# A GENERALIZATION OF NADLER'S FIXED POINT THEOREM AND ITS APPLICATION TO NONCONVEX INTEGRAL INCLUSIONS 

Hemant Kumar Pathak - Naseer Shahzad


#### Abstract

In this paper, a generalization of Nadler's fixed point theorem is presented. In the sequel, we consider a nonconvex integral inclusion and prove a Filippov type existence theorem by using an appropriate norm on the space of selection of the multifunction and a $\mathrm{H}^{+}$-type contraction for set-valued maps.


## 1. Introduction

Dynamical systems described by differential equations with continuous righthand sides was the areas of vigorous steady in the later half of the 20th century in applied mathematics, in particular, in the study of viscous fluid motion in a porous medium, propagation of light in an optically non-homogeneous medium, determining the shape of a solid of revolution moving in a flow of gas with least resistance, etc. Euler's equation plays a key role in dealing with the existence of the solution of such problems. On the other hand, Filipopov [6] has developed a solution concept for differential equations with a discontinuous right-hand side. In practice, such dynamical systems do arise and require analysis. Examples of such systems are mechanical systems with Coulomb friction modeled as

[^0]a force proportional to the sign of a velocity, systems whose control laws have discontinuities.

In a parallel development, the study of fixed points for multivalued contraction maps using the Hausdoff metric was initiated by Nadler [13]. Later, an interesting and rich fixed point theory for such maps has been developed, see, for instance, the work of Feng and Liu [5], Kaneko [7], Klim and Wardowski [8], Lim [10], Lami Dozo [11], Mizoguchi and Takahashi [12], Pathak and Shahzad [14], Reich [16], [17], Suzuki [18], and many others. For details, see [15].

## 2. Preliminaries and definitions

Let $(X, d)$ be a metric space. Let $\mathrm{CB}(X)$ and $\mathrm{C}(X)$ denote the collection of all nonempty closed and bounded subsets of $X$ and the collection of all compact subsets of $X$, respectively.

For $A, B \in \mathrm{CB}(X)$, let

$$
H(A, B)=\max \{\rho(A, B), \rho(B, A)\}, \quad H^{+}(A, B)=\frac{1}{2}\{\rho(A, B)+\rho(B, A)\}
$$

where $\rho(A, B)=\sup _{x \in A} d(x, B)$ and $d(x, B)=\inf _{y \in B} d(x, y)$. It is well known that $H$ is a metric on $\mathrm{CB}(X)$. Such a map $H$ is called Hausdorff metric induced by $d$. In Proposition 2.1 below we show that $H^{+}$is also a metric on $\mathrm{CB}(X)$. For $A \subset X$, $\bar{A}$ denotes the closure of $A$.

A set-valued mapping $T: X \rightarrow \mathrm{CB}(X)$ is said to be a
(i) multi-valued contraction mapping if there exists a fixed real number $L$, $0<L<1$ such that

$$
\begin{equation*}
H(T x, T y) \leq L d(x, y) \tag{2.1}
\end{equation*}
$$

(ii) multi-valued nonexpansive mapping if

$$
\begin{equation*}
H(T x, T y) \leq d(x, y) \quad \text { for all } x, y \in X \tag{2.2}
\end{equation*}
$$

Proposition 2.1. $H^{+}$is a metric on $\mathrm{CB}(X)$.
Proof. Let $A, B \in \mathrm{CB}(X)$ such that $H^{+}(A, B)=0$. Then this is equivalent to $\rho(A, B)=0$ and $\rho(B, A)=0$; i.e. $\inf _{y \in B} d(x, y)=0$ for any $x \in A$ and $\inf _{x \in A} d(y, x)=0$ for any $y \in B$. Therefore, these are equivalent to $x \in \bar{B}=B$ for any $x \in A$, and $y \in \bar{A}=A$ for any $y \in B$. It follows that $A \subset B$ and $B \subset A$. Hence $A=B$.

The symmetry of the function $H^{+}$follows directly from the definition.
To show the triangle inequality, let $A, B, C \in \mathrm{CB}(X)$. Then for any $(x, y, z) \in$ $A \times B \times C$, we have

$$
d(x, z) \leq d(x, y)+d(y, z)
$$

whence

$$
\inf _{z \in C} d(x, z) \leq d(x, y)+\inf _{z \in C} d(y, z) \leq d(x, y)+\rho(B, C)
$$

Since the above inequality holds for any $y \in B$, we get

$$
\inf _{z \in C} d(x, z) \leq \inf _{y \in B} d(x, y)+\rho(B, C) \leq \rho(A, B)+\rho(B, C)
$$

Hence

$$
\begin{equation*}
\rho(A, C) \leq \rho(A, B)+\rho(B, C) \tag{2.3}
\end{equation*}
$$

Interchanging the roles of $A$ and $C$, we get

$$
\begin{equation*}
\rho(C, A) \leq \rho(C, B)+\rho(B, A) \tag{2.4}
\end{equation*}
$$

Adding (2.3) and (2.4), and then dividing by 2 , we get

$$
\begin{equation*}
H^{+}(A, C) \leq H^{+}(A, B)+H^{+}(B, C) \tag{2.5}
\end{equation*}
$$

Notice that the two metrics $H$ and $H^{+}$are equivalent (see [9]) since

$$
\frac{1}{2} H(A, B) \leq H^{+}(A, B) \leq H(A, B)
$$

It is routine to prove the following:
Proposition 2.2. Let $(X,\|\cdot\|$ ) be a normed linear space. For any $\lambda$ (real or complex), $A, B \in \mathrm{CB}(X)$
(i) $H^{+}(\lambda A, \lambda B)=|\lambda| H^{+}(A, B)$,
(ii) $H^{+}(A+a, B+a)=H^{+}(A, B)$.

In a classical approach one can easily prove Theorems 2.3 and 2.5 stated below (see, also Banaś and Goebel [1]).

Theorem 2.3. If $a, b \in X$ and $A, B \in \mathrm{CB}(X)$, then the relations:
(1) $d(a, b)=H^{+}(\{a\},\{b\})$,
(2) $A \subset \bar{S}\left(B ; r_{1}\right), B \subset \bar{S}\left(A ; r_{2}\right) \Rightarrow H^{+}(A, B) \leq r$ where $r=\left(r_{1}+r_{2}\right) / 2$, and
(3) $H^{+}(A, B)<r \Rightarrow \exists r_{1}, r_{2}>0$ such that $\left(r_{1}+r_{2}\right) / 2=r$ and $A \subset$ $S\left(B ; r_{1}\right), B \subset S\left(A ; r_{2}\right)$ hold.

Proof. The relation (1) follows immediately from the definition of the function $H^{+}$.

To prove relation (2), from the inclusions $A \subset \bar{S}\left(B ; r_{1}\right), B \subset \bar{S}\left(A ; r_{2}\right)$, it follows that

$$
\forall x \in A \exists y_{x} \in B \quad \text { such that } \quad d\left(x, y_{x}\right) \leq r_{1}
$$

and

$$
\forall y \in B \exists x_{y} \in A \quad \text { such that } \quad d\left(x_{y}, y\right) \leq r_{2}
$$

From here it follows that

$$
\inf _{y \in B} d(x, y) \leq r_{1} \quad \text { for every } x \in A \quad \text { and } \quad \inf _{x \in A} d(x, y) \leq r_{2} \quad \text { for every } y \in B
$$

Hence

$$
\sup _{x \in A}\left(\inf _{y \in B} d(x, y)\right) \leq r_{1} \quad \text { and } \quad \sup _{y \in B}\left(\inf _{x \in A} d(x, y)\right) \leq r_{2}
$$

Therefore $H^{+}(A, B) \leq r$ where $r=\left(r_{1}+r_{2}\right) / 2$.
To prove relation (3), let $H^{+}(A, B)=k<r$. Then there exist $k_{1}, k_{2}>0$ such that $k=\left(k_{1}+k_{2}\right) / 2$ and

$$
\sup _{x \in A}\left(\inf _{y \in B} d(x, y)\right)=k_{1}, \quad \sup _{y \in B}\left(\inf _{x \in A} d(x, y)\right)=k_{2} .
$$

As $0<k<r$, it follows that there exist $r_{1}, r_{2}>0$ such that $k_{1}<r_{1}, k_{2}<r_{2}$ and $r=\left(r_{1}+r_{2}\right) / 2$. Then from the above inequalities it follows that

$$
\inf _{y \in B} d(x, y) \leq k_{1}<r_{1} \quad \text { for every } x \in A
$$

and

$$
\left.\inf _{x \in A} d(x, y)\right) \leq k_{2}<r_{2} \quad \text { for every } y \in B
$$

Then, for any $x \in A$ there exists $y_{x} \in B$ such that

$$
d\left(x, y_{x}\right)<\inf _{y \in B} d(x, y)+r_{1}-k_{1} \leq r_{1} .
$$

and, for any $y \in B$, there exists $x_{y} \in A$ such that

$$
d\left(x_{y}, y\right)<\inf _{x \in A} d(x, y)+r_{2}-k_{2} \leq r_{2}
$$

Hence, for any $x \in A$ and $y \in B$ it follows that

$$
x \in \bigcup_{y \in B} S\left(y ; r_{1}\right) \quad \text { and } \quad y \in \bigcup_{x \in A} S\left(x ; r_{2}\right)
$$

that is

$$
A \subset S\left(B ; r_{1}\right) \quad \text { and } \quad B \subset S\left(A ; r_{2}\right)
$$

Remark 2.4. From the relations (2) and (3) it follows immediately that the relations:
$\left(2^{\prime}\right) A \subset S\left(B ; r_{1}\right), B \subset S\left(A ; r_{2}\right) \Rightarrow H^{+}(A, B) \leq r$ where $r=\left(r_{1}+r_{2}\right) / 2$, and
(3') $H^{+}(A, B)<r \Rightarrow \exists r_{1}, r_{2}>0$ such that $\left(r_{1}+r_{2}\right) / 2=r$ and $A \subset$ $\bar{S}\left(B ; r_{1}\right), B \subset \bar{S}\left(A ; r_{2}\right)$ hold.

Theorem 2.5. If $A, B \in \mathrm{CB}(X)$, then the equalities:
(4) $H^{+}(A, B)=\inf \left\{r>0: A \subset S\left(B ; r_{1}\right), B \subset S\left(A ; r_{2}\right), r=\left(r_{1}+r_{2}\right) / 2\right\}$,
$\left(4^{\prime}\right) H^{+}(A, B)=\inf \left\{r>0: A \subset \bar{S}\left(B ; r_{1}\right), A \subset \bar{S}\left(B ; r_{2}\right), r=\left(r_{1}+r_{2}\right) / 2\right\}$
hold.
Proof. From the relation ( $2^{\prime}$ ) it follows that

$$
H^{+}(A, B) \leq \inf \left\{r>0: A \subset S\left(B ; r_{1}\right), A \subset S\left(B ; r_{2}\right), r=\left(r_{1}+r_{2}\right) / 2\right\}
$$

To prove the opposite inequality, let $H^{+}(A, B)=k$ and let $t>0$. Then $H^{+}(A, B)<k+t$. From (3) it follows that there exist $t_{1}, t_{2}>0$ with $\left(t_{1}+t_{2}\right) / 2$ $=t$ such that $A \subset S\left(B ; k+t_{1}\right)$ and $B \subset S\left(A ; k+t_{2}\right)$. Hence

$$
\begin{aligned}
\left\{r>0: A \subset S\left(B ; r_{1}\right)\right. & \left., B \subset S\left(A ; r_{2}\right)\right\} \\
& \supset\left\{k+t: t>0, A \subset S\left(B ; k+t_{1}\right), B \subset S\left(A ; k+t_{2}\right)\right\}
\end{aligned}
$$

From this inclusion relation it follows that

$$
\inf \left\{r>0: A \subset S\left(B ; r_{1}\right), B \subset S\left(A ; r_{2}\right)\right\} \leq \inf \{k+t: t>0\}=k=H^{+}(A, B)
$$

In conclusion we have

$$
H^{+}(A, B)=\inf \left\{r>0: A \subset S\left(B ; r_{1}\right), B \subset S\left(A ; r_{2}\right), r=\left(r_{1}+r_{2}\right) / 2\right\}
$$

Theorem 2.6. If the metric space $(X, d)$ is complete, then so is $(\mathrm{CB}(X)$, $\left.H^{+}\right)$and also $\mathrm{C}(X)$ is a closed subspace of $\left(\mathrm{CB}(X), H^{+}\right)$.

Proof. Let $(X, d)$ be a complete metric space and let $\left\{A_{n}\right\}_{n \in \mathbb{N}}$ be a Cauchy sequence in $\operatorname{CB}(X)$. We claim that the sequence $\left\{A_{n}\right\}_{n \in \mathbb{N}}$ is convergent to the set $B=L s A_{n}=\{x \in X: \forall \varepsilon>0, \forall m \in \mathbb{N} \exists n \in \mathbb{N}, n \geq m$ such that $\left.S(x ; \varepsilon) \cap A_{n} \neq \emptyset\right\}$.

Since the sequence $\left\{A_{n}\right\}_{n \in \mathbb{N}}$ is Cauchy, for any $\varepsilon>0$ there exists $m(\varepsilon) \in \mathbb{N}$ such that

$$
H^{+}\left(A_{n}, A_{m(\varepsilon)}\right)<\varepsilon \quad \text { for any } n \in \mathbb{N}, n \geq m(\varepsilon)
$$

Hence, by relation (4), it follows that there exist $\varepsilon_{1}, \varepsilon_{2}>0$ with $\left(\varepsilon_{1}+\varepsilon_{2}\right) / 2=\varepsilon$ and $m\left(\varepsilon_{1}\right), m\left(\varepsilon_{2}\right) \in \mathbb{N}$ such that $\min \left\{m\left(\varepsilon_{1}\right), m\left(\varepsilon_{2}\right)\right\} \geq m(\varepsilon), A_{n} \subset S\left(A_{m\left(\varepsilon_{1}\right)} ; \varepsilon_{1}\right)$ for any $n \in \mathbb{N}, n \geq m\left(\varepsilon_{1}\right)$ and $A_{m\left(\varepsilon_{2}\right)} \subset S\left(A_{n} ; \varepsilon_{2}\right)$ for any $n \in \mathbb{N}, n \geq m\left(\varepsilon_{2}\right)$.

From the properties of upper topological limit $L s$ it follows that $B \subset \bigcup_{k \geq n} A_{k}$ for any $n \in \mathbb{N}$. Therefore $B \subset \bar{S}\left(A_{m\left(\varepsilon_{1}\right)} ; \varepsilon_{1}\right)$, whence the relation:

$$
\begin{equation*}
B \subset \bar{S}\left(A_{m\left(\varepsilon_{1}\right)} ; 4 \varepsilon_{1}\right) \tag{2.6}
\end{equation*}
$$

holds. On the other hand, taking $\bar{\varepsilon}_{k}=\varepsilon_{1} / 2^{k}, k \in \mathbb{N}$, it follows that there exists $n_{k}=m\left(\bar{\varepsilon}_{k}\right) \in \mathbb{N}$ such that

$$
H^{+}\left(A_{n}, A_{n_{k}}\right)<\bar{\varepsilon}_{k}, \quad \text { for all } n \geq n_{k}
$$

Next, we choose $n_{k}$ such that the sequence $\left\{n_{k}\right\}_{k \in \mathbb{N}}$ to be strictly increasing. Let $p \in A_{n_{0}}=A_{m\left(\varepsilon_{1}\right)}$ arbitrarily, and let there be the sequence $\left\{p_{n_{k}}\right\}_{k \in \mathbb{N}}$ such that $p_{n_{0}}=p$ and $p_{n_{k}} \in A_{n_{k}}$ with the property that $d\left(p_{n_{k}}, p_{n_{k-1}}\right)<\varepsilon_{1} / 2^{k-2}$. It follows that the sequence $\left\{p_{n_{k}}\right\}_{k \in \mathbb{N}}$ is a Cauchy sequence in the complete metric space $(X, d)$. Hence it is convergent to a point $l \in X$.

Since $d\left(p_{n_{k}}, p_{n_{0}}\right)<4 \varepsilon_{1}$, it follows that $d(l, p) \leq 4 \varepsilon_{1}$. Therefore $\inf _{y \in B} d(p, y) \leq$ $4 \varepsilon_{1}$; that is, $p \in \bar{S}\left(B ; 4 \varepsilon_{1}\right)$, which implies that:

$$
\begin{equation*}
A_{n_{0}} \subset \bar{S}\left(B ; 4 \varepsilon_{1}\right) \tag{2.7}
\end{equation*}
$$

Keeping in view the relations (2.6) and (2.7), (3) yields $H^{+}\left(A_{n_{0}}, B\right) \leq 4 \varepsilon_{1}$. Taking into account the fact that $H^{+}$is a metric on $\operatorname{CB}(X)$, we get

$$
H^{+}\left(A_{n}, B\right) \leq H^{+}\left(A_{n}, A_{n_{0}}\right)+H^{+}\left(A_{n_{0}}, B\right)<5 \varepsilon_{1}
$$

for any $n \geq m\left(\varepsilon_{1}\right)=n_{0}$. Thus, the sequence $\left\{A_{n}\right\}_{n \in \mathbb{N}}$ converges to $B=L s A_{n}$; that is, $\left(\mathrm{CB}(X), H^{+}\right)$is a complete metric space. This proves the first assertion of our theorem.

To prove the second assertion, we just require to show that $\mathcal{C}(X)$ is a complete subspace of $\left(\mathrm{CB}(X), H^{+}\right)$. Let $\left\{A_{n}\right\}_{n \in \mathbb{N}}$ be a Cauchy sequence in $\mathcal{C}(X)$. Then, $\left\{A_{n}\right\}_{n \in \mathbb{N}}$ is a Cauchy sequence in $\mathcal{C} B(X)$. Let $A \in C B(X)$ be such that $A=$ $\lim _{n \rightarrow \infty} A_{n}$. Then for any $\varepsilon>0$ there exists $m(\varepsilon) \in \mathbb{N}$ such that

$$
H^{+}\left(A_{n}, A\right)<\frac{\varepsilon}{2} \quad \text { for all } n \geq m(\varepsilon), n \in \mathbb{N} .
$$

Hence, by relation (4), it follows that there exist $\varepsilon_{1}, \varepsilon_{2}>0$ with $\left(\varepsilon_{1}+\varepsilon_{2}\right) / 2=\varepsilon$ and $m\left(\varepsilon_{1}\right), m\left(\varepsilon_{2}\right) \in \mathbb{N}$ such that $\min \left\{m\left(\varepsilon_{1}\right), m\left(\varepsilon_{2}\right)\right\} \geq m(\varepsilon), A_{n} \subset S\left(A ; \varepsilon_{1} / 2\right)$ for any $n \in \mathbb{N}, n \geq m\left(\varepsilon_{1}\right)$ and $A \subset S\left(A_{n} ; \varepsilon_{2} / 2\right)$ for any $n \in \mathbb{N}, n \geq m\left(\varepsilon_{2}\right)$.

Suppose $n_{0} \geq m\left(\varepsilon_{2}\right)$ is a fixed natural number. Then $A \subset S\left(A_{n_{0}} ; \varepsilon_{2} / 2\right)$. Since $A_{n_{0}}$ is compact in $X$, it follows that it is totally bounded. Hence there exist $x_{i}^{\varepsilon_{2}}, i \in \overline{1, p}$ such that $A_{n_{0}} \subset \bigcup_{i=1}^{p} S\left(x_{i}^{\varepsilon_{2}} ; \varepsilon_{2} / 2\right)$, whence $A \subset \bigcup_{i=1}^{p} S\left(x_{i}^{\varepsilon_{2}} ; \varepsilon_{2}\right)$. Therefore $A \in \mathrm{C}(X)$.

In [13], S.B. Nadler proved the following result, which he announced earlier.
Theorem 2.7. Let $(X, d)$ be a complete metric space and $T: X \rightarrow \mathrm{CB}(X)$ a multi-valued contraction mapping. Then $T$ has a fixed point.

In this paper, we intend to generalize this result by weakening the multivalued contraction. Our main results are summarized in Section 3. Subsequently, in Section 4, first we introduce the concept of $H^{+}$-type nonexpansive mappings, then we extend some fixed point results of Lami Dozo [11] for $H^{+}$-type nonexpansive mappings. Finally, in Section 5, we consider a nonconvex integral inclusion and prove a Filippov type existence theorem by using an appropriate
norm on the space of selection of the multifunction and a $H^{+}$-type contraction for set-valued maps.

## 3. Main results

Now we state and prove our main result. We begin our discussion with the following definition.

Definition 3.1. Let $(X, d)$ be a complete metric space. A multi-valued $\operatorname{map} T: X \rightarrow \mathrm{CB}(X)$ is called $H^{+}$-contraction if
(1) there exists $L$ in $(0,1)$ such that

$$
H^{+}(T x, T y) \leq L d(x, y) \quad \text { for every } x, y \in X
$$

(2) for every $x$ in $X, y$ in $T(x)$ and $\varepsilon>0$, there exists $z$ in $T(y)$ such that

$$
d(y, z) \leq H^{+}(T(y), T(x))+\varepsilon
$$

Now we state and prove our main result.
Theorem 3.2. Every $H^{+}$-type multi-valued contraction mapping $T: X \rightarrow$ $\mathrm{CB}(X)$ with Lipschitz constant $L<1$ has a fixed point.

Proof. Let $\varepsilon>0$ be given. Let $x_{0} \in X$ be arbitrary. Fix an element $x_{1}$ in $T x_{0}$. From (2) it follows that we can choose $x_{2} \in T x_{1}$ such that

$$
\begin{equation*}
d\left(x_{1}, x_{2}\right) \leq H^{+}\left(T x_{0}, T x_{1}\right)+\varepsilon \tag{3.1}
\end{equation*}
$$

In general, if $x_{n}$ be chosen, then we choose $x_{n+1} \in T x_{n}$ such that

$$
\begin{equation*}
d\left(x_{n}, x_{n+1}\right) \leq H^{+}\left(T x_{n-1}, T x_{n}\right)+\varepsilon \tag{3.2}
\end{equation*}
$$

Set $\varepsilon=(1 / \sqrt{L}-1) H^{+}\left(T x_{n-1}, T x_{n}\right)$. Then from (3.2), it follows that

$$
\begin{aligned}
& d\left(x_{n}, x_{n+1}\right) \leq H^{+}\left(T x_{n-1}, T x_{n}\right)+\left(\frac{1}{\sqrt{L}}-1\right) H^{+}\left(T x_{n-1}, T x_{n}\right) \\
& \quad=\frac{1}{\sqrt{L}} H^{+}\left(T x_{n-1}, T x_{n}\right)
\end{aligned}
$$

Thus, we have

$$
\begin{equation*}
\sqrt{L} d\left(x_{n}, x_{n+1}\right) \leq H^{+}\left(T x_{n-1}, T x_{n}\right) \tag{3.3}
\end{equation*}
$$

Now, from (1) we have

$$
\sqrt{L} d\left(x_{n}, x_{n+1}\right) \leq L d\left(x_{n-1}, x_{n}\right)=(\sqrt{L})^{2} d\left(x_{n-1}, x_{n}\right)
$$

Hence, for all $n \in \mathbb{N}$ we have

$$
d\left(x_{n}, x_{n+1}\right) \leq \sqrt{L} d\left(x_{n-1}, x_{n}\right)
$$

Repeating the same argument $n$-times we get

$$
d\left(x_{n}, x_{n+1}\right) \leq L^{n / 2} d\left(x_{0}, x_{1}\right)
$$

This implies that $\left\{x_{n}\right\}$ is a Cauchy sequence. Since $X$ is complete, there exists $u \in X$ such that $\lim _{n \rightarrow \infty} x_{n}=u$.

Since

$$
\frac{1}{2}\left\{\rho\left(T x_{n}, T u\right)+\rho\left(T u, T x_{n}\right)\right\}=H^{+}\left(T x_{n}, T u\right) \leq L d\left(x_{n}, u\right)
$$

it follows that

$$
\liminf _{n \rightarrow \infty}\left\{\rho\left(T x_{n}, T u\right)+\rho\left(T u, T x_{n}\right)\right\}=0
$$

Since

$$
\liminf _{n \rightarrow \infty} \rho\left(T x_{n}, T u\right)+\liminf _{n \rightarrow \infty} \rho\left(T u, T x_{n}\right) \leq \liminf _{n \rightarrow \infty}\left\{\rho\left(T x_{n}, T u\right)+\rho\left(T u, T x_{n}\right)\right\}
$$

we have

$$
\liminf _{n \rightarrow \infty} \rho\left(T x_{n}, T u\right)+\liminf _{n \rightarrow \infty} \rho\left(T u, T x_{n}\right)=0
$$

This implies that

$$
\liminf _{n \rightarrow \infty} \rho\left(T x_{n}, T u\right)=0
$$

Since $\lim _{n \rightarrow \infty} d\left(x_{n+1}, u\right)=0$ exists, and

$$
d(u, T u) \leq \rho\left(T x_{n}, T u\right)+d\left(x_{n+1}, u\right)
$$

it follows that

$$
\begin{aligned}
d(u, T u) & \leq \liminf _{n \rightarrow \infty}\left[\rho\left(T x_{n}, T u\right)+d\left(x_{n+1}, u\right)\right] \\
& =\liminf _{n \rightarrow \infty} \rho\left(T x_{n}, T u\right)+\lim _{n \rightarrow \infty} d\left(x_{n+1}, u\right)=0
\end{aligned}
$$

This implies that $d(u, T u)=0$, and since $T u$ is closed it must be the case that $u \in T u$.

Remark 3.3. As $\max \{a, b\} \geq \frac{1}{2}\{a+b\}$ for all $a, b \geq 0$, it follows that multi-valued contraction (2.1) always implies multi-valued $\mathrm{H}^{+}$-contraction but the converse implication need not be true.

To see this, we observe the following:
Example 3.4. Let $X=\{0,1 / 4,1\}$ and $d: X \times X \rightarrow \mathbb{R}$ be a standard metric. Let $T: X \rightarrow \mathrm{CB}(X)$ be such that

$$
T(x)= \begin{cases}\{0\} & \text { for } x=0 \\ \{0,1 / 4\} & \text { for } x=1 / 4 \\ \{0,1\} & \text { for } x=1\end{cases}
$$

It is routine to check that multi-valued $H^{+}$-contraction condition (1) is satisfied for all $x, y \in X$ and for any $L \in[2 / 3,1)$. Further, we see that for every $x \in X$,
$y \in T(x)$ and $\varepsilon>0$, there exists $z \in T(y)$ such that $d(y, z) \leq H^{+}(T(y), T(x))+\varepsilon$. Indeed,
(i) if $x=0, y \in T(0)=\{0\}, \varepsilon>0$, there exists $z \in T(y)=\{0\}$ such that

$$
0=d(y, z) \leq H^{+}(T(y), T(x))+\varepsilon
$$

(iia) if $x=1 / 4, y \in T(x)=T(1 / 4)=\{0,1 / 4\}$, say $y=0, \varepsilon>0$, there exists $z \in T(y)=\{0\}$ such that

$$
0=d(y, z)<\frac{1}{8}+\varepsilon=H^{+}(T(y), T(x))+\varepsilon
$$

(iib) if $x=1 / 4, y \in T(x)=T(1 / 4)=\{0,1 / 4\}$, say $y=1 / 4, \varepsilon>0$, there exists $z(=1 / 4) \in T(y)=\{0,1 / 4\}$ such that

$$
0=d(y, z)<0+\varepsilon=H^{+}(T(y), T(x))+\varepsilon
$$

(iiia) if $x=1, y \in T(x)=T(1)=\{0,1\}$, say $y=0, \varepsilon>0$, there exists $z \in T(y)=\{0\}$ such that

$$
0=d(y, z)<\frac{1}{2}+\varepsilon=H^{+}(T(y), T(x))+\varepsilon
$$

(iiib) if $x=1, y \in T(x)=T(1)=\{0,1\}$, say $y=1, \varepsilon>0$, there exists $z(=1) \in T(y)=\{0,1\}$ such that

$$
0=d(y, z)<0+\varepsilon=H^{+}(T(y), T(x))+\varepsilon
$$

Thus the condition (2) is also satisfied. Clearly, $0,1 / 4,1$ are fixed points of $T$. However, we observe that the map $T$ does not satisfy the assumptions of Theorem 2.7. Indeed, for $x=0$ and $y=1$ we have

$$
H(T(0), T(1))=H(\{0\},\{0,1\})=1>L d(0,1), \quad \text { for all } L \in(0,1)
$$

Example 3.5. Let $X=[0,2 \sqrt{2} / 3] \cup\{1\}$ and $d: X \times X \rightarrow \mathbb{R}$ be a standard metric. Let $T: X \rightarrow \mathrm{CB}(X)$ be such that

$$
T(x)= \begin{cases}{\left[\frac{11 x}{50(x+1)}, \frac{11}{50}\right]} & \text { for } x \in\left[0, \frac{2 \sqrt{2}}{3}\right] \\ \left\{\frac{11}{50}\right\} & \text { for } x=1\end{cases}
$$

Set $L=0.99$. We discuss the following cases:
Case 1. When $x, y \in[0,2 \sqrt{2} / 3], y>x$, we note that

$$
\begin{aligned}
H^{+}(T x, T y) & =\frac{11}{100} \cdot \frac{y-x}{1+x+y+x y} \\
& \leq \frac{11}{100} \cdot \frac{y-x}{1+y-x}<0.99 \frac{y-x}{1+y-x} \leq 0.99 d(x, y)
\end{aligned}
$$

Case 2. When $x \in[0,2 \sqrt{2} / 3]$ and $y=1$, we note that

$$
H^{+}(T x, T y)=\frac{11}{100}\left|1-\frac{x}{1+x}\right| \leq 0.99(1-x)
$$

is true if

$$
\frac{11}{100} \cdot \frac{1}{1+x} \leq 0.99(1-x)
$$

i.e. if $1 / 9 \leq 1-x^{2}$, i.e. if $0 \leq x \leq 2 \sqrt{2} / 3$.

To check the condition (2), we consider the following cases:
Case (i). For any $x \in\left[0, \frac{2 \sqrt{2}}{3}\right], y \in T x=\left[\frac{11 x}{50(x+1)}, \frac{11}{50}\right]$ and $\varepsilon>0$ there exists $z(=y) \in T y=\left[\frac{11 y}{50(y+1)}, \frac{11}{50}\right]$ such that

$$
0=d(y, z) \leq \frac{11}{100} \cdot \frac{y-x}{1+x+y+x y}+\varepsilon=H^{+}(T(y), T(x))+\varepsilon
$$

Note that

$$
\frac{11 y}{50(y+1)} \leq \frac{11 y}{50} \leq y \leq \frac{11}{50}
$$

i.e. $y \in T y$.

Case (ii). For $x=1, y \in T x=\left\{\frac{11}{50}\right\}$ i.e. $y=\frac{11}{50}$ and $\varepsilon>0$, there exists $z\left(=\frac{792}{6100}\right) \in T y=\left[\frac{121}{3050}, \frac{11}{50}\right]$ such that

$$
d(y, z)=\frac{11}{122}<\frac{11}{122}+\varepsilon=H^{+}(T(y), T(x))+\varepsilon
$$

This proves the condition (2). Thus, all the requirements of Theorem 3.1 are satisfied and $0 \in T 0$ is the unique fixed point of $T$. However, we note that when $y=1$ and $x \rightarrow 2 \sqrt{2} / 3$ from the left, then

$$
H(T x, T y)=\frac{11 x}{50(1+x)}>1-x
$$

Thus, $T$ does not satisfy the assumptions of Theorem 2.7.
Proposition 3.6. Suppose $X$ and $\mathrm{CB}(X)$ are as in the preceding theorem, and let $T_{i}: X \rightarrow \mathrm{CB}(X), i=1,2$, be two $H^{+}$-type multi-valued contraction mappings with Lipschitz constant $L<1$. Then if $\operatorname{Fix}\left(T_{1}\right)$ and $\operatorname{Fix}\left(T_{2}\right)$ denote the respective fixed point sets of $T_{1}$ and $T_{2}$,

$$
H^{+}\left(\operatorname{Fix}\left(T_{1}\right), \operatorname{Fix}\left(T_{2}\right)\right) \leq \frac{1}{1-\sqrt{L}} \sup _{x \in X} H^{+}\left(T_{1} x, T_{2} x\right)
$$

Proof. Let $\varepsilon>0$ be given. Select $x_{0} \in \operatorname{Fix}\left(T_{1}\right)$, and then select $x_{1} \in T_{2} x_{0}$. From (2) it follows that we can choose $x_{2} \in T_{2} x_{1}$ such that

$$
d\left(x_{1}, x_{2}\right) \leq H^{+}\left(T_{2} x_{0}, T_{2} x_{1}\right)+\varepsilon
$$

Now define $\left\{x_{n}\right\}$ inductively so that $x_{n+1} \in T_{2}\left(x_{n}\right)$ and

$$
\begin{equation*}
d\left(x_{n}, x_{n+1}\right) \leq H^{+}\left(T_{2} x_{n-1}, T_{2} x_{n}\right)+\varepsilon . \tag{3.4}
\end{equation*}
$$

Set $\varepsilon=\left(\frac{1}{\sqrt{L}}-1\right) H^{+}\left(T_{2} x_{n-1}, T_{2} x_{n}\right)$. Then from (3.4), it follows that

$$
\begin{aligned}
d\left(x_{n}, x_{n+1}\right) \leq H^{+}\left(T_{2} x_{n-1}, T_{2} x_{n}\right)+\left(\frac{1}{\sqrt{L}}-1\right) H^{+} & \left(T_{2} x_{n-1}, T_{2} x_{n}\right) \\
& =\frac{1}{\sqrt{L}} H^{+}\left(T_{2} x_{n-1}, T_{2} x_{n}\right)
\end{aligned}
$$

Thus, we have

$$
\begin{equation*}
\sqrt{L} d\left(x_{n}, x_{n+1}\right) \leq H^{+}\left(T_{2} x_{n-1}, T_{2} x_{n}\right) \tag{3.5}
\end{equation*}
$$

Now applying (1) for $T_{2}$ we have

$$
\sqrt{L} d\left(x_{n}, x_{n+1}\right) \leq L d\left(x_{n-1}, x_{n}\right)=(\sqrt{L})^{2} d\left(x_{n-1}, x_{n}\right) .
$$

Hence, for all $n \in \mathbb{N}$ we have

$$
d\left(x_{n}, x_{n+1}\right) \leq \sqrt{L} d\left(x_{n-1}, x_{n}\right)
$$

Repeating the same argument $n$-times we get

$$
d\left(x_{n}, x_{n+1}\right) \leq L^{n / 2} d\left(x_{0}, x_{1}\right)
$$

This implies that $\left\{x_{n}\right\}$ is a Cauchy sequence with limit, say $z$. Since $T_{2}$ is continuous, we have

$$
\lim _{n \rightarrow \infty} H\left(T_{2} x_{n}, T_{2} z\right)=0
$$

Also, since $x_{n+1} \in T_{2}\left(x_{n}\right)$ it must be the case that $z \in T_{2} z$; that is, $z \in \operatorname{Fix}\left(T_{2}\right)$. Furthermore, using (3.5) we have

$$
\begin{aligned}
d\left(x_{0}, z\right) & \leq \sum_{n=0}^{\infty} d\left(x_{n+1}, x_{n}\right) \leq\left(1+\sqrt{L}+(\sqrt{L})^{2}+\ldots\right) d\left(x_{1}, x_{0}\right) \\
& \leq \frac{1}{1-\sqrt{L}}\left(H^{+}\left(T_{2} x_{0}, T_{1} x_{0}\right)+\varepsilon\right)
\end{aligned}
$$

Reversing the roles of $T_{1}$ and $T_{2}$ and repeating the argument as above leads to the conclusion that, for each $y_{0} \in \operatorname{Fix}\left(T_{2}\right)$, there exist $y_{1} \in T_{1} y_{0}$ and $w \in \operatorname{Fix}\left(T_{1}\right)$ such that

$$
d\left(y_{0}, w\right) \leq \frac{1}{1-\sqrt{L}}\left(H^{+}\left(T_{1} y_{0}, T_{2} y_{0}\right)+\varepsilon\right)
$$

Since $\varepsilon>0$ is arbitrary, the conclusion follows.
Theorem 3.7. Suppose $X$ and $\mathrm{CB}(X)$ are as in the preceding theorem, and let $T_{i}: X \rightarrow \mathrm{CB}(X), i=1,2, \ldots$ be a sequence of $H^{+}$-type multi-valued contraction mappings with Lipschitz constant $L<1$. If $\lim _{n \rightarrow \infty} H^{+}\left(T_{n} x, T_{0} x\right)=0$ uniformly for $x \in X$, then

$$
\lim _{n \rightarrow \infty} H^{+}\left(\operatorname{Fix}\left(T_{n}\right), \operatorname{Fix}\left(T_{0}\right)\right)=0
$$

Proof. Let $\varepsilon>0$ be given. Since $\lim _{n \rightarrow \infty} H^{+}\left(T_{n} x, T_{0} x\right)=0$ uniformly for $x \in X$, it is possible to choose $N \in \mathbb{N}$, so that for $n \geq N$,

$$
\sup _{x \in X} H^{+}\left(T_{n} x, T_{0} x\right)<(1-\sqrt{L}) \varepsilon
$$

By Proposition 3.6, $H^{+}\left(\operatorname{Fix}\left(T_{n}\right), \operatorname{Fix}\left(T_{0}\right)\right)<\varepsilon$ for all $n \geq N$. Hence the conclusion follows.

## 4. $H^{+}$-type nonexpansive mappings

In this section, first we introduce the class of $H^{+}$-type nonexpansive mappings. Then we apply the main result of preceding section to obtain fixed points of $\mathrm{H}^{+}$-type nonexpansive mappings in its natural terrain; i.e. Banach space satisfying Opial's condition.

Definition 4.1. Let $(X,\|\cdot\|)$ be a Banach space. A multi-valued map $T: X \rightarrow \mathcal{C} B(X)$ is called $H^{+}$-nonexpansive if
$\left(1^{\prime}\right) H^{+}(T x, T y) \leq\|x-y\|$ for every $x, y \in X$,
(2') for every $x \in X, y \in T(x)$ and $\varepsilon>0$, there exists $z \in T(y)$ such that

$$
\|y-z\| \leq H^{+}(T(y), T(x))+\varepsilon
$$

In the following $K$ is a nonempty convex weakly compact subset of a Banach space $X . X$ is said to satisfy Opial's condition if for each $x_{0}$ in $X$ and each sequence $\left\{x_{n}\right\}$ converging weakly to $x_{0}$ (i.e. $x_{n} \rightharpoonup x_{0}$ ), the inequality

$$
\liminf _{n \rightarrow \infty}\left\|x_{n}-x\right\|>\liminf _{n \rightarrow \infty}\left\|x_{n}-x_{0}\right\|
$$

holds for all $x \neq x_{0}$.
We will say that a mapping $T: X \rightarrow 2^{X}$ is demiclosed if

$$
x_{n} \rightharpoonup x \quad \text { and } \quad y_{n} \in T x_{n} \rightarrow y \Rightarrow y \in T x
$$

Proposition 4.2. Let $T: K \rightarrow \mathrm{C}(X)$ be $H^{+}$-type multi-valued nonexpansive mapping and let $X$ satisfy Opial's condition. Then $I-T$ is demiclosed.

Proof. Since the domain of $I-T$ is weakly compact it is enough to prove that the graph of $I-T$ is sequentially closed. Let $\left(x_{n}, y_{n}\right) \in \mathrm{G}(I-T)$ where $\mathrm{G}(I-T)$ denotes the graph of $I-T$ such that

$$
x_{n} \rightharpoonup x \quad \text { and } \quad y_{n} \rightarrow y .
$$

Then $x \in K$ and we have to prove that $y \in(I-T) x$. Since $y_{n} \in x_{n}-T x_{n}$, $y_{n}=x_{n}-z_{n}$ for some $z_{n} \in T x_{n}$.

By $\left(2^{\prime}\right)$, for $z_{n} \in T x_{n}$ and $\varepsilon>0$, we can choose $z_{n}^{\prime} \in T x$ such that

$$
\left\|z_{n}-z_{n}^{\prime}\right\| \leq H^{+}\left(T x_{n}, T x\right)+\varepsilon
$$

Since $T$ is nonexpansive, the above inequality yields

$$
\begin{equation*}
\left\|z_{n}-z_{n}^{\prime}\right\| \leq\left\|x_{n}-x\right\|+\varepsilon \tag{4.1}
\end{equation*}
$$

Since $\varepsilon>0$ is arbitrary, so on letting $\varepsilon \rightarrow 0$ and taking liminf on both sides of (4.1), we have

$$
\begin{equation*}
\liminf _{n \rightarrow \infty}\left\|x_{n}-x\right\| \geq \liminf _{n \rightarrow \infty} \mid z_{n}-z_{n}^{\prime}\left\|\geq \liminf _{n \rightarrow \infty}\right\| x_{n}-y_{n}-z_{n}^{\prime} \| \tag{4.2}
\end{equation*}
$$

But $T x$ is compact and $y_{n} \rightarrow y$. Hence there exists a subsequence of $\left\{z_{n}^{\prime}\right\}$, again denoted by $\left\{z_{n}^{\prime}\right\}$, converging to $z \in T x$. Hence, from (4.2) we get

$$
\begin{equation*}
\liminf _{n \rightarrow \infty}\left\|x_{n}-x\right\| \geq \liminf _{n \rightarrow \infty}\left\|x_{n}-y-z\right\| \tag{4.3}
\end{equation*}
$$

By Opial's condition we have $y+z=x$. Thus $y=x-z \in x-T x$.
Let $K$ be a nonempty convex subset of a Banach space $X$. Let $T: K \rightarrow \mathcal{C}(X)$ be a multi-valued mapping. For a fixed $x_{0} \in K$ and any $x \in K$, we define the segment $\left[x, x_{0}\right]$ by $\left[x, x_{0}\right]=\left\{y \in K: y=\lambda x+(1-\lambda) x_{0}, 0 \leq \lambda \leq 1\right\}$. We call $T$ to be $x_{0}$-redundant if $T y=T x$ for all $y \in\left[x, x_{0}\right]$.

Theorem 4.3. Let $X$ be a Banach space which satisfies Opial's condition, $K$ is a nonempty convex weakly compact subset of $X$ and let $T: K \rightarrow \mathrm{C}(K)$ be a $H^{+}$-type multi-valued nonexpansive mapping. If there exists $x_{0} \in K$ such that $T$ is $x_{0}$-redundant, then $T$ has a fixed point in $K$.

Proof. Let $\left\{k_{n}\right\}$ be a sequence of real numbers such that $0<k_{n}<1$ and $k_{n} \rightarrow 1$ as $n \rightarrow \infty$. Define

$$
\begin{equation*}
T_{n} x=k_{n} T x+\left(1-k_{n}\right) x_{0} \quad \text { for all } x \in K \text { and } n \in \mathbb{N} \tag{4.4}
\end{equation*}
$$

By Proposition 2.2 (i) and (ii), for any $x, y \in K$ and $n \in \mathbb{N}$ we have

$$
\left.H^{+}\left(T_{n}(x)\right), T_{n}(y)\right)=k_{n} H^{+}(T(x), T(y)) \leq k_{n}\|x-y\|
$$

Now let $\varepsilon>0$ be given. $\operatorname{By}\left(2^{\prime}\right)$, corresponding to any $y$ in $T(x)$ i.e. in turn, for any $y^{\prime}=k_{n} y+\left(1-k_{n}\right) x_{0}$ in $T_{n}(x)$, there exists $z \in T(y)$ and, in turn, there exists $z^{\prime}=k_{n} z+\left(1-k_{n}\right) x_{0}$ in $T_{n}(y)$, and hence, in $T_{n}\left(y^{\prime}\right)=k_{n} T\left(y^{\prime}\right)+\left(1-k_{n}\right) x_{0}=$ $k_{n} T\left(k_{n} y+\left(1-k_{n}\right) x_{0}\right)+\left(1-k_{n}\right) x_{0}=k_{n} T(y)+\left(1-k_{n}\right) x_{0}=T_{n}(y)$ such that

$$
\|y-z\| \leq H^{+}(T(y), T(x))+\varepsilon
$$

Thus, for all $n \in \mathbb{N}$, this yields

$$
\begin{aligned}
\left\|y^{\prime}-z^{\prime}\right\| & =k_{n}\|y-z\| \leq k_{n}\left(H^{+}(T(y), T(x))+\varepsilon\right) \\
& =H^{+}\left(T_{n}(y), T_{n}(x)\right)+k_{n} \varepsilon<H^{+}\left(T_{n}\left(y^{\prime}\right), T_{n}(x)\right)+\varepsilon
\end{aligned}
$$

Hence $T_{n}$ is a $H^{+}$-type multivalued $k_{n}$-contraction mapping for all $n \in \mathbb{N}$. Also, since $K$ is a complete metric space, therefore it follows from Theorem 3.2, that
for each $n \in \mathbb{N}$, there exists $x_{n} \in K$ such that $x_{n} \in T_{n}\left(x_{n}\right)$. Since $K$ is weakly compact, there exists a subsequence of $\left\{x_{n}\right\}$, again denoted by $\left\{x_{n}\right\}$, converging weakly to $x \in K$. From (4.4), there exists $z_{n} \in T x_{n}$ such that

$$
x_{n}=k_{n} z_{n}+\left(1-k_{n}\right) x_{0} \quad \text { for all } n \in \mathbb{N} .
$$

It then follows that

$$
\left\|x_{n}-z_{n}\right\|=\left(1-k_{n}\right)\left\|x_{0}-z_{n}\right\|
$$

Hence $y_{n}=x_{n}-z_{n} \in(I-T) x_{n}$ and $y_{n} \rightarrow 0$ as $n \rightarrow \infty$. This means that $\left(x_{n}, y_{n}\right) \in \mathrm{G}(I-T)$ and $x_{n} \rightharpoonup x, y_{n} \rightarrow 0$. So by demiclosedness of $(I-T), 0 \in$ $(I-T) x$ i.e. $x \in T x$.

## 5. Existence theorem for nonconvex integral inclusions

In this section, we shall consider a nonconvex integral inclusion and prove a Filippov type existence theorem by using an appropriate norm on the space of selection of the multifunction and a $H^{+}$-type contraction for set-valued maps.

Let $I:=[0, T], T>0$ and $\mathcal{L}(I)$ denote the $\sigma$-algebra of all Lebesgue measurable subsets of $I$. Let $X$ be a real separable Banach space with the norm $\|\cdot\|$. Let $\mathcal{P}(X)$ denote the family of all nonempty subsets of $X$ and $\mathcal{B}(X)$ the family of all Borel subsets of $X$.

Throughout this section, let $\mathrm{C}(I, X)$ denote the Banach space of all continuous functions $x(\cdot): I \rightarrow X$ endowed with the norm $\|x(\cdot)\|_{C}=\sup _{t \in I}\|x(t)\|$. Consider the following integral inclusion

$$
\begin{gather*}
x(t)=\lambda(t)+\int_{0}^{t}[a(t, s) g(t, u(s))+f(t, s, u(s))] d s,  \tag{5.1}\\
u(t) \in F(t, V(x)(t)) \quad \text { a.e. }(I:=[0, T]), \tag{5.2}
\end{gather*}
$$

where $\lambda(\cdot): I \rightarrow X, g(\cdot, \cdot): I \times X \rightarrow X, F(\cdot, \cdot): I \times X \rightarrow \mathcal{P}(X), f(\cdot, \cdot, \cdot): I \times$ $I \times X \rightarrow X, V: \mathrm{C}(I, X) \rightarrow \mathrm{C}(I, X), a(\cdot, \cdot): I \times I \rightarrow \mathbb{R}=(-\infty, \infty)$ are given mappings. In the sequel, we also use the following: For any $x \in X, \lambda \in C(I, X), \sigma \in$ $L^{1}(I, E)$, we define the set-valued maps $M_{\lambda, \sigma}(t):=F\left(t, V\left(x_{\sigma, \lambda}\right)(t)\right), t \in I, T_{\lambda}(\sigma)$ $:=\left\{\psi(\cdot) \in L^{1}(I, E): \psi(t) \in M_{\lambda, \sigma}(t)\right.$ a.e. $\left.(I)\right\}$.

In order to study problem (5.1)-(5.2) we introduce the following assumption.
Hypothesis 5.1. Let $F(\cdot, \cdot): I \times X \rightarrow \mathcal{P}(X)$ be a set-valued map with nonempty closed values that verify:
$\left(\mathrm{H}_{1}\right)$ The set-valued map $F(\cdot, \cdot)$ is $\mathcal{L}(I) \otimes \mathcal{B}(X)$ measurable.
$\left(\mathrm{H}_{2}\right)$ There exists $L(\cdot) \in L^{1}\left(I, \mathbb{R}_{+}\right)$such that, for almost all $t \in I, F(t, \cdot)$ is $L(t)$-Lipschitz in the sense that:

$$
\begin{equation*}
H^{+}(F(t, x), F(t, y)) \leq L(t)\|x-y\| \quad \text { for all } x, y \in X \tag{C1}
\end{equation*}
$$

and for any $x, y \in X, w \in F(t, x)$ and $\varepsilon>0$, there exists $z \in F(t, y)$ such that:

$$
\begin{equation*}
\|w-z\| \leq H^{+}(F(t, x), F(t, y))+\varepsilon \tag{C2}
\end{equation*}
$$

and $T_{\lambda}(\cdot)$ satisfies the condition: For any $\sigma \in L^{1}(I, E), \sigma_{1} \in T_{\lambda}(\sigma)$ and any given $\varepsilon>0$ there exists $\sigma_{2} \in T_{\lambda}\left(\sigma_{1}\right)$ such that:

$$
\begin{equation*}
\left\|\sigma_{1}-\sigma_{2}\right\|_{1} \leq H^{+}\left(T_{\lambda}(\sigma), T_{\lambda}\left(\sigma_{1}\right)\right)+\varepsilon \quad \text { for almost all } t \in I \tag{C3}
\end{equation*}
$$

$\left(\mathrm{H}_{3}\right)$ The mappings $f: I \times I \times X \rightarrow X, g, \lambda: I \times X \rightarrow X$ are continuous, $V: \mathrm{C}(I, X) \rightarrow \mathrm{C}(I, X)$ and there exist the constants $M_{1}, M_{2}, M_{3}>0$ such that:

$$
\begin{array}{rlrl}
\left\|f\left(t, s, u_{1}\right)-f\left(t, s, u_{2}\right)\right\| & \leq M_{1}\left\|u_{1}-u_{2}\right\|, & & \text { for all } u_{1}, u_{2} \in X \\
\left\|g\left(s, u_{1}\right)-g\left(s, u_{2}\right)\right\| & \leq M_{2}\left\|u_{1}-u_{2}\right\|, & & \text { for all } u_{1}, u_{2} \in X \\
\left\|V\left(x_{1}\right)(t)-V\left(x_{2}\right)(t)\right\| & \leq M_{3}\left\|x_{1}(t)-x_{2}(t)\right\|, & & \text { for all } t \in I \\
& & \text { and all } x_{1}, x_{2} \in \mathrm{C}(I, X)
\end{array}
$$

$\left(\mathrm{H}_{4}\right)$ Let a:I $\times I \rightarrow \mathbb{R}$ be continuous and satisfy the uniform Hölder's continuity condition in the first and second arguments with the exponent $\rho$; i.e. there exists a positive number b such that

$$
\left|a\left(t_{1}, s_{1}\right)-a\left(t_{2}, s_{2}\right)\right| \leq b\left(\left|t_{1}-t_{2}\right|^{\rho}+\left|s_{1}-s_{2}\right|^{\rho}\right)
$$

for all $t_{1}, t_{2}, s_{1}, s_{2} \in I$ and $|a(t, s)| \leq 2 b T+|a(0,0)|=M_{4}$ for all $t, s \in I$ and $0<\rho \leq 1$.

Note that the system (5.1)-(5.2) includes a large variety of differential inclusions and control systems including those defined by partial differential equations.

Assume that $U$ be an open bounded subset of $\mathbb{R}^{n}$ (or $Y$, a subset of $X$ homeomorphic to $\left.\mathbb{R}^{n}\right)$ and $U_{T}=U \times(0, T]$ for some fixed $T>0$. We say that the partial differential operator $\frac{\partial}{\partial t}+L$ is parabolic if there exists a constant $\theta>0$ such that

$$
\sum_{i, j=1}^{n} a^{i j}(x, t) \xi_{i} \xi_{j} \geq \theta|\xi|^{2}
$$

for all $(x, t) \in U_{T}, \xi \in \mathbb{R}^{n}$. The letter $L$ denotes for each time $t$ a second order partial differential operator, having either the divergence form

$$
L u=-\sum_{i, j=1}^{n}\left(a^{i j}(x, t) u_{x_{i}}\right)_{x_{j}}+\sum_{i=1}^{n} b^{i}(x, t) u_{x_{i}}+\mathrm{C}(x, t) u
$$

or else the nondivergence form

$$
L u=-\sum_{i, j=1}^{n} a^{i j}(x, t) u_{x_{i} x_{j}}+\sum_{i=1}^{n} b^{i}(x, t) u_{x_{i}}+\mathrm{C}(x, t) u
$$

for given coefficients $a^{i j}, b^{i}, c(i, j=1, \ldots, n)$.
A family $\left\{G(t): t \in \mathbb{R}_{+}=[0, \infty)\right\}$ of bounded linear operators from $X$ into $X$ is a $C_{0}$-semigroup (also called linear semigroup of class $\left.\left(C_{0}\right)\right)$ on $X$ if
(i) $G(0)=$ the identity operator, and $G(t+s)=G(t) G(s)$ for all
(ii) $G(\cdot)$ is strongly continuous in $t \in \mathbb{R}_{+}$;
(iii) $\|G(t)\| \leq M e^{\omega t}$ for some $M>0$, real $\omega$ and $t \in \mathbb{R}_{+}$.

Example 5.2. Set $f(t, \tau, u)=G(t-\tau) u, g(\tau, u(\tau))=0, V(x)=x, \lambda(t)=$ $G(t) x_{0}$ where $\{G(t)\}_{t \geq 0}$ is a $C_{0}$-semigroup with an infinitesimal generator $A$. Then a solution of system (5.1)-(5.2) represents a mild solution of

$$
\begin{equation*}
x^{\prime}(t) \in A x(t)+F(t, x(t)), \quad x(0)=x_{0} . \tag{5.3}
\end{equation*}
$$

In particular, this problem includes control systems governed by parabolic partial differential equations as a special case. When $A=0$, the relation (5.3) reduces to classical differential inclusions

$$
\begin{equation*}
x^{\prime}(t) \in F(t, x(t)), \quad x(0)=x_{0} \tag{5.4}
\end{equation*}
$$

Denote

$$
\begin{equation*}
\Phi(u)(t)=\int_{0}^{t}[a(t, \tau) g(\tau, u(\tau))+f(t, \tau, u(\tau))] d \tau, \quad t \in I \tag{5.5}
\end{equation*}
$$

Then the integral inclusion system (5.1)-(5.2) reduces to the form

$$
\begin{equation*}
x(t)=\lambda(t)+\Phi(u)(t), u(t) \in F(t, V(x)(t)) \quad \text { a.e. }(I), \tag{5.6}
\end{equation*}
$$

which may be written in more compact form as

$$
u(t) \in F(t, V(\lambda+\Phi(u))(t)) \quad \text { a.e. }(I)
$$

Now we recall the following:
Definition 5.3. A pair of functions $(x, u)$ is called a solution pair of integral inclusion system (5.6), if $x(\cdot) \in \mathrm{C}(I, X), u(\cdot) \in L^{1}(I, X)$ and satisfy relation (5.6).

For our further discussion, we denote by $S(\lambda)$ the solution set of (5.1)-(5.2).
Notice that the integral operator in (5.5) plays a key role in the proofs of our main results.

For given $\alpha \in \mathbb{R}$ we denote by $L^{1}(I, X)$ the Banach space of all Bochner integrable functions $u(\cdot): I \rightarrow X$ endowed with the norm

$$
\|u(\cdot)\|_{1}=\int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)}\|u(t)\| d t
$$

where $m(t)=\int_{0}^{t} L(s) d s, t \in I$.

Theorem 5.4. Let Hypothesis 5.1 be satisfied, $\lambda(\cdot, \cdot), \mu(\cdot, \cdot) \in \mathrm{C}(I \times X, X)$ and let $u(\cdot) \in L^{1}(I, X)$ be such that

$$
d(v(t), F(t, V(y)(t)) \leq p(t) \quad \text { a.e. }(I),
$$

where $p(\cdot) \in L^{1}\left(I, \mathbb{R}_{+}\right)$and $y(t)=\mu(t, u(t))+\Phi(u)(t)$, for all $t \in I$. Then for every $\alpha>1,0<h<1$, there exist $\nu \in \mathbb{N}$ and $x(\cdot) \in S(\lambda)$ such that, for every $t \in I$,

$$
\begin{aligned}
& \|x(t)-y(t)\| \leq\|\lambda-\mu\|_{C}\left[1+\frac{e^{\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(T)}}{\sqrt{\alpha}(\sqrt{\alpha}-1)}\right] \\
& +\frac{\sqrt{\alpha}}{(\sqrt{\alpha}-1)}\left(M_{4} M_{2}+M_{1}\right) e^{\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(T)} \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} p(t) d t
\end{aligned}
$$

Proof. For $\lambda \in \mathrm{C}(I, X)$ and $u \in L^{1}(I, X)$ define

$$
x_{u, \lambda}(t)=\lambda(t)+\int_{0}^{t}[a(t, s) g(t, u(s))+f(t, s, u(s))] d s
$$

Let us consider that $\lambda \in \mathrm{C}(I, X), \sigma \in L^{1}(I, X)$ and define the set-valued maps

$$
\begin{align*}
M_{\lambda, \sigma}(t) & :=F\left(t, V\left(x_{\sigma, \lambda}\right)(t)\right), \quad t \in I  \tag{5.7}\\
T_{\lambda}(\sigma) & :=\left\{\psi(\cdot) \in L^{1}(I, X): \psi(t) \in M_{\lambda, \sigma}(t) \text { a.e. }(I)\right\} . \tag{5.8}
\end{align*}
$$

Further, in view of condition (C3) of Hypothesis $5.1\left(\mathrm{H}_{2}\right), T_{\lambda}(\cdot)$ satisfies the condition: For any $\sigma \in L^{p}(I, E), \sigma_{1} \in T_{\lambda}(\sigma)$ and any given $\varepsilon>0$ there exists $\sigma_{2} \in T_{\lambda}\left(\sigma_{1}\right)$ such that

$$
\begin{equation*}
\left\|\sigma_{1}-\sigma_{2}\right\|_{1} \leq H^{+}\left(T_{\lambda}(\sigma), T_{\lambda}\left(\sigma_{1}\right)\right)+\varepsilon \tag{5.9}
\end{equation*}
$$

Now we claim that $T_{\lambda}(\sigma)$ is nonempty and closed for every $\sigma \in L^{1}(I, X)$.
The set-valued map $M_{\lambda, \sigma}(\cdot)$ is measurable. For example the map $t \rightarrow$ $F\left(t, V\left(x_{\sigma, \lambda}\right)(t)\right.$ can be approximated by step functions and so we can apply Theorem III. 40 in [2]. Since the values of $F$ are closed, with the measurable selection theorem we infer that $M_{\lambda, \sigma}(\cdot)$ is nonempty.

Also, the set $T_{\lambda}(\sigma)$ is closed. Indeed, if $\psi_{n} \in T_{\lambda}(\cdot)$ and $\left\|\psi_{n}-\psi\right\|_{1} \rightarrow 0$, then there exists a subsequence $\psi_{n_{k}}$ such that $\psi_{n_{k}}(t) \rightarrow \psi(t)$ for almost every $t \in I$ and we find that $\psi \in T_{\lambda}(\sigma)$.

Let $\sigma_{1}, \sigma_{2} \in L^{1}(I, X)$ be given. Let $\psi_{1} \in T_{\lambda}\left(\sigma_{1}\right)$ and let $\delta>0$. Consider the following set-valued map:

$$
\begin{aligned}
& \mathcal{G}(t):=M_{\lambda, \sigma_{2}}(t) \\
& \cap\left\{z \in X:\left\|\psi_{1}(t)-z\right\| \leq M_{3}\left(M_{4} M_{2}+M_{1}\right) L(t) \int_{0}^{t}\left\|\sigma_{1}(s)-\sigma_{2}(s)\right\| d s+\delta\right\} .
\end{aligned}
$$

Then

$$
\begin{aligned}
d\left(\psi_{1}, M_{\lambda, \sigma_{2}}(t)\right) \leq & \rho\left(F\left(t, V\left(x_{\sigma_{1}, \lambda}\right)(t)\right), F\left(t, V\left(x_{\sigma_{2}, \lambda}\right)(t)\right)\right)+\varepsilon \\
\leq & \left.\left.L(t) \| V\left(x_{\sigma_{1}, \lambda}\right)(t)\right)-V\left(x_{\sigma_{2}, \lambda}\right)(t)\right) \|+\varepsilon \\
\leq & M_{3} L(t)\left\|x_{\sigma_{1}, \lambda}(t)-x_{\sigma_{2}, \lambda}(t)\right\|+\varepsilon \\
\leq & M_{3} L(t)\left[\int_{0}^{t} \mid a(t, s)\left\|g\left(t, \sigma_{1}(s)\right)-g\left(t, \sigma_{2}(s)\right)\right\| d s\right. \\
& \left.+\int_{0}^{t}\left\|f\left(t, s, \sigma_{1}(s)\right)-f\left(t, s, \sigma_{2}(s)\right)\right\| d s\right]+\varepsilon \\
\leq & M_{3} L(t)\left[\left(M_{4} M_{2}+M_{1}\right) \int_{0}^{t}\left\|\sigma_{1}(s)-\sigma_{2}(s)\right\| d s\right]+\varepsilon
\end{aligned}
$$

Since $\varepsilon$ is arbitrary, letting $\varepsilon \rightarrow 0$, we have that $\mathcal{G}(\cdot)$ is nonempty bounded and has closed values. Further, by Proposition III. 4 in [2], $\mathcal{G}(\cdot)$ is measurable.

Let $\psi_{2}(\cdot)$ be a measurable selector of $\mathcal{G}(\cdot)$. It follows that $\psi_{2} \in T_{\lambda}\left(\sigma_{2}\right)$ and

$$
\begin{aligned}
& \| \psi_{1}-\psi_{2}\left\|_{1}=\int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)}\right\| \psi_{1}(t)-\psi_{2}(t) \| d t \\
& \leq \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} M_{3} L(t)\left[\left(M_{4} M_{2}+M_{1}\right) \int_{0}^{t}\left\|\sigma_{1}(s)-\sigma_{2}(s)\right\| d s\right] d t \\
& \quad+\delta \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} d t \\
& \leq \frac{1}{\alpha}\left\|\sigma_{1}-\sigma_{2}\right\|_{1}+\delta \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} d t .
\end{aligned}
$$

Since $\delta$ is arbitrary, so letting $\delta \rightarrow 0$ we deduce from the above inequality that

$$
d\left(\psi_{1}, T_{\lambda}\left(\sigma_{2}\right)\right) \leq \frac{1}{\alpha}\left\|\sigma_{1}-\sigma_{2}\right\|_{1}
$$

Thus, we have

$$
\begin{equation*}
\rho\left(T_{\lambda}\left(\sigma_{1}\right), T_{\lambda}\left(\sigma_{2}\right)\right)=\sup _{\psi_{1} \in T_{\lambda}\left(\sigma_{1}\right)} d\left(\psi_{1}, T_{\lambda}\left(\sigma_{2}\right)\right) \leq \frac{1}{\alpha}\left\|\sigma_{1}-\sigma_{2}\right\|_{1} \tag{5.10}
\end{equation*}
$$

Now replacing $\sigma_{1}(\cdot)$ with $\sigma_{2}(\cdot)$, we obtain

$$
\begin{equation*}
H^{+}\left(T_{\lambda}\left(\sigma_{1}\right), T_{\lambda}\left(\sigma_{2}\right)\right) \leq \frac{1}{\alpha}\left\|\sigma_{1}-\sigma_{2}\right\|_{1} \tag{5.11}
\end{equation*}
$$

Now adding (5.10) and (5.11) and dividing by 2, we obtain

$$
H^{+}\left(T_{\lambda}\left(\sigma_{1}\right), T_{\lambda}\left(\sigma_{2}\right)\right) \leq \frac{1}{\alpha}\left\|\sigma_{1}-\sigma_{2}\right\|_{1}
$$

Hence we conclude that $T_{\lambda}(\cdot)$ is a contraction on $L^{1}(I, X)$. Next, we consider the following set-valued maps

$$
\begin{aligned}
\widetilde{F}(t, x) & :=F(t, x)+p(t) \\
\widetilde{M}_{\lambda, \sigma}(t) & :=\widetilde{F}\left(t, V\left(x_{\sigma, \lambda}\right)(t)\right), \quad t \in I \\
\widetilde{T}_{\lambda}(\sigma) & :=\left\{\psi(\cdot) \in L^{1}(I, X) ; \psi(t) \in \widetilde{M}_{\lambda, \sigma}(t) \text { a.e. }(I)\right\} .
\end{aligned}
$$

It is obvious that $\widetilde{F}(\cdot, \cdot)$ satisfies Hypothesis 5.1.
Let $\phi \in T_{\lambda}(\sigma), \delta>0$ and define

$$
\mathcal{G}_{1}(t):=\widetilde{M}_{\lambda, \sigma(t)} \cap\left\{z \in X:\|\phi(t)-z\| \leq M_{3} L(t)\|\lambda-\mu\|_{C}+p(t)+\delta\right\}
$$

Using the same argument as used for the set valued $\operatorname{map} \mathcal{G}(\cdot)$, we deduce that $\mathcal{G}_{1}(\cdot)$ is measurable with nonempty closed values.

Next, we prove the following estimate:

$$
\begin{align*}
H^{+}\left(T_{\lambda}(\sigma), \widetilde{T}_{\mu}(\sigma)\right) \leq \frac{1}{\alpha\left(M_{4} M_{2}+M_{1}\right)} & \|\lambda-\mu\|_{C}  \tag{5.12}\\
& +\int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} p(t) d t
\end{align*}
$$

Let $\psi(\cdot) \in T_{\mu}(\sigma)$. Then

$$
\begin{aligned}
\|\phi-\psi\|_{1} \leq & \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)}\|\phi(t)-\psi(t)\| d t \\
\leq & \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)}\left[M_{3} L(t)\|\lambda-\mu\|_{C}+p(t)+\delta\right] d t \\
= & \|\lambda-\mu\|_{C} \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} M_{3} L(t) d t \\
& +\int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} p(t) d t+\delta \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} d t \\
\leq & \frac{1}{\alpha\left(M_{4} M_{2}+M_{1}\right)}\|\lambda-\mu\|_{C}+\int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} p(t) d t \\
& +\delta \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} d t
\end{aligned}
$$

As $\delta$ is arbitrary, we obtain (5.12).
Now applying Proposition 3.6 we obtain

$$
\begin{aligned}
H^{+}\left(\operatorname{Fix}\left(T_{\lambda}\right), \operatorname{Fix}\left(\widetilde{T}_{\mu}\right)\right) \leq & \frac{1}{\sqrt{\alpha}(\sqrt{\alpha}-1)\left(M_{4} M_{2}+M_{1}\right)}\|\lambda-\mu\|_{C} \\
& +\frac{\sqrt{\alpha}}{\sqrt{\alpha}-1} \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} p(t) d t
\end{aligned}
$$

Since $v(\cdot) \in \operatorname{Fix}\left(\widetilde{T}_{\mu}\right)$, it follows that there exists $\nu \in \mathbb{N}$ and $u(\cdot) \in \operatorname{Fix}\left(T_{\mu}\right)$ such that

$$
\begin{align*}
\|v-u\|_{1} \leq & \frac{1}{\sqrt{\alpha}(\sqrt{\alpha}-1)\left(M_{4} M_{2}+M_{1}\right)}\|\lambda-\mu\|_{C}  \tag{5.13}\\
& +\frac{\sqrt{\alpha}}{\sqrt{\alpha}-1} \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} p(t) d t
\end{align*}
$$

We define

$$
x=\lambda(t)+\int_{0}^{t}[a(t, s) g(t, u(s))+f(t, s, u(s))] d s
$$

Then one has the following inequality:

$$
\begin{aligned}
\|x(t)-y(t)\| & \leq\|\lambda(t)-\mu(t)\|+\left(M_{4} M_{2}+M_{1}\right) \int_{0}^{t}\|u(s)-v(s)\| d s \\
& \leq\|\lambda-\mu\|_{C}+\left(M_{4} M_{2}+M_{1}\right) e^{\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(T)}\|u-v\|_{1} .
\end{aligned}
$$

Combining the last inequality with (5.13), we obtain

$$
\begin{aligned}
& \|x(t)-y(t)\| \leq\|\lambda-\mu\|_{C}\left[1+\frac{e^{\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(T)}}{\sqrt{\alpha}(\sqrt{\alpha}-1)}\right] \\
& +\frac{\sqrt{\alpha}}{(\sqrt{\alpha}-1)}\left(M_{4} M_{2}+M_{1}\right) e^{\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(T)} \int_{0}^{T} e^{-\alpha\left(M_{4} M_{2}+M_{1}\right) M_{3} m(t)} p(t) d t
\end{aligned}
$$

This completes the proof.
Remarks 5.5. (a) If $a(t, \tau) \equiv 0$, Theorem 5.4 complements the result in [4] obtained for mild solutions of the semilinear differential inclusion (5.3).
(b) If $a(t, \tau)=0, f(t, \tau, u)=\mathcal{G}(t-\tau) u, V(x)=x, \lambda(t)=\mathcal{G}(t) x_{0}$ where $\{\mathcal{G}(t)\}_{t \geq 0}$ is a $C_{0}$-semigroup with an infinitesimal generator $A$, Theorem 5.4 complements the result in [3] obtained for mild solutions of the semilinear differential inclusion (5.3).

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## Hemant Kumar Pathak

School of Studies in Mathematics
Pt. Ravishankar Shukla University
Raipur (C.G.) 492010, INDIA
E-mail address: hkpathak05@gmail.com

Naseer Shahzad
King Abdulaziz University
Department of Mathematics
PO Box 80203
21589 Jeddah, SAUDI ARABIA
E-mail address: nshahzad@kau.edu.sa


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