$\begin{array}{lll} \textbf{Topological Methods in Nonlinear Analysis} \\ \textbf{Volume 51, No. 1, 2018, 1-22} \\ \textbf{DOI: } 10.12775/\text{TMNA.2017.061} \end{array}$

© 2018 Juliusz Schauder Centre for Nonlinear Studies Nicolaus Copernicus University

A CLASS OF DELAY EVOLUTION HEMIVARIATIONAL INEQUALITIES AND OPTIMAL FEEDBACK CONTROLS

Liang Lu — Zhenhai Liu — Jing Zhao

ABSTRACT. In this paper, we study the feedback optimal control for a class of evolution hemivariational inequalities with delay. First, we obtain the existence of feasible pairs by applying the Cesari property, the Filippov theorem, the properties of Clarke subdifferential and a fixed point theorem for multivalued maps. Next, the results of optimal feedback control pairs and time optimal control for delay evolution hemivariational inequalities are presented under sufficient conditions. Finally, an example is included to illustrate our main results.

1. Introduction

Hemivariational inequalities were introduced to deal with the mechanical problems with nonsmooth and nonconvex energy superpotentials (see [31], [32]). It is an efficient tool in mathematical models to describe the antiplane shear deformations of a piezoelectric cylinder in frictional contact with a foundation,

²⁰¹⁰ Mathematics Subject Classification. Primary: 49J15, 49J27, 93B52, 49J52.

Key words and phrases. Optimal feedback control; feasible pair; delay evolution equation; hemivariational inequality.

This research was supported by National Natural Science Foundation of China Grant Nos. 11671101, 11661001, 11661012, 11461021, Guangxi Natural Science Foundation under Grant No. 2017GXNSFBA198031, Project of Guangxi Education Department Grant No. 2017KY0648, Postgraduate Research & Practice Innovation Program of Jiangsu Province No. KYCX17_0319, Special Funds of Guangxi Distinguished Experts Construction Engineering, Guangxi Colleges and Universities Key Laboratory of Symbolic Computation and Engineering Data Processing.