposition 3.4 of [26] that $\left(\mathcal{P}_{h}\right)$ has a unique solution satisfying

$$
\begin{align*}
&\|\dot{x}\|_{L_{H}^{2}} \leq \frac{1}{2}(\rho+1)\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}}+\|h\|_{L_{H}^{2}}+\left[\sqrt{T-T_{0}} k(0)\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}}\right.  \tag{3.4}\\
&\left.+\frac{(\rho+1)^{2}}{4}\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}}^{2}+\varphi\left(T_{0}, x_{0}\right)-\varphi(T, x(T))\right]^{1 / 2}
\end{align*}
$$

where $|h|$ is the function of $I$ into $\mathbb{R}$ defined by $|h|(t):=\|h(t)\|$ for all $t \in I$. Hence, observing that

$$
\begin{aligned}
\sqrt{T-T_{0}} k(0)\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}(I)} & =2 \sqrt{T-T_{0}}\left(\frac{k(0)}{2}\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}(I)}\right) \\
& \leq\left(T-T_{0}\right)+\frac{k^{2}(0)}{4}\|\dot{a}+|h|\|_{L_{\mathbb{R}}(I)}^{2},
\end{aligned}
$$

we obtain

$$
\begin{aligned}
& \|\dot{x}\|_{L_{H}^{2}(I)} \leq \frac{(\rho+1)}{2}\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}(I)}+\|h\|_{L_{H}^{2}(I)} \\
+ & {\left[\left(T-T_{0}\right)+\frac{\left(k^{2}(0)+(\rho+1)^{2}\right)}{4}\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}(I)}^{2}+\varphi\left(T_{0}, x\left(T_{0}\right)\right)-\varphi(T, x(T))\right]^{1 / 2} }
\end{aligned}
$$

and hence

$$
\begin{aligned}
& \|\dot{x}\|_{L_{H}^{2}(I)}^{2} \leq 2\left[\frac{(\rho+1)}{2}\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}(I)}+\|h\|_{L_{H}^{2}(I)}\right]^{2} \\
+ & 2\left[\left(T-T_{0}\right)+\frac{\left(k^{2}(0)+(\rho+1)^{2}\right)}{4}\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}(I)}^{2}+\varphi\left(T_{0}, x\left(T_{0}\right)\right)-\varphi(T, x(T))\right] .
\end{aligned}
$$

We may also write

$$
\begin{aligned}
& \|\dot{x}\|_{L_{H}^{2}(I)}^{2} \leq(\rho+1)^{2}\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}(I)}^{2}+4\|h\|_{L_{H}^{2}(I)}^{2} \\
+ & 2\left[\left(T-T_{0}\right)+\varphi\left(T_{0}, x\left(T_{0}\right)\right)-\varphi(T, x(T))\right]+\frac{\left(k^{2}(0)+(\rho+1)^{2}\right)}{2}\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}(I)}^{2} .
\end{aligned}
$$

Setting

$$
b_{0}=\frac{1}{2}\left(k^{2}(0)+3(\rho+1)^{2}\right), \quad b_{1}=2\left[\left(T-T_{0}\right)+\varphi\left(T_{0}, x\left(T_{0}\right)\right)-\varphi(T, x(T))\right]
$$

one has

$$
\|\dot{x}\|_{L_{H}^{2}(I)}^{2} \leq b_{0}\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}(I)}^{2}+4\|h\|_{L_{H}^{2}(I)}^{2}+b_{1} .
$$

As $\|\dot{a}+|h|\|_{L_{\mathbb{R}}^{2}(I)}^{2} \leq 2\|\dot{a}\|_{L_{\mathbb{R}}^{2}(I)}^{2}+2\|h\|_{L_{H}^{2}(I)}^{2}$, putting $\sigma=2\left(b_{0}+2\right)$, we get

$$
\|\dot{x}\|_{L_{H}^{2}(I)}^{2} \leq 2 b_{0}\|\dot{a}\|_{L_{\mathbb{R}}^{2}(I)}^{2}+\sigma\|h\|_{L_{H}^{2}(I)}^{2}+b_{1} .
$$

Equivalently,

$$
\int_{T_{0}}^{T}\|\dot{x}(t)\|^{2} d t \leq 2 b_{0} \int_{T_{0}}^{T} \dot{a}^{2}(t) d t+\sigma \int_{T_{0}}^{T}\|h(t)\|^{2} d t+b_{1} .
$$

## 4. Set-valued perturbation

We study here the perturbed problem $\left(\mathcal{P}_{F(\cdot, \cdot)}\right)$ under an upper hemicontinuity property for the set-valued perturbation $F$. In the development, we will use some ideas from [11], [19], [20].

Theorem 4.1. Let $H$ be a real separable Hilbert space. Assume that $\varphi: I \times$ $H \rightarrow \mathbb{R}_{+} \cup\{+\infty\}$ is an extended-real-valued function satisfying $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{2}\right)$ of Theorem 3.1. Let $F: I \times H \rightrightarrows H$ be a set-valued mapping with nonempty convex compact values such that:
(a) $F(\cdot, \cdot)$ is globally scalarly upper semicontinuous on $I \times H$;
(b) for some compact subset $K \subset \mathbb{B}$ and some non-negative function $\beta(\cdot) \in$ $L_{\mathbb{R}}^{2}(I)$, for all $(t, x) \in I \times H$, one has the growth type condition

$$
F(t, x) \subset \beta(t)(1+\|x\|) K
$$

Then, for any $x_{0} \in \operatorname{dom} \varphi\left(T_{0}, \cdot\right)$ the following problem

$$
\left\{\begin{array}{l}
-\dot{x}(t) \in \partial \varphi(t, x(t))+F(t, x(t)) \quad \text { for a.e. } t \in I  \tag{1}\\
x\left(T_{0}\right)=x_{0}
\end{array}\right.
$$

has at least one absolutely continuous solution. More precisely, there exists an absolutely continuous map $x(\cdot): I \rightarrow H$ and an integrable map $y(\cdot): I \rightarrow H$ such that $x\left(T_{0}\right)=x_{0}, x(t) \in \operatorname{dom} \varphi(t, x(t))$ for all $t \in I$ and, for almost all $t \in I, y(t) \in F(t, x(t))$ and $-\dot{x}(t)-y(t) \in \partial \varphi(t, x(t))$, with

$$
\|y(t)\| \leq(\beta(t)+1)(1+\|x(t)\|)
$$

Moreover, the following inequalities hold true

$$
\begin{equation*}
\int_{T_{0}}^{T}\|\dot{x}(t)\|^{2} d t \leq \alpha+\sigma \int_{T_{0}}^{T}\|y(t)\|^{2} d t \tag{4.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{T_{0}}^{T}\|\dot{x}(t)\|^{2} d t \leq \alpha+\sigma \int_{T_{0}}^{T}(\beta(s)+1)^{2}(1+\|x(s)\|)^{2} d s \tag{4.2}
\end{equation*}
$$

where
(4.3) $\alpha=\left(k^{2}(0)+3(\rho+1)^{2}\right) \int_{T_{0}}^{T} \dot{a}^{2}(t) d t+2\left[T-T_{0}+\varphi\left(T_{0}, x_{0}\right)-\varphi(T, x(T))\right]$,

$$
\begin{equation*}
\sigma=k^{2}(0)+3(\rho+1)^{2}+4 \tag{4.4}
\end{equation*}
$$

Proof. We suppose, without loss of generality, that $K$ is convex and contains 0 . If not so, we may replace $K$ by $\overline{\operatorname{co}}(K \cup\{0\})$ which is compact according to Dunford and Schwartz ([17, Theorem V.2.6]). Since the function $(1+\beta(\cdot))^{2}$ is $\lambda$-integrable on $I=\left[T_{0}, T\right]$, for the real number

$$
\begin{equation*}
m=\frac{1}{4\left(T-T_{0}\right)\left(k^{2}(0)+3(\rho+1)^{2}+4\right)}>0 \tag{4.5}
\end{equation*}
$$

there exists a finite subdivision $T_{0}<T_{1}<\ldots<T_{k}=T$ such that for each $j=1, \ldots, k$ one has

$$
\begin{equation*}
\int_{T_{j-1}}^{T_{j}}(\beta(s)+1)^{2} d s<m . \tag{4.6}
\end{equation*}
$$

Let us start first by establishing a solution on the interval $I_{1}:=\left[T_{0}, T_{1}\right]$ by constructing a sequence of maps $\left(x_{n}(\cdot)\right)$ in $\mathcal{C}_{H}\left(I_{1}\right)$ which has a subsequence converging uniformly on $I_{1}$ to a solution of $\left(\mathcal{P}_{1}\right)$.
(A) Construction of the sequence $\left(x_{n}(\cdot)\right)$.

Define, for every $n \in \mathbb{N}$, a partition of $I_{1}:=\left[T_{0}, T_{1}\right]$ with

$$
t_{i}^{n}:=T_{0}+(i-1) \frac{T_{1}-T_{0}}{n} \quad(1 \leq i \leq n+1)
$$

and consider for $i \in\{1, \ldots, n\}, \delta_{i}^{n} \in\left[t_{i}^{n}, t_{i+1}^{n}\right]$ such that

$$
\begin{equation*}
\beta\left(\delta_{i}^{n}\right) \leq \inf _{t \in\left[t_{i}^{n}, t_{i+1}^{n}\right]} \beta(t)+1 . \tag{4.7}
\end{equation*}
$$

Then, fix any $n \in \mathbb{N}$. Put $x_{1}^{n}\left(t_{1}^{n}\right)=x_{0}$ and choose $y_{1}^{n} \in F\left(\delta_{1}^{n}, x_{0}\right)$. Then, relying on Proposition 3.2, denote by $x_{1}^{n}(\cdot):\left[t_{1}^{n}, t_{2}^{n}\right] \rightarrow H$ the absolutely continuous solution on $\left[t_{1}^{n}, t_{2}^{n}\right]$ of the inclusion

$$
\left\{\begin{array}{l}
-\dot{x}(t) \in \partial \varphi(t, x(t))+y_{1}^{n} \quad \text { for a.e. } t \in\left[t_{1}^{n}, t_{2}^{n}\right] \\
x\left(t_{1}^{n}\right)=x_{1}^{n}\left(t_{1}^{n}\right)=x_{0} \in \operatorname{dom} \varphi\left(t_{1}^{n}, \cdot\right) .
\end{array}\right.
$$

Next, for each $i \in\{2, \ldots, n\}$, choose $y_{i}^{n} \in F\left(\delta_{i}^{n}, x_{i-1}^{n}\left(t_{i}^{n}\right)\right)$, and let

$$
x_{i}^{n}(\cdot):\left[t_{i}^{n}, t_{i+1}^{n}\right] \rightarrow H
$$

be the absolutely continuous solution of

$$
\left\{\begin{array}{l}
-\dot{x}(t) \in \partial \varphi(t, x(t))+y_{i}^{n} \quad \text { for a.e. } t \in\left[t_{i}^{n}, t_{i+1}^{n}\right] \\
x\left(t_{i}^{n}\right)=x_{i-1}^{n}\left(t_{i}^{n}\right) \in \operatorname{dom} \varphi\left(t_{i}^{n}, \cdot\right)
\end{array}\right.
$$

Recall that, in view of Proposition 3.2, inequality (3.3) holds true in each subinterval $\left[t_{i}^{n}, t_{i+1}^{n}\right]$ of $I_{1}$, that is, for any $i \in\{1, \ldots, n\}$, one has

$$
\begin{equation*}
\int_{t_{i}^{n}}^{t_{i+1}^{n}}\left\|\dot{x}_{i}^{n}(t)\right\|^{2} d t \leq 2 b_{0} \int_{t_{i}^{n}}^{t_{i+1}^{n}} \dot{a}^{2}(t) d t+\sigma \int_{t_{i}^{n}}^{t_{i+1}^{n}}\left\|y_{i}^{n}\right\|^{2} d t+c_{i} . \tag{4.8}
\end{equation*}
$$

with

$$
\begin{aligned}
b_{0} & =\frac{1}{2}\left(k^{2}(0)+3(\rho+1)^{2}\right), \\
\sigma & =k^{2}(0)+3(\rho+1)^{2}+4, \\
c_{i} & =2\left[\left(t_{i+1}^{n}-t_{i}^{n}\right)+\varphi\left(t_{i}^{n}, x_{i}^{n}\left(t_{i}^{n}\right)\right)-\varphi\left(t_{i+1}^{n}, x_{i}^{n}\left(t_{i+1}^{n}\right)\right)\right] .
\end{aligned}
$$

Now, define $x_{n}:\left[T_{0}, T_{1}\right] \rightarrow H$ by

$$
x_{n}(t)= \begin{cases}x_{i}^{n}(t) & \text { if } t \in\left[t_{i}^{n}, t_{i+1}^{n}[\text { for some } i \in\{1, \ldots, n\},\right. \\ x_{n}^{n}\left(T_{1}\right) & \text { if } t=T_{1} .\end{cases}
$$

Such a map $x_{n}(\cdot)$ is absolutely continuous on $\left[T_{0}, T_{1}\right]$. Consider the maps $\theta_{n}, \Delta_{n}:\left[T_{0}, T_{1}\right] \rightarrow\left[T_{0}, T_{1}\right]$ such that

$$
\theta_{n}(t)= \begin{cases}t_{i}^{n} & \text { if } t \in\left[t_{i}^{n}, t_{i+1}^{n}[\text { for some } i \in\{1, \ldots, n\}\right. \\ T_{1} & \text { if } t=T_{1}\end{cases}
$$

and

$$
\Delta_{n}(t)= \begin{cases}\delta_{i}^{n} & \text { if } t \in\left[t_{i}^{n}, t_{i+1}^{n}[\text { for some } i \in\{1, \ldots, n\}\right. \\ \delta_{n}^{n} & \text { if } t=T_{1}\end{cases}
$$

Next, define $y_{n}:\left[T_{0}, T_{1}\right] \rightarrow H$ by

$$
y_{n}(t)= \begin{cases}y_{i}^{n} & \text { if } t \in\left[t_{i}^{n}, t_{i+1}^{n}[\text { for some } i \in\{1, \ldots, n\}\right. \\ y_{n}^{n} & \text { if } t=T_{1}\end{cases}
$$

Then, for each $n \in \mathbb{N}$, we have the following:
(1) $y_{n}(t) \in F\left(\Delta_{n}(t), x_{n}\left(\theta_{n}(t)\right)\right) \subset \beta\left(\Delta_{n}(t)\right)\left(1+\left\|x_{n}\left(\theta_{n}(t)\right)\right\|\right) K$, for all $t \in$ $\left[T_{0}, T_{1}\right]$,
(2) for all $t \in\left[T_{0}, T_{1}\right],\left\|y_{n}(t)\right\| \leq \beta\left(\Delta_{n}(t)\right)\left(1+\left\|x_{n}\left(\theta_{n}(t)\right)\right\|\right)$,
(3) $x_{n}\left(T_{0}\right)=x_{0}$,
(4) $-\dot{x}_{n}(t) \in \partial \varphi\left(t, x_{n}(t)\right)+y_{n}(t)$ for almost every $t \in\left[T_{0}, T_{1}\right]$, and hence $-\dot{x}_{n}(t) \in \partial \varphi\left(t, x_{n}(t)\right)+F\left(\Delta_{n}(t), x_{n}\left(\theta_{n}(t)\right)\right) \quad$ for a.e. $t \in\left[T_{0}, T_{1}\right]$.

Further, we may write (4.8), as follows

$$
\begin{equation*}
\int_{t_{i}^{n}}^{t_{i+1}^{n}}\left\|\dot{x}_{n}(t)\right\|^{2} d t \leq 2 b_{0} \int_{t_{i}^{n}}^{t_{i+1}^{n}} \dot{a}^{2}(t) d t+\sigma \int_{t_{i}^{n}}^{t_{i+1}^{n}}\left\|y_{n}(t)\right\|^{2} d t+c_{i} . \tag{4.9}
\end{equation*}
$$

Taking (2) and (4.7) into account, it results that, for any $i \in\{1, \ldots, n\}$,

$$
\begin{aligned}
\int_{t_{i}^{n}}^{t_{i+1}^{n}} & \left\|\dot{x}_{n}(t)\right\|^{2} d t \\
& \leq 2 b_{0} \int_{t_{i}^{n}}^{t_{i+1}^{n}} \dot{a}^{2}(t) d t+\sigma \int_{t_{i}^{n}}^{t_{i+1}^{n}}(\beta(t)+1)^{2}\left(1+\left\|x_{n}\left(\theta_{n}(t)\right)\right\|\right)^{2} d t+c_{i} \\
& \leq 2 b_{0} \int_{t_{i}^{n}}^{t_{i+1}^{n}} \dot{a}^{2}(t) d t+\sigma\left(1+\left\|x_{n}\left(t_{i}^{n}\right)\right\|\right)^{2} \int_{t_{i}^{n}}^{t_{i+1}^{n}}(\beta(t)+1)^{2} d t+c_{i} \\
& \leq 2 b_{0} \int_{t_{i}^{n}}^{t_{i+1}^{n}} \dot{a}^{2}(t) d t+\sigma\left(1+\max _{1 \leq i \leq n+1}\left\|x_{n}\left(t_{i}^{n}\right)\right\|\right)^{2} \int_{t_{i}^{n}}^{t_{i+1}^{n}}(\beta(t)+1)^{2} d t+c_{i}
\end{aligned}
$$

and, with this being true for any $i \in\{1, \ldots, n\}$, we obtain

$$
\sum_{i=1}^{n} \int_{t_{i}^{n}}^{t_{i+1}^{n}}\left\|\dot{x}_{n}(t)\right\|^{2} d t \leq 2 b_{0} \int_{T_{0}}^{T_{1}} \dot{a}^{2}(t) d t+\sigma\left(1+\left\|x_{n}(\cdot)\right\|_{\infty}\right)^{2} \int_{T_{0}}^{T_{1}}(\beta(t)+1)^{2} d t+c_{n}^{\prime}
$$

where $\|\cdot\|_{\infty}$ denotes the supremum norm over the interval $\left[T_{0}, T_{1}\right]$ and

$$
c_{n}^{\prime}=\sum_{i=1}^{n} c_{i}=2\left[T_{1}-T_{0}+\varphi\left(T_{0}, x_{0}\right)-\varphi\left(T_{1}, x_{n}\left(T_{1}\right)\right)\right] .
$$

As $-\varphi\left(T_{1}, x_{n}\left(T_{1}\right)\right) \leq 0$, putting $d=2\left[T_{1}-T_{0}+\varphi\left(T_{0}, x_{0}\right)\right]$, we may write

$$
\int_{T_{0}}^{T_{1}}\left\|\dot{x}_{n}(t)\right\|^{2} d t \leq 2 b_{0} \int_{T_{0}}^{T_{1}} \dot{a}^{2}(t) d t+2 \sigma\left(1+\left\|x_{n}(\cdot)\right\|_{\infty}^{2}\right) \int_{T_{0}}^{T_{1}}(\beta(t)+1)^{2} d t+d
$$

and hence

$$
\begin{equation*}
\int_{T_{0}}^{T_{1}}\left\|\dot{x}_{n}(t)\right\|^{2} d t \leq b+c\left\|x_{n}(\cdot)\right\|_{\infty}^{2} \tag{4.10}
\end{equation*}
$$

where
$b=2 b_{0} \int_{T_{0}}^{T_{1}} \dot{a}^{2}(t) d t+2 \sigma \int_{T_{0}}^{T_{1}}(\beta(t)+1)^{2} d t+d \quad$ and $\quad c=2 \sigma \int_{T_{0}}^{T_{1}}(\beta(t)+1)^{2} d t$.
Using the Cauchy-Schwartz inequality and (4.10), one has for all $s \in I_{1}$

$$
\left\|x_{n}(s)-x_{0}\right\|^{2} \leq\left(s-T_{0}\right)\left(\int_{T_{0}}^{s}\left\|\dot{x}_{n}(t)\right\|^{2} d t\right) \leq\left(T_{1}-T_{0}\right)\left(b+c\left\|x_{n}(\cdot)\right\|_{\infty}^{2}\right)
$$

and hence

$$
\left\|x_{n}(s)\right\|^{2} \leq 2\left\|x_{0}\right\|^{2}+2\left\|x_{n}(s)-x_{0}\right\|^{2} \leq 2\left\|x_{0}\right\|^{2}+2\left(T_{1}-T_{0}\right)\left(b+c\left\|x_{n}(\cdot)\right\|_{\infty}^{2}\right)
$$

Consequently, for each $n$, we get

$$
\left(1-2\left(T_{1}-T_{0}\right) c\right)\left\|x_{n}(\cdot)\right\|_{\infty}^{2} \leq 2\left(\left\|x_{0}\right\|^{2}+\left(T-T_{0}\right) b\right)
$$

According to (4.6), that is, $2\left(T_{1}-T_{0}\right) c<1$, one has, for any $t$ and for any $n$,

$$
\begin{equation*}
\left\|x_{n}(\cdot)\right\|_{\infty} \leq M_{1} \tag{4.11}
\end{equation*}
$$

where

$$
M_{1}:=\left(\frac{2\left(\left\|x_{0}\right\|^{2}+\left(T_{1}-T_{0}\right) b\right)}{1-2\left(T_{1}-T_{0}\right) c}\right)^{1 / 2}
$$

For each $n \in \mathbb{N}$ and any $t \in I_{1}:=\left[T_{0}, T_{1}\right]$, define $z_{n}(t):=\int_{T_{0}}^{t} y_{n}(s) d s$. Then, the $\operatorname{map} z_{n}(\cdot)$ is absolutely continuous on $\left[T_{0}, T_{1}\right]$. By virtue of (2), (4.7) and (4.11), for $T_{0} \leq r \leq t \leq T_{1}$, we have

$$
\begin{equation*}
\left\|y_{n}(t)\right\| \leq\left(M_{1}+1\right)(\beta(t)+1) \tag{4.12}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|z_{n}(t)-z_{n}(r)\right\| \leq\left(M_{1}+1\right) \int_{r}^{t}(\beta(s)+1) d s \tag{4.13}
\end{equation*}
$$

so that the family $\left(z_{n}\right)_{n \in \mathbb{N}}$ is equicontinuous in $\mathcal{C}_{H}\left(I_{1}\right)$.
Furthermore, since $K$ is convex with $0 \in K$, it follows from (1), (4.7) and (4.11) that

$$
\forall n \in \mathbb{N}, \forall t \in\left[T_{0}, T_{1}\right], \quad y_{n}(t) \in\left(M_{1}+1\right)(\beta(t)+1) K
$$

Since $K$ is closed and convex, this yields that for all $n \geq 1$ and $t \in\left[T_{0}, T_{1}\right]$

$$
\begin{equation*}
z_{n}(t) \in\left[\left(M_{1}+1\right) \int_{T_{0}}^{t}(\beta(s)+1) d s\right] K \tag{4.14}
\end{equation*}
$$

and once more, since $K$ is convex with $0 \in K$, we deduce that for any $t \in\left[T_{0}, T_{1}\right]$ the set $\left\{z_{n}(t), n \in \mathbb{N}\right\}$ is included in the strongly compact set

$$
\left[\left(M_{1}+1\right) \int_{T_{0}}^{T_{1}}(\beta(s)+1) d s\right] K .
$$

(B) Uniform convergence of a subsequence of $\left(x_{n}(\cdot)\right)$ to some map $u_{1}(\cdot)$.

Ascoli's theorem ensures us that, up to a subsequence, $\left(z_{n}\right)$ converges uniformly on $\left[T_{0}, T_{1}\right]$ to some continuous mapping $z(\cdot)$. Further, (4.10) and (4.11) entail that

$$
\begin{equation*}
\sup _{n \in \mathbb{N}}\left\|\dot{x}_{n}(\cdot)\right\|_{L_{H}^{2}\left(I_{1}\right)}<+\infty \tag{4.15}
\end{equation*}
$$

Now, making use of the monotonicity of $\partial \varphi(t, \cdot)$ for all $t \in I_{1}$, we will show that the corresponding subsequence $\left(x_{n}\right)$ converges uniformly on $I_{1}$ to some solution over $I_{1}$ of the differential inclusion under consideration. For any $n \in \mathbb{N}$ and any $t \in\left[T_{0}, T_{1}\right]$, define $X_{n}(t):=x_{n}(t)+z_{n}(t)$. The maps $X_{n}$ are clearly absolutely continuous and for any fixed $p, q \in \mathbb{N}$, and for almost all $t \in\left[T_{0}, T_{1}\right]$, one has

$$
\begin{aligned}
\frac{1}{2} \frac{d}{d t} \| X_{p}(t) & -X_{q}(t) \|^{2}=\left\langle\dot{X}_{p}(t)-\dot{X}_{q}(t), X_{p}(t)-X_{q}(t)\right\rangle \\
& =\left\langle\dot{X}_{p}(t)-\dot{X}_{q}(t), x_{p}(t)-x_{q}(t)\right\rangle+\left\langle\dot{X}_{p}(t)-\dot{X}_{q}(t), z_{p}(t)-z_{q}(t)\right\rangle
\end{aligned}
$$

By definition, one has

$$
\begin{aligned}
& -\dot{X}_{p}(t)=-\dot{x}_{p}(t)-y_{p}(t) \in \partial \varphi\left(t, x_{p}(t)\right), \\
& -\dot{X}_{q}(t)=-\dot{x}_{q}(t)-y_{q}(t) \in \partial \varphi\left(t, x_{q}(t)\right),
\end{aligned}
$$

and the monotonicity property of $\partial \varphi(t, \cdot)$ entails that

$$
\left\langle\dot{X}_{p}(t)-\dot{X}_{q}(t), x_{p}(t)-x_{q}(t)\right\rangle \leq 0
$$

Therefore, one has

$$
\frac{1}{2} \frac{d}{d t}\left\|X_{p}(t)-X_{q}(t)\right\|^{2} \leq\left\|\dot{X}_{p}(t)-\dot{X}_{q}(t)\right\|\left\|z_{p}(t)-z_{q}(t)\right\| .
$$

Now, we deduce from (4.15) that the sequence $\left(\dot{x}_{n}\right)$ is bounded in $L_{H}^{2}\left(I_{1}\right)$, and since via (4.12)

$$
\sup _{n \in \mathbb{N}}\left\|\dot{z}_{n}(\cdot)\right\|_{L_{H}^{2}\left(I_{1}\right)}^{2} \leq\left(M_{1}+1\right)^{2} \int_{T_{0}}^{T_{1}}(\beta(s)+1)^{2} d s<+\infty
$$

we conclude that

$$
A:=\sup _{n \in \mathbb{N}}\left\|\dot{X}_{n}(\cdot)\right\|_{L_{H}^{2}\left(I_{1}\right)}<+\infty .
$$

The uniform convergence of the sequence $\left(z_{n}\right)$ ensures us that

$$
\int_{T_{0}}^{T_{1}}\left\|z_{p}(t)-z_{q}(t)\right\| d t \rightarrow 0
$$

when $p, q \rightarrow \infty$. This, along with the fact that $\left\|X_{p}\left(T_{0}\right)-X_{q}\left(T_{0}\right)\right\|=0$, entails

$$
\lim _{p, q \rightarrow \infty}\left\|X_{p}(\cdot)-X_{q}(\cdot)\right\|_{\infty}=0
$$

Then, the uniform Cauchy's criterion guarantees that the sequence $\left(X_{n}(\cdot)\right)$ converges uniformly on $I_{1}$ to some map $X(\cdot) \in \mathcal{C}_{H}\left(I_{1}\right)$. So, the sequence $\left(x_{n}\right)=$ $\left(X_{n}-z_{n}\right)$ converges uniformly on $I_{1}$ to some continuous map $u_{1}(\cdot) \in \mathcal{C}_{H}\left(I_{1}\right)$, with $u_{1}\left(T_{0}\right)=x_{0}$ according to (3). By (4.15) the sequence $\left(\dot{x}_{n}\right)$ is bounded in $L_{H}^{\infty}\left(I_{1}\right)$ and hence also in $L_{H}^{2}\left(I_{1}\right)$. We may then extract a subsequence converging weakly in $L_{H}^{2}\left(I_{1}\right)$ to some map $v(\cdot)$. The equality

$$
x_{n}(t)=x_{n}\left(T_{0}\right)+\int_{T_{0}}^{t} \dot{x}_{n}(s) d s \quad \text { for all } t \in I_{1}
$$

then yields

$$
\begin{equation*}
u_{1}(t)=u_{1}\left(T_{0}\right)+\int_{T_{0}}^{t} v(s) d s \quad \text { for all } t \in I_{1} \tag{4.16}
\end{equation*}
$$

and hence the map $u_{1}(\cdot)$ is absolutely continuous on $I_{1}$ with $\dot{u}_{1}(\cdot)=v(\cdot)$ on $I_{1}$.
(C) Let us prove that $u_{1}(\cdot)$ is a solution of $\left(\mathcal{P}_{1}\right)$ on $I_{1}$.

Recall that, for almost all $t \in\left[T_{0}, T_{1}\right]$, for all $n \in \mathbb{N}$ one has

$$
-\dot{X}_{n}(t) \in \partial \varphi\left(t, x_{n}(t)\right) \quad \text { and } \quad y_{n}(t) \in F\left(\Delta_{n}(t), x_{n}\left(\theta_{n}(t)\right)\right)
$$

where $\lim _{n \rightarrow \infty} \max \left\{\left|\triangle_{n}(t)-t\right| ;\left|\theta_{n}(t)-t\right|\right\}=0$ and that by (4.12) one also has

$$
\sup _{n \in \mathbb{N}}\left\|y_{n}(\cdot)\right\|_{L_{H}^{2}\left(I_{1}\right)}^{2} \leq\left(M_{1}+1\right)^{2} \int_{T_{0}}^{T_{1}}(\beta(s)+1)^{2} d s<+\infty .
$$

We may assume that the sequences $\left(y_{n}\right)$ and $\left(\dot{x}_{n}\right)$ converge weakly in $L_{H}^{2}\left(\left[T_{0}, T_{1}\right]\right)$ to $y^{1}$ and $\dot{u}_{1}$ respectively (see (4.16)). Then, the corresponding subsequence $\left(\dot{X}_{n}\right)$ converges weakly in $L_{H}^{2}\left(\left[T_{0}, T_{1}\right]\right)$ to $y^{1}+\dot{u}_{1}$. Classically, following the corresponding arguments of the proof of Theorem 1 in [20], one has

$$
\begin{equation*}
-\dot{u}_{1}(t) \in \partial \varphi\left(t, u_{1}(t)\right)+y^{1}(t) \quad \text { for a.e. } t \in\left[T_{0}, T_{1}\right] . \tag{4.17}
\end{equation*}
$$

It remains to show that $y^{1}(t) \in F\left(t, u_{1}(t)\right)$ for almost every $t \in\left[T_{0}, T_{1}\right]$. By construction, we have $y_{n}(t) \in F\left(\Delta_{n}(t), x_{n}\left(\theta_{n}(t)\right)\right)$ for almost every $t \in\left[T_{0}, T_{1}\right]$. As $\left(\triangle_{n}(t), x_{n}\left(\theta_{n}(t)\right)\right)$ converges to $\left(t, u_{1}(t)\right)$ for each $t \in\left[T_{0}, T_{1}\right]$ and $\left(y_{n}\right)$ converges weakly in $L_{H}^{2}\left(\left[T_{0}, T_{1}\right]\right)$ to $y^{1}$, and $F$ is scalarly upper semicontinuous on $\left[T_{0}, T_{1}\right] \times H$, invoking the closure theorem in [4, Theorem 1.4.1], we get the required inclusion. Combining this with (4.17), we conclude that $u_{1}(\cdot)$ is an
absolutely continuous solution of $-\dot{u}_{1}(t) \in \partial \varphi\left(t, u_{1}(t)\right)+F\left(t, u_{1}(t)\right)$ for almost every $t \in\left[T_{0}, T_{1}\right], u_{1}\left(T_{0}\right)=x_{0}$ over $I_{1}$. Summing (4.9) it follows that

$$
\sum_{i=1}^{n} \int_{t_{i}^{n}}^{t_{i+1}^{n}}\left\|\dot{x}_{n}(t)\right\|^{2} d t \leq 2 b_{0} \sum_{i=1}^{n} \int_{t_{i}^{n}}^{t_{i+1}^{n}} \dot{a}^{2}(t) d t+\sigma \sum_{i=1}^{n} \int_{t_{i}^{n}}^{t_{i+1}^{n}}\left\|y_{n}(t)\right\|^{2} d t+\sum_{i=1}^{n} c_{i}
$$

and hence, for all $n$, we have

$$
\begin{equation*}
\int_{T_{0}}^{T_{1}}\left\|\dot{x}_{n}(t)\right\|^{2} d t \leq 2 b_{0} \int_{T_{0}}^{T_{1}} \dot{a}^{2}(t) d t+\sigma \int_{T_{0}}^{T_{1}}\left\|y_{n}(t)\right\|^{2} d t+c_{n}^{\prime} \tag{4.18}
\end{equation*}
$$

Taking (4.7) and (1) into account we obtain

$$
\begin{align*}
& \int_{T_{0}}^{T_{1}}\left\|\dot{x}_{n}(t)\right\|^{2} d t  \tag{4.19}\\
& \quad \leq 2 b_{0} \int_{T_{0}}^{T_{1}} \dot{a}^{2}(t) d t+\sigma \int_{T_{0}}^{T_{1}}(\beta(t)+1)^{2}\left(1+\left\|x_{n}\left(\theta_{n}(t)\right)\right\|\right)^{2} d t+c_{n}^{\prime}
\end{align*}
$$

As an estimate on the velocity, let us underline that, taking the superior limit on $n$ in (4.18) and using the preceding convergence results yield

$$
\int_{T_{0}}^{T_{1}}\left\|\dot{u}_{1}(t)\right\|^{2} d t \leq 2 b_{0} \int_{T_{0}}^{T_{1}} \dot{a}^{2}(t) d t+\sigma \int_{T_{0}}^{T_{1}}\left\|y^{1}(t)\right\|^{2} d t+\limsup _{n} c_{n}^{\prime}
$$

Since $x_{n}(t) \rightarrow u_{1}(t)$, by the lower semicontinuity of $\varphi(t, \cdot)$, we have

$$
\begin{aligned}
\underset{n}{\limsup } c_{n}^{\prime} & =2\left[T_{1}-T_{0}+\varphi\left(T_{0}, x_{0}\right)-\liminf _{n} \varphi\left(T_{1}, x_{n}\left(T_{1}\right)\right)\right] \\
& \leq 2\left[T_{1}-T_{0}+\varphi\left(T_{0}, x_{0}\right)-\varphi\left(T_{1}, u_{1}\left(T_{1}\right)\right)\right]
\end{aligned}
$$

Hence, we obtain

$$
\begin{equation*}
\int_{T_{0}}^{T_{1}}\left\|\dot{u}_{1}(t)\right\|^{2} d t \leq \alpha_{1}+\sigma \int_{T_{0}}^{T_{1}}\left\|y^{1}(t)\right\|^{2} d t \tag{4.20}
\end{equation*}
$$

where

$$
\alpha_{1}=\left(k^{2}(0)+3(\rho+1)^{2}\right) \int_{T_{0}}^{T_{1}} \dot{a}^{2}(t) d t+2\left[T_{1}-T_{0}+\varphi\left(T_{0}, x_{0}\right)-\varphi\left(T_{1}, u_{1}\left(T_{1}\right)\right)\right] .
$$

Similarly, taking the superior limit on $n$ in (4.19) and using the preceding convergence results again yield

$$
\begin{equation*}
\int_{T_{0}}^{T_{1}}\left\|\dot{u}_{1}(t)\right\|^{2} d t \leq \alpha_{1}+\sigma \int_{T_{0}}^{T_{1}}(\beta(t)+1)^{2}\left(1+\left\|u_{1}(t)\right\|\right)^{2} d t \tag{4.21}
\end{equation*}
$$

The analysis above also yields a solution $u_{2}(\cdot)$ to the differential inclusion $\left(\mathcal{P}_{1}\right)$ on the interval $I_{2}:=\left[T_{1}, T_{2}\right]$ with the initial condition $u_{2}\left(T_{1}\right)=u_{1}\left(T_{1}\right)$ and by (4.20) and (4.21) the solution satisfies for
$\alpha_{2}=\left(k^{2}(0)+3(\rho+1)^{2}\right) \int_{T_{1}}^{T_{2}} \dot{a}^{2}(t) d t+2\left[T_{2}-T_{1}+\varphi\left(T_{1}, u_{1}\left(T_{1}\right)\right)-\varphi\left(T_{2}, u_{2}\left(T_{2}\right)\right)\right]$
and for some $L^{2}\left(I_{2}\right)$-selection $y^{2}(\cdot)$ of $F\left(\cdot, u_{2}(\cdot)\right)$ we have the inequalities

$$
\int_{T_{1}}^{T_{2}}\left\|\dot{u}_{2}(t)\right\|^{2} d t \leq \alpha_{2}+\sigma \int_{T_{1}}^{T_{2}}\left\|y^{2}(t)\right\|^{2} d t
$$

and

$$
\int_{T_{1}}^{T_{2}}\left\|\dot{u}_{2}(t)\right\|^{2} d t \leq \alpha_{2}+\sigma \int_{T_{1}}^{T_{2}}(\beta(t)+1)^{2}\left(1+\left\|u_{2}(t)\right\|\right)^{2} d t
$$

Proceeding in a similar way we obtain $u_{3}(\cdot)$ on $\left[T_{2}, T_{3}\right], \ldots, u_{k}(\cdot)$ on $\left[T_{k-1}, T_{k}\right]$. Putting $x(t)=u_{j}(t)$ and $y(t)=y^{j}(t)$ if $t \in\left[T_{j-1}, T_{j}\right]$, we see that $x(\cdot)$ is an absolutely continuous solution of $\left(\mathcal{P}_{1}\right)$ on the whole interval $I=\left[T_{0}, T\right]$ and the estimations (4.1) and (4.2) of the theorem hold because
$\alpha:=\sum_{j=1}^{k} \alpha_{j}=\left(k^{2}(0)+3(\rho+1)^{2}\right) \int_{T_{0}}^{T} \dot{a}^{2}(t) d t+2\left[T-T_{0}+\varphi\left(T_{0}, x_{0}\right)-\varphi(T, x(T))\right]$.
The proof of the theorem is then complete.
As a consequence, we have the following properties
Proposition 4.2. The absolutely continuous solution $x(\cdot)$ of $\left(\mathcal{P}_{1}\right)$ satisfies

$$
\int_{T_{0}}^{T}\|\dot{x}(t)\|^{2} d t \leq \alpha+\sigma(1+l)^{2} \int_{T_{0}}^{T}(\beta(t)+1)^{2} d t
$$

and $y(t) \in(1+l)(\beta(t)+1) \overline{\mathrm{CO}}(K \cup\{0\}),\|y(t)\| \leq(\beta(t)+1)(1+l)$ for almost every $t \in I$ with $l:=\left\|x_{0}\right\|+[\xi(T)]^{1 / 2}$ and where $\xi(\cdot)$ is the increasing, continuous, and non-negative function defined on $\left[T_{0}, T\right]$ by

$$
\xi(s)=b(s)+2 \sigma\left(s-T_{0}\right) \int_{T_{0}}^{s} b(\tau)(\beta(\tau)+1)^{2} \exp \left(2 \sigma \int_{\tau}^{s} \theta(\beta(\theta)+1)^{2} d \theta\right) d \tau
$$

and, for each $t \in\left[T_{0}, T\right]$,

$$
b(t)=\left(t-T_{0}\right)\left[\alpha+2 \sigma\left(1+\left\|x_{0}\right\|\right)^{2} \int_{T_{0}}^{t}(\beta(\tau)+1)^{2} d \tau\right]
$$

The constants $\alpha$ and $\sigma$ are defined as in Theorem 4.1.
Proof. Owing to (4.2) and making use of the absolute continuity of $x(\cdot)$ on $\left[T_{0}, T\right]$, we may write, for $T_{0} \leq s<T$,

$$
\begin{aligned}
\left\|x(s)-x_{0}\right\|^{2} & \leq\left(s-T_{0}\right) \int_{T_{0}}^{s}\|\dot{x}(\tau)\|^{2} d \tau \\
& \leq\left(s-T_{0}\right)\left[\alpha+\sigma \int_{T_{0}}^{s}(\beta(\tau)+1)^{2}(1+\|x(\tau)\|)^{2} d \tau\right]
\end{aligned}
$$

Hence, for any $s \in\left[T_{0}, T\right]$,

$$
\begin{aligned}
\left\|x(s)-x_{0}\right\|^{2} \leq\left(s-T_{0}\right)[\alpha+2 \sigma(1+ & \left.\left\|x_{0}\right\|\right)^{2} \int_{T_{0}}^{s}(\beta(\tau)+1)^{2} d \tau \\
& \left.+2 \sigma \int_{T_{0}}^{s}(\beta(\tau)+1)^{2}\left\|x(\tau)-x_{0}\right\|^{2} d \tau\right] .
\end{aligned}
$$

Applying Gronwall's inequality entails that given $s \in\left[T_{0}, T\right]$, one has

$$
\begin{equation*}
\left\|x(s)-x_{0}\right\|^{2} \leq \xi(s) \tag{4.22}
\end{equation*}
$$

where

$$
\xi(s)=b(s)+c(s) \int_{T_{0}}^{s} b(\tau)(\beta(\tau)+1)^{2} \exp \left(\int_{\tau}^{s}(\beta(\theta)+1)^{2} c(\theta) d \theta\right) d \tau
$$

with

$$
\begin{aligned}
& b(t)=\left(t-T_{0}\right)\left[\alpha+2 \sigma\left(1+\left\|x_{0}\right\|\right)^{2} \int_{T_{0}}^{t}(\beta(\tau)+1)^{2} d \tau\right] \\
& c(t)=2 \sigma\left(t-T_{0}\right) .
\end{aligned}
$$

Clearly such functions $b(\cdot), c(\cdot)$ and $\xi(\cdot)$ are increasing and continuous on $\left[T_{0}, T\right]$. Indeed, as a straight consequence of (4.22) and the finiteness of $T$, one has $\|x(\cdot)\|_{\infty} \leq l$, where $l:=\left\|x_{0}\right\|+[\xi(T)]^{1 / 2}$. Consequently,

$$
\|y(t)\| \leq(\beta(t)+1)(1+l) \quad \text { for a.e. } t \in I
$$

## 5. Separately scalarly u.s.c. perturbation

In this section we weaken the assumption of Theorem 4.1 concerning the setvalued map $F$. Here, it is assumed to be separately scalarly upper semicontinuous on $H$ and to have measurable selection with respect to the first variable. The development is for a large an adaptation of [19], [20]. In the remaining of the paper, we will denote by $\alpha, \sigma$, and $m$ the constants defined in Section 4, by (4.3), (4.4) and (4.5), respectively.

To begin with, we suppose that the function $\beta(\cdot)$ in the growth condition is constant.

Theorem 5.1. Under assumptions of Theorem 4.1 on $\varphi$, let $F: I \times H \rightrightarrows H$ be a set-valued mapping with nonempty convex compact values such that
(a) for any $x \in H, F(\cdot, x)$ has a $\lambda$-measurable selection;
(b) for all $t \in I, F(t, \cdot)$ is scalarly upper semicontinuous on $H$;
(c) for some compact subset $K \subset \mathbb{B}$ and some real number $\beta>0$, for all $(t, x) \in I \times H$, one has

$$
F(t, x) \subset \beta(1+\|x\|) K
$$

Then, for any $x_{0} \in \operatorname{dom} \varphi\left(T_{0}, \cdot\right)$ the following problem

$$
\left\{\begin{array}{l}
-\dot{x}(t) \in \partial \varphi(t, x(t))+F(t, x(t)) \quad \text { for a.e. } t \in I  \tag{2}\\
\quad x\left(T_{0}\right)=x_{0}
\end{array}\right.
$$

has at least one absolutely continuous solution. More precisely, there exist an absolutely continuous map $x(\cdot): I \rightarrow H$ and an integrable map $z(\cdot): I \rightarrow H$ such that $x\left(T_{0}\right)=x_{0}, x(t) \in \operatorname{dom} \varphi(t, x(t))$ for all $t \in I$ and for almost all $t \in I$, $z(t) \in F(t, x(t))$ and $-\dot{x}(t)-z(t) \in \partial \varphi(t, x(t))$ and

$$
\begin{equation*}
z(t) \in(\beta+1)(1+\|x(t)\|) \overline{\operatorname{co}}(K \cup\{0\}) \tag{5.1}
\end{equation*}
$$

Moreover, the following inequalities hold true

$$
\begin{equation*}
\int_{T_{0}}^{T}\|\dot{x}(t)\|^{2} d t \leq \alpha+\sigma \int_{T_{0}}^{T}\|z(t)\|^{2} d t \tag{5.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{T_{0}}^{T}\|\dot{x}(t)\|^{2} d t \leq \alpha+\sigma(\beta+1)^{2} \int_{T_{0}}^{T}(1+\|x(t)\|)^{2} d t . \tag{5.3}
\end{equation*}
$$

Proof. We will reduce the problem to the previous case, via set-valued versions of Scorza-Dragoni's theorem and Dugundji's extension theorem, and construct a sequence of absolutely continuous maps $\left(x_{n}(\cdot)\right)$. Next, it will be proved that this sequence has a subsequence converging uniformly in $\mathcal{C}_{H}(I)$ to a solution of $\left(\mathcal{P}_{2}\right)$.

We suppose without loss of generality, that $K$ is convex and contains 0 . If not so, we may replace $K$ by $\overline{c o}(K \cup\{0\})$. Dividing, if necessary $I$ into intervals of a same suitable length, we may suppose also that,

$$
\begin{equation*}
(\beta+1)^{2}\left(T-T_{0}\right)<m \tag{5.4}
\end{equation*}
$$

(A) Existence of the sequence $\left(x_{n}(\cdot)\right)$.

Set for the real number

$$
\begin{aligned}
\alpha_{0} & =\left(k^{2}(0)+3(\rho+1)^{2}\right) \int_{T_{0}}^{T} \dot{a}^{2}(t) d t+2\left[T-T_{0}+\varphi\left(T_{0}, x_{0}\right)\right], \\
M_{2} & :=\left(\frac{2\left(\left\|x_{0}\right\|^{2}+\left(T-T_{0}\right)\left[\alpha_{0}+2 \sigma(\beta+1)^{2}\left(T-T_{0}\right)\right]\right)}{1-4\left(T-T_{0}\right)^{2} \sigma(\beta+1)^{2}}\right)^{1 / 2}
\end{aligned}
$$

and fix a continuous function $\phi: \mathbb{R}^{+} \rightarrow[0,1]$ such that

$$
\phi(\tau)= \begin{cases}1 & \text { if } \tau \leq M_{2}  \tag{5.5}\\ 0 & \text { if } \tau \geq M_{2}+1\end{cases}
$$

Let us consider the compact convex metric space $Y:=\beta\left(2+M_{2}\right) K$, which is a Borel subset of $H$, and let us define a set-valued map $\widehat{F}: I \times H \rightrightarrows Y$ by

$$
\widehat{F}(t, x):=\phi(\|x\|) F(t, x) .
$$

Obviously, $\widehat{F}(\cdot, x)$ has a measurable selection for all $x \in H$ and, for each $t \in\left[T_{0}, T\right]$, the graph of $\widehat{F}(t, \cdot)$ is closed in $H \times Y$. Therefore, according to the set-valued version of Scorza-Dragoni's theorem from Castaing and Monteiro Marques [12], there exists a set-valued map $\widetilde{F}: I \times H \rightrightarrows Y$ with convex compact (possibly empty) values such that:

- for some $\lambda$-negligible subset $N_{0} \subset I$, for all $t \in I \backslash N_{0}$ and for all $x \in H$,

$$
\begin{equation*}
\widetilde{F}(t, x) \subset \widehat{F}(t, x) \tag{5.6}
\end{equation*}
$$

- there exists an increasing sequence $\left(I_{n}\right)_{n \geq 1}$ of compact subsets of $I$ such that, for each $n \geq 1, \lambda\left(I \backslash I_{n}\right) \leq 1 / n$ and the restriction of $\widetilde{F}$ to $I_{n} \times H$, denoted by $\left.\widetilde{F}\right|_{I_{n} \times H}$, is (globally) upper semicontinuous with nonempty convex compact values.
By the set-valued version of Dugundji's extension theorem from Benabdellah and Faik [5], for each $n \geq 1$, there exists some upper semicontinuous extension $\widetilde{F}_{n}$ of $\left.\widetilde{F}\right|_{I_{n} \times H}$ to $I \times H$ that takes on nonempty convex compact values and satisfies, like $\widehat{F}$,

$$
\widetilde{F}_{n}(t, x) \subset \beta(1+\|x\|) K \quad \text { for all }(t, x) \in I \times H
$$

Since $(\beta+1)^{2}\left(T-T_{0}\right)<m$, due to Theorem 4.1, for each $n \geq 1$, there exist an absolutely continuous map $x_{n}(\cdot): I \rightarrow H$ and an integrable map $z_{n}(\cdot): I \rightarrow H$ such that $x_{n}\left(T_{0}\right)=x_{0}$, and for almost all $t \in I$,

$$
\begin{gather*}
z_{n}(t) \in \widetilde{F}_{n}\left(t, x_{n}(t)\right)  \tag{5.7}\\
-\dot{x}_{n}(t)-z_{n}(t) \in \partial \varphi\left(t, x_{n}(t)\right)  \tag{5.8}\\
\left\|z_{n}(t)\right\| \leq\left(M_{2}+1\right)(\beta+1) \quad \text { and } \quad z_{n}(t) \in\left(M_{2}+1\right)(\beta+1) K \tag{5.9}
\end{gather*}
$$

and

$$
\begin{equation*}
\int_{T_{0}}^{T}\left\|\dot{x}_{n}(t)\right\|^{2} d t \leq \alpha_{0}+\sigma\left(T-T_{0}\right)(\beta+1)^{2}\left(1+M_{2}\right)^{2} \tag{5.10}
\end{equation*}
$$

In view of (4.2), we may also write

$$
\begin{equation*}
\int_{T_{0}}^{T}\left\|\dot{x}_{n}(t)\right\|^{2} d t \leq \alpha_{n}+\sigma(\beta+1)^{2} \int_{T_{0}}^{T}\left(1+\left\|x_{n}(t)\right\|\right)^{2} d t \tag{5.11}
\end{equation*}
$$

with

$$
\alpha_{n}=\left(k^{2}(0)+3(\rho+1)^{2}\right) \int_{T_{0}}^{T} \dot{a}^{2}(t) d t+2\left[T-T_{0}+\varphi\left(T_{0}, x_{0}\right)-\varphi\left(T, x_{n}(T)\right)\right] .
$$

(B) Uniform convergence of a subsequence of $\left(x_{n}(\cdot)\right)$ to some map $(x(\cdot))$.

In order to prove this, consider the map

$$
Z_{n}(t):=\int_{T_{0}}^{t} z_{n}(s) d s
$$

As in the proof of Theorem 4.1, thanks to (5.9), via Arzela-Ascoli's theorem, we may suppose that the sequence $\left(Z_{n}(\cdot)\right)$ converges uniformly in $\mathcal{C}_{H}(I)$ to some $\operatorname{map} Z(\cdot): I \rightarrow H$. Now, let us set

$$
X_{n}(t):=x_{n}(t)+Z_{n}(t) .
$$

We aim at proving that $\left(X_{n}(\cdot)\right)$ is a Cauchy sequence in $\left(\mathcal{C}_{H}(I),\|\cdot\|_{\infty}\right)$. The maps $X_{n}(\cdot)$ are clearly absolutely continuous and for any fixed $p, q \in \mathbb{N}$, and for almost all $t \in\left[T_{0}, T\right]$, one has

$$
\begin{aligned}
\frac{1}{2} \frac{d}{d t} \| X_{p}(t) & -X_{q}(t) \|^{2}=\left\langle\dot{X}_{p}(t)-\dot{X}_{q}(t), X_{p}(t)-X_{q}(t)\right\rangle \\
& =\left\langle\dot{X}_{p}(t)-\dot{X}_{q}(t), x_{p}(t)-x_{q}(t)\right\rangle+\left\langle\dot{X}_{p}(t)-\dot{X}_{q}(t), Z_{p}(t)-Z_{q}(t)\right\rangle .
\end{aligned}
$$

By definition, one has

$$
\begin{aligned}
& -\dot{X}_{p}(t)=-\dot{x}_{p}(t)-z_{p}(t) \in \partial \varphi\left(t, x_{p}(t)\right), \\
& -\dot{X}_{q}(t)=-\dot{x}_{q}(t)-z_{q}(t) \in \partial \varphi\left(t, x_{q}(t)\right),
\end{aligned}
$$

and the monotonicity property of $\partial \varphi(t, \cdot)$ entails that

$$
\left\langle\dot{X}_{p}(t)-\dot{X}_{q}(t), x_{p}(t)-x_{q}(t)\right\rangle \leq 0 .
$$

Therefore, one has

$$
\frac{1}{2} \frac{d}{d t}\left\|X_{p}(t)-X_{q}(t)\right\|^{2} \leq\left\|\dot{X}_{p}(t)-\dot{X}_{q}(t)\right\|\left\|Z_{p}(t)-Z_{q}(t)\right\| .
$$

Now, we deduce from (5.10) that the sequence $\left(\dot{x}_{n}\right)$ is bounded in $L_{H}^{2}(I)$ and since via (5.9)

$$
\sup _{n \in \mathbb{N}}\left\|\dot{Z}_{n}(\cdot)\right\|_{L_{H}^{2}(I)}^{2} \leq\left(T-T_{0}\right)\left(M_{2}+1\right)^{2}(\beta+1)^{2}<+\infty
$$

we conclude that $A:=\sup _{n \in \mathbb{N}}\left\|\dot{X}_{n}(\cdot)\right\|_{L_{H}^{2}(I)}<+\infty$. The uniform convergence of the sequence $\left(Z_{n}\right)$ assures us that

$$
\int_{T_{0}}^{T}\left\|Z_{p}(t)-Z_{q}(t)\right\| d t \rightarrow 0
$$

when $p, q \rightarrow \infty$. This, along with the fact that $\left\|X_{p}\left(T_{0}\right)-X_{q}\left(T_{0}\right)\right\|=0$, entails, via Lemma 2.1,

$$
\lim _{p, q \rightarrow \infty}\left\|X_{p}(\cdot)-X_{q}(\cdot)\right\|_{\infty}=0
$$

Then, the uniform Cauchy's criterion guarantees that the sequence $\left(X_{n}(\cdot)\right)$ converges uniformly on $I$ to some map $X(\cdot) \in \mathcal{C}_{H}(I)$. So, the sequence $\left(x_{n}\right)=$ $\left(X_{n}-Z_{n}\right)$ converges uniformly on $I$ to some continuous map $x(\cdot) \in \mathcal{C}_{H}(I)$, with $x\left(T_{0}\right)=x_{0}$, that is,

$$
\begin{equation*}
x_{n}(\cdot) \rightarrow x(\cdot) \quad \text { strongly in } L_{H}^{2}(I) \tag{5.12}
\end{equation*}
$$

By (5.10) the sequence $\left(\dot{x}_{n}\right)$ is bounded in $L_{H}^{\infty}(I)$ and hence also in $L_{H}^{2}(I)$. We may then, extract a subsequence converging weakly in $L_{H}^{2}(I)$ to some map $v(\cdot)$. The equality

$$
x_{n}(t)=x_{n}\left(T_{0}\right)+\int_{T_{0}}^{t} \dot{x}_{n}(s) d s \quad \text { for all } t \in I
$$

then yields,

$$
\begin{equation*}
x(t)=x\left(T_{0}\right)+\int_{T_{0}}^{t} v(s) d s \quad \text { for all } t \in I \tag{5.13}
\end{equation*}
$$

and hence the map $x(\cdot)$ is absolutely continuous on $I$ with $\dot{x}(\cdot)=v(\cdot)$ for almost all $t \in I$ and

$$
\begin{equation*}
\dot{x}_{n}(\cdot) \rightarrow \dot{x}(\cdot) \quad \text { weakly in } L_{H}^{2}(I) . \tag{5.14}
\end{equation*}
$$

Due to (5.9), we may also suppose that, for some map $z(\cdot) \in L_{H}^{2}(I)$, one has

$$
\begin{equation*}
z_{n}(\cdot) \rightarrow z(\cdot) \quad \text { weakly in } L_{H}^{2}(I) \tag{5.15}
\end{equation*}
$$

(C) Now, we proceed to prove that $x(\cdot)$ is a solution of $\left(\mathcal{P}_{2}\right)$.

Taking (5.12), (5.14) and (5.15) into account, as in the proof of Theorem 4.1, we have, via the closure property of the subdifferential operator $\partial \varphi(t, \cdot)$, for almost all $t \in I$ the required inclusion, that is,

$$
\begin{equation*}
\dot{x}(t)+z(t) \in-\partial \varphi(t, x(t)) \quad \text { for a.e. } t \in I \text {. } \tag{5.16}
\end{equation*}
$$

It remains to prove that $z(t) \in F(t, x(t))$ for almost every $t \in I$. Due to (5.15), by Mazur's lemma, there exists a sequence $\left(\zeta_{n}(\cdot)\right)$ in $L_{H}^{1}(I)$ such that

$$
\begin{equation*}
\zeta_{n}(\cdot) \in \operatorname{co}\left\{z_{k}(\cdot): k \geq n\right\} \quad \text { for all } n \geq 1 \tag{5.17}
\end{equation*}
$$

which converges strongly in $L_{H}^{1}(I)$ to $z(\cdot)$. Thus, extracting a subsequence, we may suppose that $\zeta_{n}(t) \rightarrow z(t)$ for almost every $t \in I$. This, along with (5.17), implies that, for some negligible subset $N_{1} \subset I$,

$$
\begin{equation*}
z(t) \in \bigcap_{n} \overline{\operatorname{co}}\left\{z_{k}(t): k \geq n\right\} \quad \text { for all } t \in I \backslash N_{1} . \tag{5.18}
\end{equation*}
$$

Taking (5.7) into account, we may also suppose that, for all $n \geq 1$ and for all $t \in I \backslash N_{1}$,

$$
\begin{equation*}
z_{n}(t) \in \widetilde{F}_{n}\left(t, x_{n}(t)\right) . \tag{5.19}
\end{equation*}
$$

Consider the $\lambda$-negligible subset $N:=\left(I \backslash \bigcup I_{n}\right) \cup N_{0} \cup N_{1}$. We are going to prove that $z(t) \in F(t, x(t))$ for all $t \in I \backslash N$. Fix any $\tau \in I \backslash N$. From (5.18) and (5.19), it follows that, for any $\xi \in H$,

$$
\begin{equation*}
\langle\xi, z(\tau)\rangle \leq \limsup _{n} \sigma\left(\widetilde{F}_{n}\left(\tau, x_{n}(\tau)\right), \xi\right) \tag{5.20}
\end{equation*}
$$

On the other hand, by definition of $N$, there exists an integer $n(\tau)$ such that $\tau \in I_{n(\tau)} \backslash N_{0}$ and, $\left(I_{n}\right)$ being increasing, one has $\tau \in I_{n}$ for all $n \geq n(\tau)$. Consequently, for all $n \geq n(\tau)$,

$$
\begin{equation*}
\widetilde{F}_{n}\left(\tau, x_{n}(\tau)\right)=\widetilde{F}\left(\tau, x_{n}(\tau)\right) \subset \widehat{F}\left(\tau, x_{n}(\tau)\right) \tag{5.21}
\end{equation*}
$$

the inclusion coming from (5.6). Note that, by (5.10), and taking (5.4) into account, one has, for all $n \geq 1$ and for almost all $t \in I,\left\|x_{n}(t)\right\| \leq M_{2}$, and hence, thanks to (5.5), for all $n \geq 1$,

$$
\begin{equation*}
\widehat{F}\left(\tau, x_{n}(\tau)\right)=F\left(\tau, x_{n}(\tau)\right) \tag{5.22}
\end{equation*}
$$

Therefore, due to (5.20)-(5.22) and the fact that $F(\tau, \cdot)$ is scalarly upper semicontinuous, we have

$$
\langle\xi, z(\tau)\rangle \leq \sigma(F(\tau, x(\tau)), \xi)
$$

This being true for any $\xi \in H$, and $F(\tau, x(\tau))$ being closed and convex, it results that $z(\tau) \in F(\tau, x(\tau))$. Since the latter is satisfied for any $\tau \in I \backslash N$, one has

$$
z(t) \in F(\tau, x(t)) \quad \text { for a.e. } t \in I
$$

This, along with (5.16) and the fact that $x\left(T_{0}\right)=\lim _{n} x_{n}\left(T_{0}\right)=x_{0}$, proves that $x(\cdot)$ is a solution of $\left(\mathcal{P}_{2}\right)$. Finally, taking the superior limit on $n$ in (5.11), as in the proof of Theorem 4.1, we get the required inequality.

Actually, we have the following more general result. Here, the growth condition involves an $L_{\mathbb{R}}^{1}(I)$ function instead of a constant.

Theorem 5.2. Under assumptions of Theorem 4.1 on $H$ and $\varphi$, let $F: I \times$ $H \rightrightarrows H$ be a set-valued mapping with nonempty convex compact values such that
(a) for any $x \in H, F(\cdot, x)$ has a $\lambda$-measurable selection;
(b) for all $t \in I, F(t, \cdot)$ is scalarly upper semicontinuous on $H$;
(c) for some compact subset $K \subset \mathbb{B}$ and for some non-negative function $\beta(\cdot) \in L_{\mathbb{R}}^{1}(I)$, for all $(t, x) \in I \times H$, one has

$$
F(t, x) \subset \beta(t)(1+\|x\|) K .
$$

Then, for any $x_{0} \in \operatorname{dom} \varphi\left(T_{0}, \cdot\right)$ the following problem

$$
\left\{\begin{array}{l}
-\dot{x}(t) \in \partial \varphi(t, x(t))+F(t, x(t)) \quad \text { for a.e. } t \in I  \tag{3}\\
x\left(T_{0}\right)=x_{0}
\end{array}\right.
$$

has at least one absolutely continuous solution. More precisely, there exist an absolutely continuous map $x(\cdot): I \rightarrow H$ and an integrable map $z(\cdot): I \rightarrow H$ such that $x\left(T_{0}\right)=x_{0}, x(t) \in \operatorname{dom} \varphi(t, x(t))$ for all $t \in I$, and for almost all $t \in I, z(t) \in F(t, x(t))$ and $-\dot{x}(t)-z(t) \in \partial \varphi(t, x(t))$ and

$$
z(t) \in 2(\beta(t)+1)(\|x(t)\|+1) \overline{\operatorname{co}}(K \cup\{0\}) .
$$

Proof. We suppose without loss of generality, that $K$ is convex and contains 0 . If not so, we may replace $K$ by $\overline{c o}(K \cup\{0\})$. Suppose further,

$$
\begin{equation*}
\int_{T_{0}}^{T}(\beta(s)+1) d s<\frac{1}{2}\left(T-T_{0}\right)^{1 / 2} m^{1 / 2} \tag{5.23}
\end{equation*}
$$

(A) Following an idea from Deimling [16], let us set $\widehat{T}:=\int_{T_{0}}^{T}(\beta(s)+1) d s$ and let us define an absolutely continuous function $\widehat{\beta}(\cdot):\left[T_{0}, T\right] \rightarrow[0, \widehat{T}]$ by

$$
\begin{equation*}
\widehat{\beta}(t):=\int_{T_{0}}^{t}(\beta(s)+1) d s \tag{5.24}
\end{equation*}
$$

Thanks to the fact that $\beta(t)+1>0$ for almost all $t \in I$, the absolutely continuous function $\widehat{\beta}(\cdot)$ is increasing and hence has a continuous inverse function $\widehat{\beta}^{-1}(\cdot):[0, \widehat{T}] \rightarrow\left[T_{0}, T\right]$. Notice that $\widehat{\beta}^{-1}(\cdot)$ is Lipschitz on $[0, \widehat{T}]$. Indeed, for $\widehat{t}, \widehat{s} \in[0, \widehat{T}]$ with $\widehat{s} \leq \widehat{t}$ there exist $t, s \in\left[T_{0}, T\right]$ with $s \leq t$ such that $\widehat{t}=\widehat{\beta}(t)$ and $\widehat{s}=\widehat{\beta}(s)$, and then, using (5.24), one has

$$
\widehat{\beta}^{-1}(\widehat{t})-\widehat{\beta}^{-1}(\widehat{s})=t-s \leq \int_{s}^{t}(\beta(\tau)+1) d \tau=\widehat{\beta}(t)-\widehat{\beta}(s)=\widehat{t}-\widehat{s}
$$

This yields that, for any $\widehat{t}, \widehat{s} \in[0, \widehat{T}], \widehat{\beta}^{-1}(\widehat{t})-\widehat{\beta}^{-1}(\widehat{s}) \leq \widehat{t}-\widehat{s}$, which means that $\widehat{\beta}^{-1}(\cdot)$ is Lipschitz on $[0, \widehat{T}]$.

Now, consider the set-valued map $\widehat{F}:[0, \widehat{T}] \times H \rightrightarrows H$ defined by

$$
\begin{equation*}
\widehat{F}(t, x):=\frac{1}{\beta\left(\widehat{\beta}^{-1}(t)\right)+1} F\left(\widehat{\beta}^{-1}(t), x\right) . \tag{5.25}
\end{equation*}
$$

Clearly, like $F$, the set-valued map $\widehat{F}$ satisfies the conditions (a) and (b) of Theorem 5.1 and, by (c), for all $(t, x) \in[0, \widehat{T}] \times H$,

$$
\begin{equation*}
\widehat{F}(t, x) \subset(1+\|x\|) K \tag{5.26}
\end{equation*}
$$

Consider also the single valued map $\widehat{\varphi}:[0, \widehat{T}] \times H \rightarrow[0,+\infty]$ defined by

$$
\widehat{\varphi}(t, x):=\varphi\left(\widehat{\beta}^{-1}(t), x\right) .
$$

Obviously, $\widehat{\varphi}$ satisfies assumptions $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{2}\right)$. Therefore, from the previous result, there exist an absolutely continuous map $X(\cdot):[0, \widehat{T}] \rightarrow H$ and an integrable map $\widehat{z}(\cdot):[0, \widehat{T}] \rightarrow H$ such that $X(0)=x_{0}$ and, for almost all $t \in[0, \widehat{T}]$,

$$
\left\{\begin{array}{l}
\widehat{z}(t) \in \widehat{F}(t, X(t))  \tag{5.27}\\
-\dot{X}(t) \in \partial \widehat{\varphi}(t, X(t))+\widehat{z}(t)
\end{array}\right.
$$

By inequality (5.3), along with (5.26), one has

$$
\begin{equation*}
\int_{0}^{\widehat{T}}\|\dot{X}(t)\|^{2} d t \leq \alpha+4 \sigma \int_{0}^{\widehat{T}}(1+\|X(t)\|)^{2} d t \tag{5.28}
\end{equation*}
$$

Then

$$
\begin{aligned}
\int_{0}^{\widehat{T}}\|\dot{X}(t)\|^{2} d t & \leq \alpha+4 \sigma\left(1+\|X(\cdot)\|_{\infty}\right)^{2} \int_{0}^{\widehat{T}} d t \\
& \leq \alpha+4 \sigma\left(1+\|X(\cdot)\|_{\infty}\right)^{2} \widehat{T} \leq \alpha+8 \sigma\left(1+\|X(\cdot)\|_{\infty}^{2}\right) \widehat{T}
\end{aligned}
$$

where $\|\cdot\|_{\infty}$ denotes the supremum norm over the interval $[0, \widehat{T}]$.
Using the Cauchy-Schwarz inequality, one has, for all $s \in[0, \widehat{T}]$,

$$
\begin{aligned}
\|X(s)-X(0)\|^{2} & \leq s\left(\int_{0}^{s}\|\dot{X}(t)\|^{2} d t\right) \leq \widehat{T}\left(\alpha+8 \sigma\left(1+\|X(\cdot)\|_{\infty}^{2}\right) \widehat{T}\right) \\
\|X(s)\|^{2} & \leq 2\left\|x_{0}\right\|^{2}+2\left\|X(s)-x_{0}\right\|^{2} \\
& \leq 2\left\|x_{0}\right\|^{2}+2 \widehat{T}\left(\alpha+8 \sigma\left(1+\|X(\cdot)\|_{\infty}^{2}\right) \widehat{T}\right)
\end{aligned}
$$

Then $\left(1-16 \sigma \widehat{T}^{2}\right)\|X(\cdot)\|_{\infty}^{2} \leq 2\left(\left\|x_{0}\right\|^{2}+\widehat{T}(\alpha+8 \sigma \widehat{T})\right)$. Therefore, taking (5.23) into account, that is, $16 \sigma \widehat{T}^{2}<1$, one has $\|X(\cdot)\|_{\infty} \leq M_{3}$, where

$$
M_{3}:=\left(\frac{2\left(\left\|x_{0}\right\|^{2}+\widehat{T}(\alpha+8 \sigma \widehat{T})\right)}{1-16 \sigma \widehat{T}^{2}}\right)^{1 / 2} .
$$

Consequently, inclusion (5.1) of Theorem 5.1 yields $(\beta=1), \widehat{z}(t) \in 2\left(1+M_{3}\right) K$.
(B) Let us prove that the absolutely continuous map $x(\cdot):\left[T_{0}, T\right] \rightarrow H$ defined, for any $t \in\left[T_{0}, T\right]$, by $x(t)=X(\widehat{\beta}(t))$ is a solution of $\left(\mathcal{P}_{3}\right)$.

Let us set $I_{1}:=\left\{t \in\left[T_{0}, T\right]: \widehat{\beta}(t)\right.$ exists $\}$ and $I_{2}:=\{\widehat{t} \in[0, \widehat{T}]: \dot{X}(\widehat{t})$ exists and (5.27) holds at $\widehat{t}\}$. Consider the subsets $N_{1}:=\left[T_{0}, T\right] \backslash I_{1}$ and $\widehat{N}_{2}:=[0, \widehat{T}] \backslash I_{2}$, which are $\lambda$-negligible, and put

$$
N_{2}:=\left\{t \in\left[T_{0}, T\right]: \widehat{\beta}(t) \in \widehat{N}_{2}\right\}=\widehat{\beta}^{-1}\left(\widehat{N}_{2}\right) .
$$

As $\widehat{\beta}^{-1}(\cdot)$ is Lipschitz on $[0, \widehat{T}]$, the set $N_{2}$ is also $\lambda$-negligible. So, $N:=N_{1} \cup N_{2}$ is $\lambda$-negligible and, for any $t \in\left[T_{0}, T\right] \backslash N$,

$$
\begin{equation*}
\dot{x}(t)=\dot{\widehat{\beta}}(t) \dot{X}(\widehat{\beta}(t))=(\beta(t)+1) \dot{X}(\widehat{\beta}(t)) . \tag{5.29}
\end{equation*}
$$

The definitions of the negligible sets above, along with (5.25) and (5.27), entail that, for all $t \in\left[T_{0}, T\right] \backslash N$,

$$
\left\{\begin{array}{l}
\widehat{z}(\widehat{\beta}(t)) \in \frac{1}{\beta(t)+1} F(t, x(t)), \\
-\dot{X}(\widehat{\beta}(t)) \in \partial \varphi(t, x(t))+\widehat{z}(\widehat{\beta}(t)) .
\end{array}\right.
$$

Hence, defining $z(\cdot):\left[T_{0}, T\right] \rightarrow H$ by $z(t):=(\beta(t)+1) \widehat{z}(\widehat{\beta}(t))$, we obtain, by (5.29), for any $t \in\left[T_{0}, T\right] \backslash N$, and

$$
\left\{\begin{array}{l}
z(t) \in F(t, x(t)), \\
-\dot{x}(t) \in \partial \varphi(t, x(t))+z(t),
\end{array}\right.
$$

which ends the proof.

Remark 5.3. Under conditions of Theorem 5.1 or Theorem 5.2, estimates and inclusions in Proposition 4.2 hold true.

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